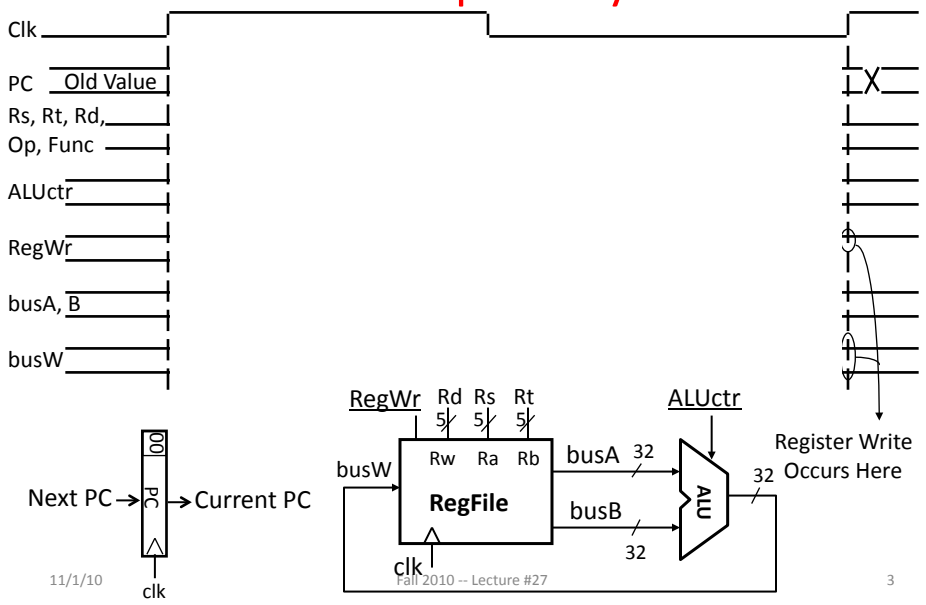
CS 61C: Great Ideas in Computer Architecture (Machine Structures)
Control Implementation

Instructors:
Randy H. Katz
David A. Patterson
http://inst.eecs.Berkeley.edu/~cs61c/fa10

Agenda

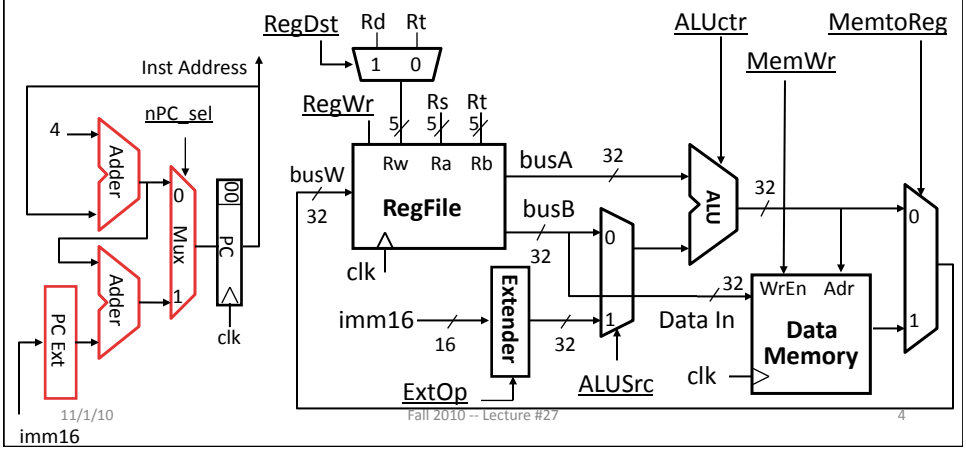
- Datapath Control
- Administrivia
- Technology Break
- Controller Implementation

Register-Register Timing: One Complete Cycle



Datapath's Control Signals

- ExtOp: "zero", "sign"
- ALUsrc: 0 ⇒ regB; 1 ⇒ immed
- ALUctr: "ADD", "SUB", "OR"
- MemWr: 1 ⇒ write memory
- MemtoReg: 0 ⇒ ALU; 1 ⇒ Mem
- RegDst: 0 ⇒ "rt"; 1 ⇒ "rd"
- RegWr: 1 ⇒ write register



