

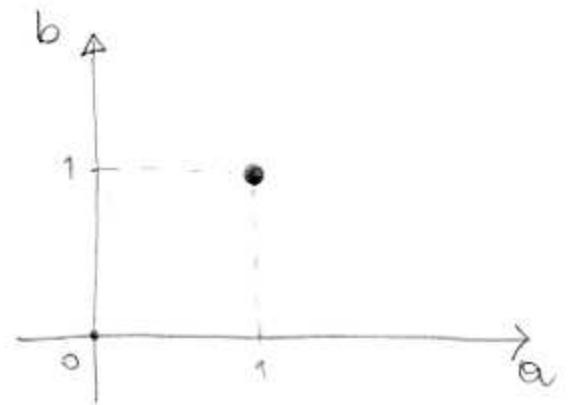
LOGIC MINIMIZATION

We now introduce a way of representing Boolean functions that will help us

in understanding logic minimization.

Consider the two variables function:

a	b	$f(a,b)$
0	0	0
0	1	0
1	0	0
1	1	1



As shown on the right, we can represent the function on a plane whose coordinates are the Boolean variables. Variables can only be 0 or 1 because they are Boolean. In this representation we use a dot to say that, for that input combination, the function evaluates to 1.

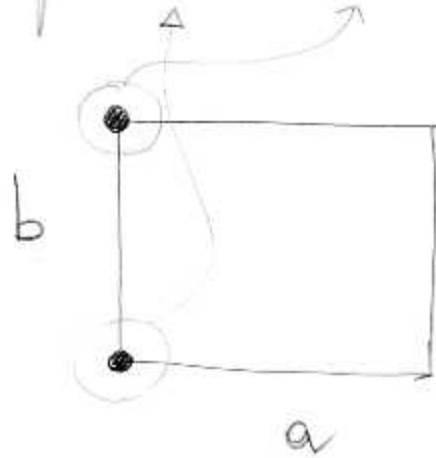
For instance, consider the following function:

a	b	f
0	0	1
0	1	1
1	0	0
1	1	0

cube
representation \rightarrow

Minterm canonical
form:

$$f = a'b' + a'b$$



This function can be simplified:

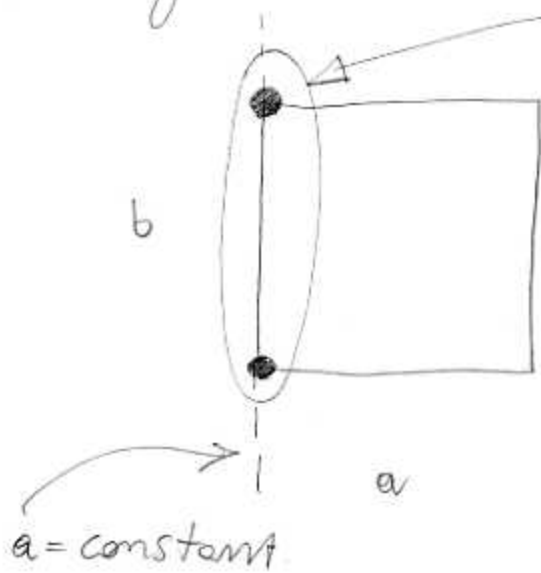
$$f = a'b' + a'b = a'(b' + b) = a'$$

because $b + b' = 1$ (it is one of the postulates of a Boolean algebra).

If we look at the function (I mean the table) we note that there are two rows for which one variable is constant, the other changes and the function is equal to 1. Of course, both minterms are going to appear in the formula representing f and since one variable is constant we can use associativity and put the variable in evidence.

The other variable changes so it is going to appear as the sum of a variable and its negation which is equal to 1.

Using the cube representation:



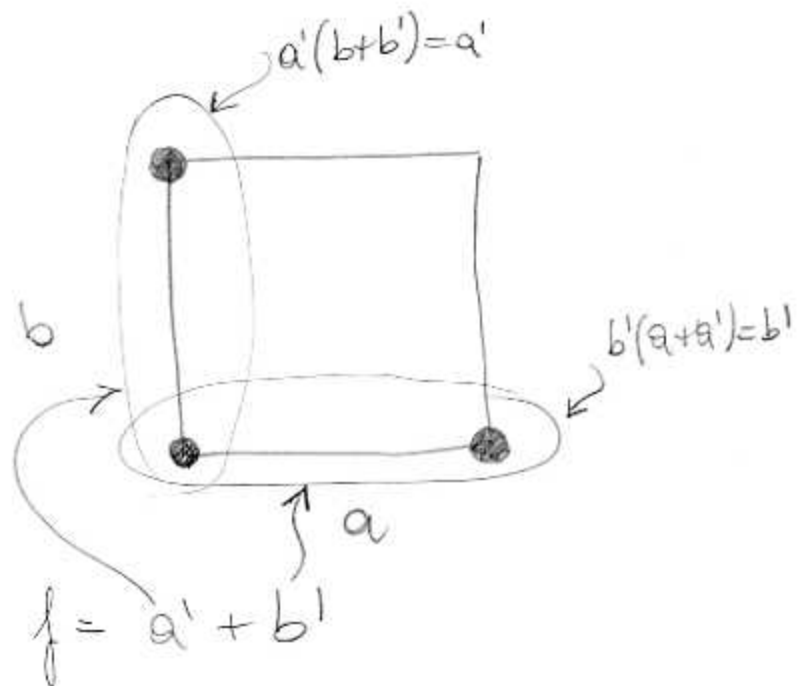
group of adjacent points.

