

EECS151/251A Discussion 8

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Plan for Today

- Practice Problem
- Your Questions

Quick Reminder about Dynamic Power

- $P_{SW} = \frac{1}{2} \alpha C V_{DD}^2 F$
- P_{SW} : Switching Power
- α : Activity Factor (Avg. Percentage of Nodes to Switch)
- C : Total Chip Capacitance
- V_{DD} : VDD of Chip
- F : Clock Frequency

- From the Chip-Level “Dynamic” Power Slide of Lecture 12

Problem 1: Overclocking

- Let us take a hypothetical CPU which nominally operates with a 3 GHz clock at a VDD of 0.9 V.
- Let us assume that the VDD required to support a particular clock frequency can be approximated as the linear function $VDD = 0.0002f + 0.3$ where f is the clock frequency in MHz and VDD is in V.
 - a) Approximately what VDD is required to run the CPU at 4 GHz?
 - b) What is the ratio of active power dissipation between an overclocked CPU running at 4 GHz compared to the same CPU running at 3 GHz?

Problem 1(a): Finding New VDD

- $V_{DD} = 0.0002f + 0.3$
- $V_{DD} = 0.0002(4000) + 0.3$
- $V_{DD} = 1.1V$

Problem 1(b): Power Ratio

- 3 GHz Operating Point

- $P_{SW3} = \frac{1}{2} \alpha C V_{DD}^2 F$
- $P_{SW3} = \frac{1}{2} \alpha C (0.9V)^2 (3 \text{ GHz})$

- 4 GHz Operating Point

- $P_{SW4} = \frac{1}{2} \alpha C V_{DD}^2 F$
- $P_{SW4} = \frac{1}{2} \alpha C (1.1V)^2 (4 \text{ GHz})$

- Capacitance is the same in both cases (chip did not change).
- Activity factor is assumed to be the same (running the same application)

- $\frac{P_{SW4}}{P_{SW3}} = (1.1V)^2 (4 \text{ GHz}) / (0.9V)^2 (3 \text{ GHz})$
- $\frac{P_{SW4}}{P_{SW3}} = 1.998$

- Almost 2x the amount of power is required to run the system at a 1.33x faster clock rate!
- That's 2x the amount of heat that needs to be dissipated
- One of the reasons why overclocking requires a robust power supply and a good cooling solution
- One way to address this is to shut down cores when overclocking.

Problem 2: Parallelism for Lower Power

- A ASIC implementation of a video encoder (Version A) is being modified to be more power efficient (Version B). The new version of the encoder works on segments of a video in parallel. However, there is a price for this parallelism:
 - If τ_{orig} is the critical path delay in version A, the critical path in version B is increased by $0.1 N \tau_{orig}$ where N is the number of parallel video encoders
 - If A_{orig} is the area of version A, in addition to the N replications of the encoder, $0.2 N A_{orig}$ in area overhead is also added to version B
- Version B includes N=4 transcoders

Problem 2: Parallelism for Lower Power

- a) What is the new critical path length of version B?
- b) If version B was run at the fastest rate possible and used all 4 of its encoders, how long would it take to transcode a video compared to version A? (*Assume the required cycles to encode a video can be split evenly across the decoders*)
- c) Using all 4 transcoders, what clock rate is required to transcode a video in the same amount of time as version A?
- d) What is the chip size of version B compared to version A?
- e) How much power is consumed in version B as compared to version A when transcoding a video in the same amount of time (max rate of version A)?

Problem 2(a): New Critical Path Delay

- $\tau_{CPB} = \tau_{orig} + 0.1(4)\tau_{orig}$
- $\tau_{CPB} = 1.4\tau_{orig}$
- $\tau_{CPB} \approx 1.4(333.3 \text{ ps}) = 466.7$
- Fastest clk approx. 2.143 GHz

Problem 2(b): Transcode a Video at Full Speed

- Let L be the number of cycles required to transcode a given video with version A
 - $\tau_{videoA} = \tau_{CPA} L = \tau_{orig} L$
- Version B has 4 transcoders, each of which are capable of splitting the encoding work evenly between them
 - Number of required clock cycles to encode video in version B is $L/4$
- $\tau_{videoB} = \tau_{CPB} L/4 = 1.4\tau_{orig} L/4$
- $\tau_{videoB}/\tau_{videoA} = (1.4\tau_{orig}L/4)/(\tau_{orig} L) = 1.4/4$
- $\tau_{videoB}/\tau_{videoA} = 0.35$
- Not quite $\frac{1}{4}$ the time due to the overhead in version B

Problem 2(c): Slowing Clock Rate

- Want $\tau_{videoB} = \tau_{videoA}$
- Because of the parallel units, if version A requires L cycles to encode a video, version B requires $L/4$ cycles
- $\tau_{videoB} = \tau_{videoA}$
- $\tau_{clkB} L/4 = \tau_{orig} L$
- $\tau_{clkB} = 4 \tau_{orig}$
- $\tau_{clkB} = 4 (333.3 \text{ ps}) = 1.333 \text{ ns}$
- Required clock rate is 750 MHz
- This rate is achievable with version B as it is far below the maximum clock rate
- However, note that this is $\frac{1}{4}$ the max frequency of version A but is less than $\frac{1}{4}$ the max frequency of version B due to delay overhead

Problem 2(d): Chip Area

- There are 2 components to area growth in version B
 - Replicas of the video transcoder
 - Overhead
- $A_B = N A_{orig} + 0.2 N A_{orig}$
- $A_B = 1.2 N A_{orig}$
- $A_B = 1.2 (4) A_{orig}$
- $A_B = 4.8 A_{orig}$

Problem 2(e): Dynamic Power Consumption

- Let us assume that the capacitance is proportional to the area of the chip.
 - $C_B = 4.8 C_{orig}$
- The additional copies of the encoder as well as the overhead increase C for version B as compared to version A
- Activity factor is assumed to be the same (running the same application)
- Assume both chips were produced with the same frequency vs. VDD relationship
 - Version A operates at 0.9V at 3 GHz
 - Version B operates at 0.9V at 3 GHz
 - Find new Y intercept
 - $V_{DD} = 0.0002f + offset$
 - $0.9 = 0.0002(2.143) + offset$
 - $offset = 0.4714$
- $V_{DDB} = 0.0002(750) + 0.4714 = 0.6214V$
- Version A
 - $P_{SWA} = \frac{1}{2} \alpha C_{orig} V_{DD_A}^2 F$
 - $P_{SWA} = \frac{1}{2} \alpha C_{orig} (0.9V)^2 (3 GHz)$
- Version B
 - $P_{SWB} = \frac{1}{2} \alpha C_B V_{DD_B}^2 F$
 - $P_{SWB} = \frac{1}{2} \alpha 4.8 C_{orig} (0.6214V)^2 (0.75 GHz)$
- $\frac{P_{SWB}}{P_{SWA}} = 4.8(0.6214V)^2(0.75 GHz)/(0.9V)^2(3 GHz)$
- $\frac{P_{SWB}}{P_{SWA}} = 0.5721$
- Note, if there was no area overhead, the change in C and the change in F would have canceled.