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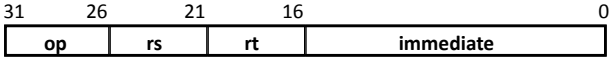
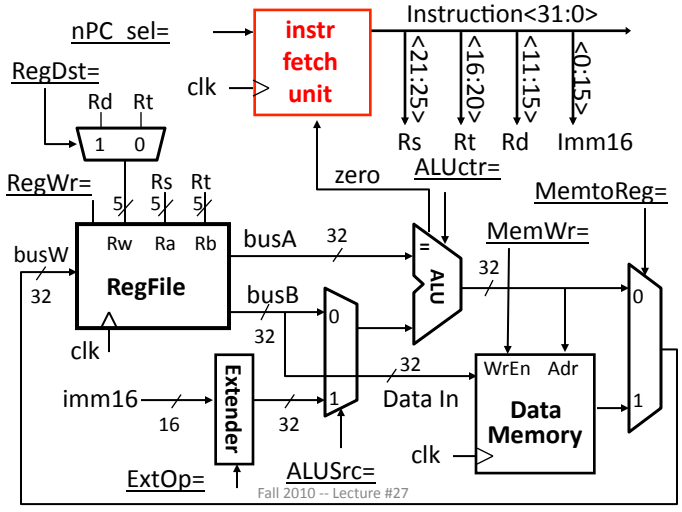
Single Cycle Datapath during Store



- Data Memory {R[rs] + SignExt[imm16]} = R[rt]



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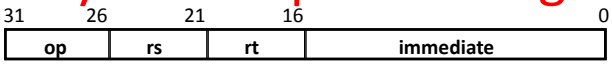

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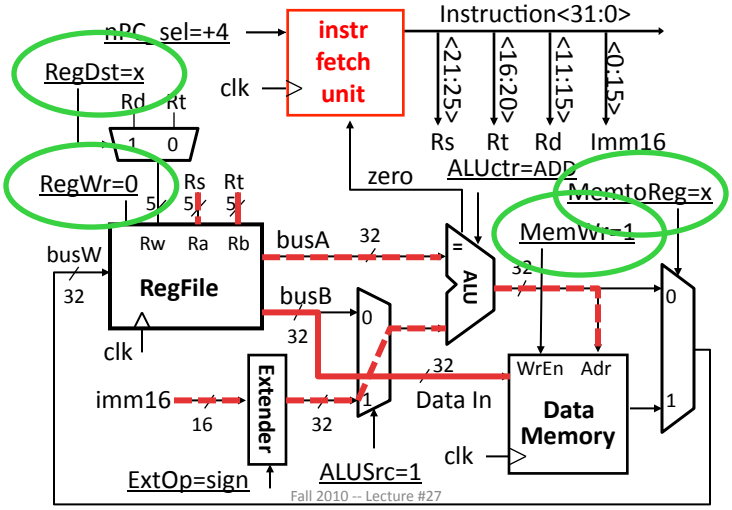
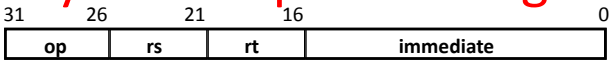
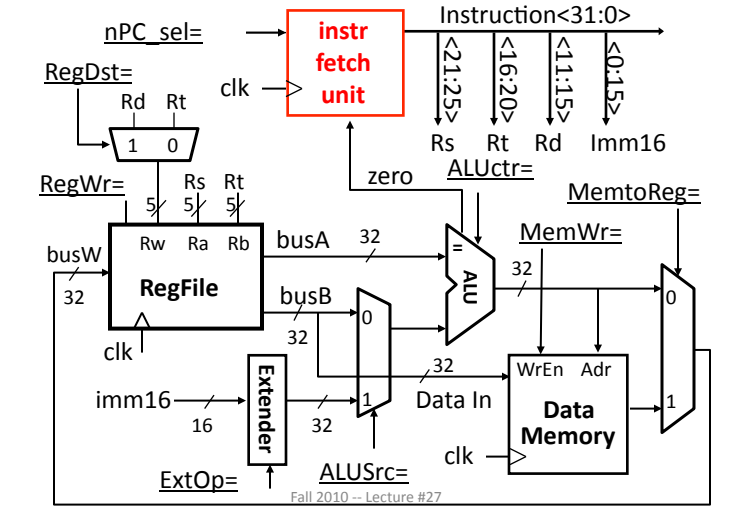