If we group points along the line $a = \text{constant}$ then the term corresponding to that group is equal

just to a' (a' because the line is $a=0$).

For instance;

a	b	f
0	0	1
0	1	1
1	0	1
1	1	0

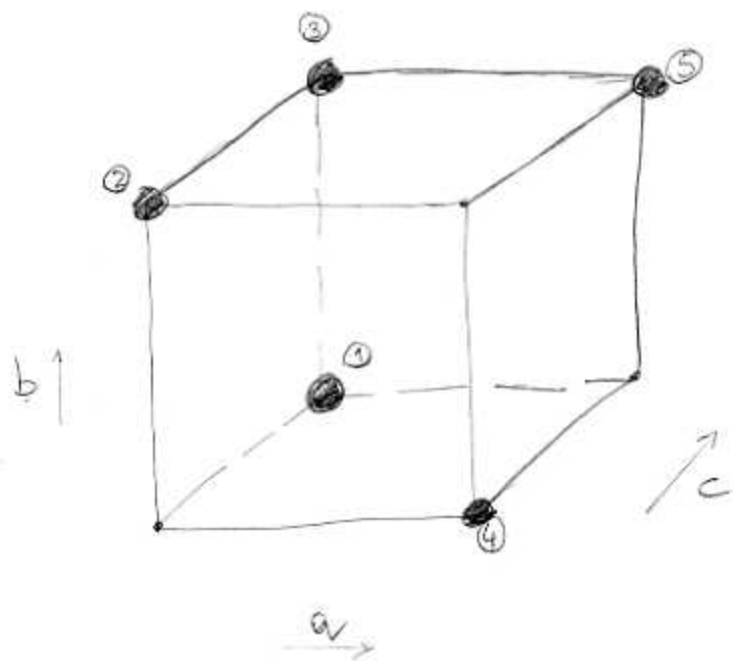


The function is in fact a NAND function $(a \cdot b)' = a' + b'$.

What if we have three variables?

We can use a cube instead of a square.

	a	b	c	f
	0	0	0	0
①	0	0	1	1
②	0	1	0	1
③	0	1	1	1
④	1	0	0	1
	1	0	1	0
	1	1	0	0
⑤	1	1	1	1

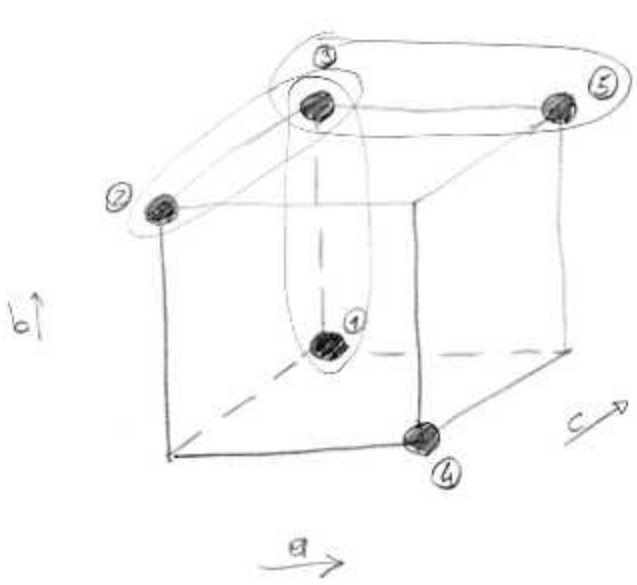


Minterm canonical form:

$$f = a'b'c + a'bc' + a'bc + ab'c' + abc$$

①
②
③
④
⑤

In our function there are adjacent points that we can group to eliminate variables:



$$f = a'b + a'c + bc + abc'$$

\uparrow \uparrow \uparrow
 ②+③ ①+③ ④

\downarrow
 ③+⑤

This formula is "simpler" than the minterm canonical form. It is then clear that grouping minterms is beneficial from complexity point of view.