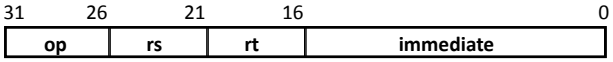
Single Cycle Datapath during Branch



- if (R[rs] - R[rt] == 0) then Zero = 1 ; else Zero = 0



Single Cycle Datapath during Branch



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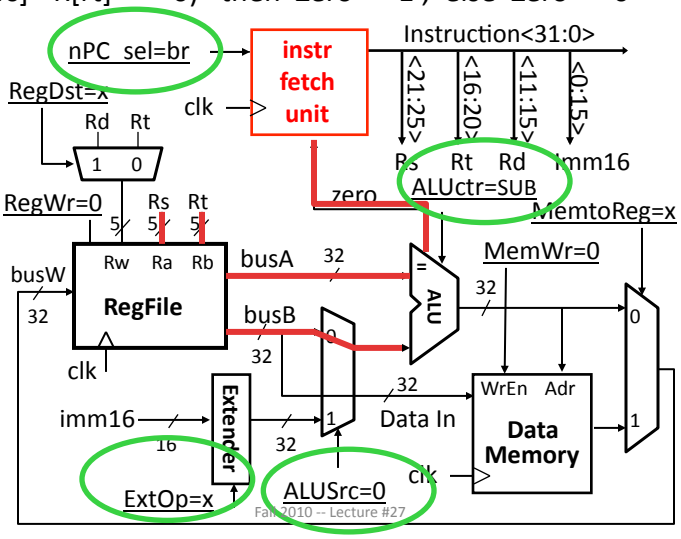
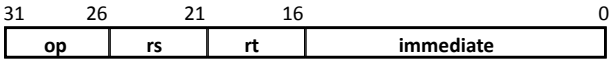
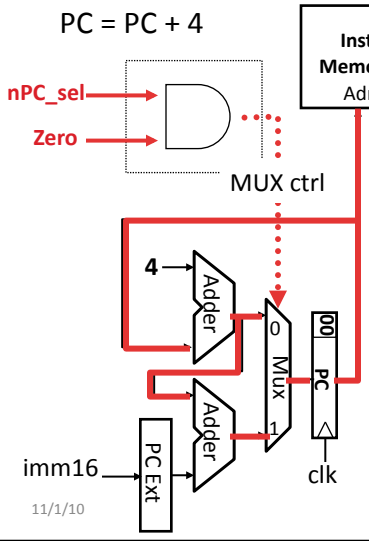


Instruction Fetch Unit at the End of Branch



- if (Zero == 1) then PC = PC + 4 + SignExt[imm16]*4 ; else PC = PC + 4

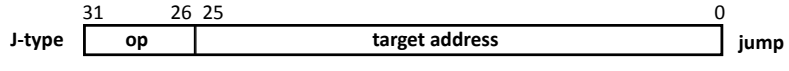


- How to encode nPC_sel?
  - Direct MUX select?
  - Branch inst. / not branch inst.
- Let's pick 2nd option

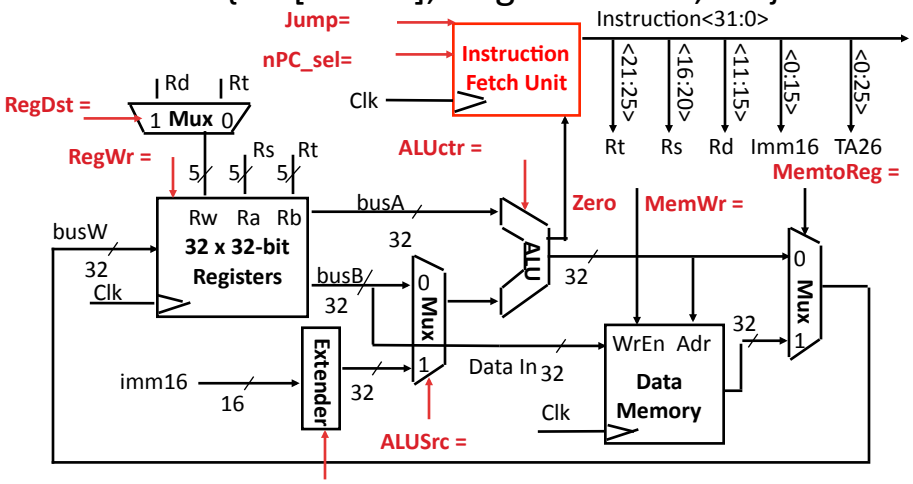
nPC_sel	zero?	MUX
0	x	0
1	0	0
1	1	1

Q: What logic gate?

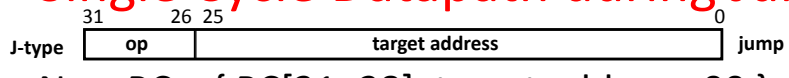
Single Cycle Datapath during Jump



- New PC = { PC[31..28], target address, 00 }



Single Cycle Datapath during Jump



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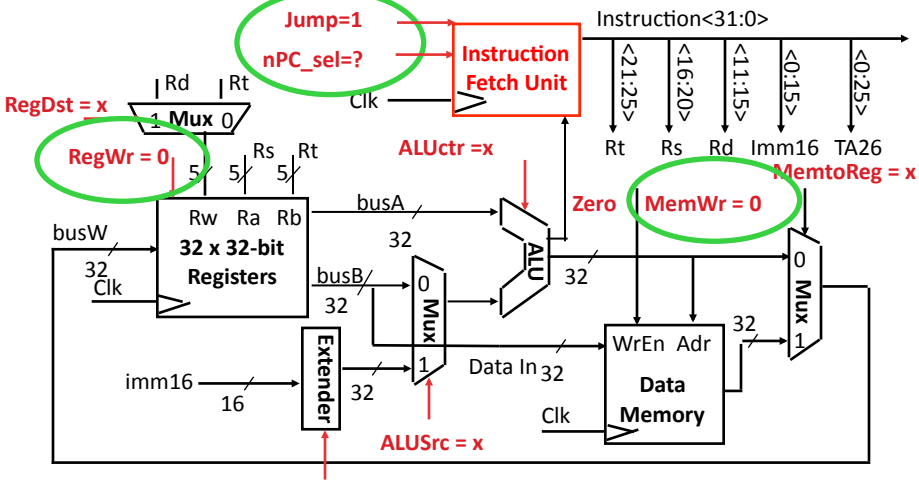
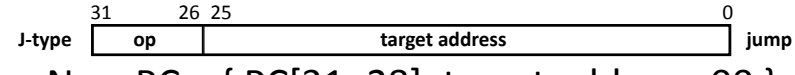


Instruction Fetch Unit at the End of Jump



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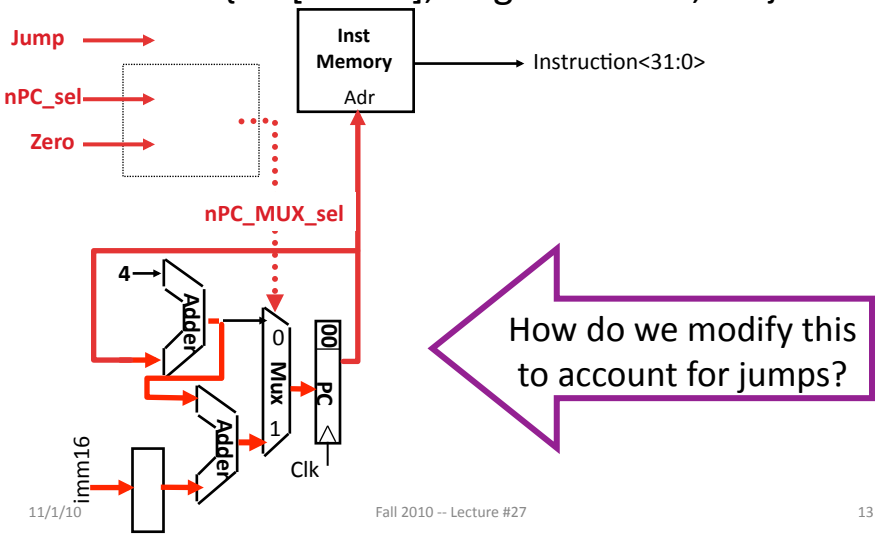

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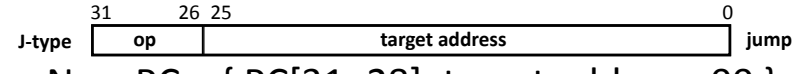

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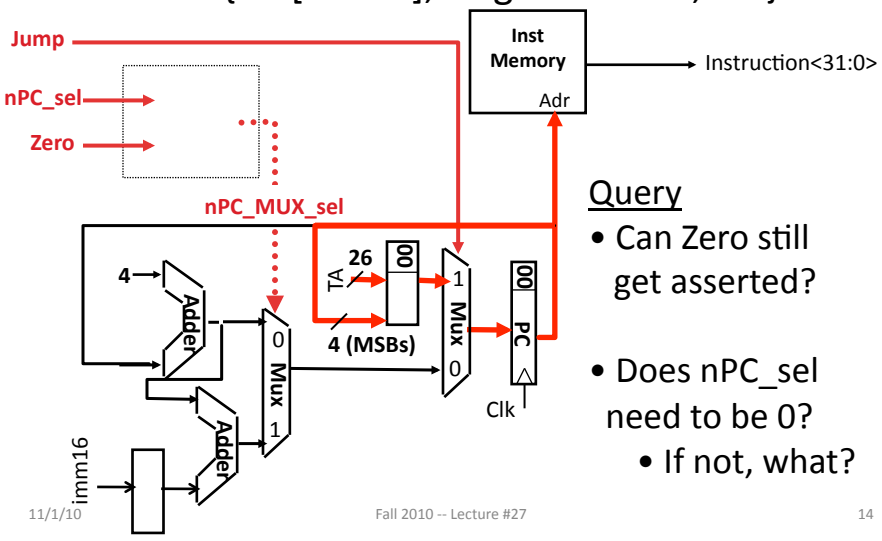

Query

- Can Zero still get asserted?
- Does nPC_sel need to be 0?
  - If not, what?

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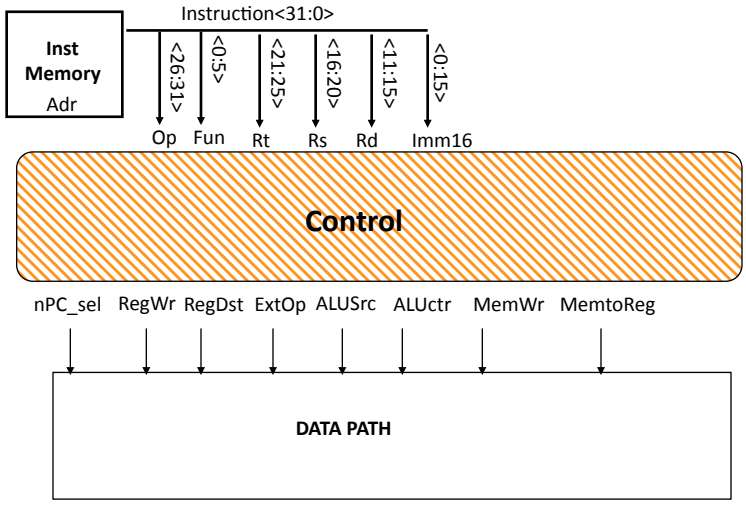
Given Datapath: RTL → Control



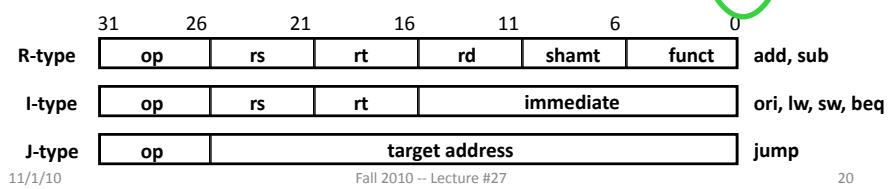
Summary of the Control Signals (1/2)

inst	Register Transfer
add	R[rd] ← R[rs] + R[rt]; PC ← PC + 4
	ALUsrc=RegB, ALUctr="ADD", RegDst=rd, RegWr, nPC_sel="+4"
sub	R[rd] ← R[rs] – R[rt]; PC ← PC + 4
	ALUsrc=RegB, ALUctr="SUB", RegDst=rd, RegWr, nPC_sel="+4"
ori	R[rt] ← R[rs] + zero_ext(Imm16); PC ← PC + 4
	ALUsrc=Im, Extop="Z", ALUctr="OR", RegDst=rt,RegWr, nPC_sel="+4"
lw	R[rt] ← MEM[R[rs] + sign_ext(Imm16)]; PC ← PC + 4
	ALUsrc=Im, Extop="sn", ALUctr="ADD", MemtoReg, RegDst=rt, RegWr, nPC_sel = "+4"
sw	MEM[R[rs] + sign_ext(Imm16)] ← R[rs]; PC ← PC + 4
	ALUsrc=Im, Extop="sn", ALUctr = "ADD", MemWr, nPC_sel = "+4"
beq	if (R[rs] == R[rt]) then PC ← PC + sign_ext(Imm16)] || 00 else PC ← PC + 4
	nPC_sel = "br", ALUctr = "SUB"

Summary of the Control Signals (2/2)

See Appendix A

	func	10 0000	10 0010	We Don't Care :-)				
	op	00 0000	00 0000	00 1101	10 0011	10 1011	00 0100	00 0010
		add	sub	ori	lw	sw	beq	jump
RegDst		1	1	0	0	x	x	x
ALUSrc		0	0	1	1	1	0	x
MemtoReg		0	0	0	1	x	x	x
RegWrite		1	1	1	1	0	0	0
MemWrite		0	0	0	0	1	0	0
nPCsel		0	0	0	0	0	1	?
Jump		0	0	0	0	0	0	1
ExtOp		x	x	0	1	1	x	x
ALUctr<2:0>		Add	Subtract	Or	Add	Add	Subtract	x



Boolean Expressions for Controller

```
RegDst    = add + sub
ALUSrc    = ori + lw + sw
MemtoReg  = lw
RegWrite  = add + sub + ori + lw
MemWrite  = sw
nPCsel    = beq
Jump      = jump
ExtOp     = lw + sw
ALUctr[0] = sub + beq   (assume ALUctr is 00 ADD, 01 SUB, 10 OR)
ALUctr[1] = or
```

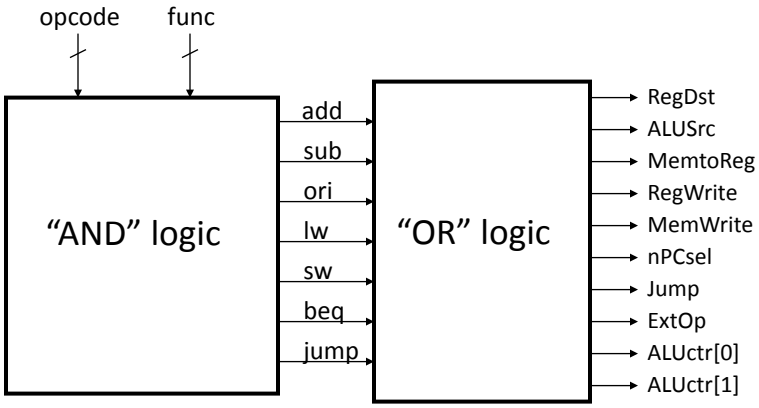
Where:

$rtype = \sim op_5 \cdot \sim op_4 \cdot \sim op_3 \cdot \sim op_2 \cdot \sim op_1 \cdot \sim op_0$,
$ori = \sim op_5 \cdot \sim op_4 \cdot op_3 \cdot op_2 \cdot \sim op_1 \cdot op_0$
$lw = op_5 \cdot \sim op_4 \cdot \sim op_3 \cdot \sim op_2 \cdot op_1 \cdot op_0$
$sw = op_5 \cdot \sim op_4 \cdot op_3 \cdot \sim op_2 \cdot op_1 \cdot op_0$
$beq = \sim op_5 \cdot \sim op_4 \cdot \sim op_3 \cdot op_2 \cdot \sim op_1 \cdot \sim op_0$
$jump = \sim op_5 \cdot \sim op_4 \cdot \sim op_3 \cdot \sim op_2 \cdot op_1 \cdot \sim op_0$

How do we implement this in gates?

$add = rtype \cdot func_5 \cdot \sim func_4 \cdot \sim func_3 \cdot \sim func_2 \cdot \sim func_1 \cdot \sim func_0$
$sub = rtype \cdot func_5 \cdot \sim func_4 \cdot \sim func_3 \cdot \sim func_2 \cdot func_1 \cdot \sim func_0$

Controller Implementation



Summary: Single-cycle Processor

- Five steps to design a processor:
  1. Analyze instruction set → datapath requirements
  2. Select set of datapath components & establish clock methodology
  3. Assemble datapath meeting the requirements
  4. Analyze implementation of each instruction to determine setting of control points that effects the register transfer.
  5. Assemble the control logic
     - Formulate Logic Equations
     - Design Circuits