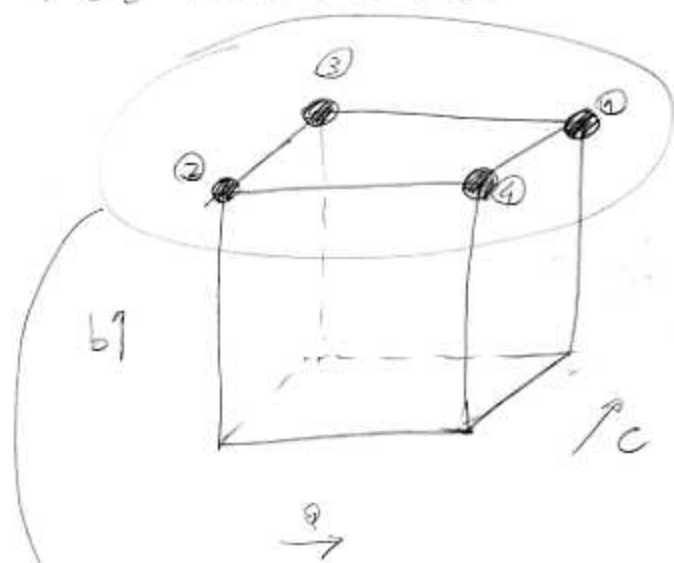
If a function has n variables then a minterm is the "and" of n variables. Now in order for one of them to disappear we need the sum of two minterms where that only variable changes. Meaning:

$$x_1 \dots x_j \dots x_m + x_1 \dots x_j' \dots x_m = x_1 \dots x_{j-1} x_{j+1} \dots x_m \overbrace{(x_j + x_j')}^1$$

where x_1, \dots, x_n are our boolean variables.
 If we want two variables to disappear then we need $n-2$ variables to be fixed and the remaining 2 have to change in all possible combinations.
 So basically in order to drop two variables we should be able to group 4 adjacent points.

Note that grouping 3 points doesn't give us any benefit.

For instance:



$$\begin{aligned}
 f &= bac + ba'c' + ba'c + bac' \\
 &\quad \text{①} \quad \text{②} \quad \text{③} \quad \text{④} \\
 &= b(a'c' + a'c) + b(ac + ac') \\
 &\quad \text{②+③} \quad \text{①+④} \\
 &= ba'(c+c') + b(a(c+c')) = \\
 &= ba' + ba = b(a+a') = \underline{\underline{b}}
 \end{aligned}$$

→ this group is a plane where b is constant and a and c change in all possible combination so $f = b$.

We want to find a way of grouping points in such a way that the resulting formula has the least number of terms and variables.

Note that, for the previous function, the minterm canonical form has 4 terms each containing 3 variables (the 4 points in the cube representation) while the formula we found contains only one term with one variable.

also you can check that the function f is:

$$\begin{array}{ccc|c}
 a & b & c & f \\
 0 & 0 & 0 & 0 \\
 0 & 0 & 1 & 0 \\
 0 & 1 & 0 & 1 \text{ ②} \\
 0 & 1 & 1 & 1 \text{ ③} \\
 1 & 0 & 0 & 0 \\
 1 & 0 & 1 & 0 \\
 1 & 1 & 0 & 1 \text{ ④} \\
 1 & 1 & 1 & 1 \text{ ⑤}
 \end{array}$$

and f is equal to the second column which is b , hence $f=b$

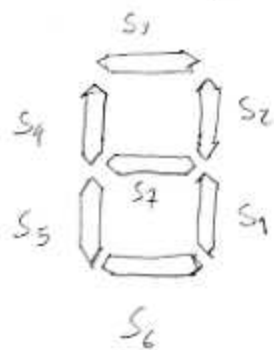
Queen McCluskey algorithm

This algorithm finds the minimum formula representation of a Boolean function when the cost of a formula is the number of terms and/or the number of variables instances in the formula.

Intuitively, the algorithm starts from the function points (in the cube representation) and tries to expand the points along all possible axes, finding all groups of two points. Then recursively the Q.M. algorithm looks for groups of 4 points, then 8 points and so on. At the end it takes the minimum number of groups covering all points in the function. The algorithm is best explained with an example. For instance:

Consider a seven segment display.

It is a device which has 7 LED's laid out as follows



Depending on which LED you switch on, this device displays a different number.



For instance, if S_3, S_2, S_2, S_1, S_6 are switched on then it displays number three (of course all other LED's have to be off.)

We can write a logic function for each segment to display numbers. If we consider 3 inputs, we can display from 0 to 7. The Boolean function for S_3 for instance is:

a	b	c	S_3
0	0	0	1
0	0	1	0
0	1	0	1
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	1
1	1	1	1

(Input number in binary format is abc)

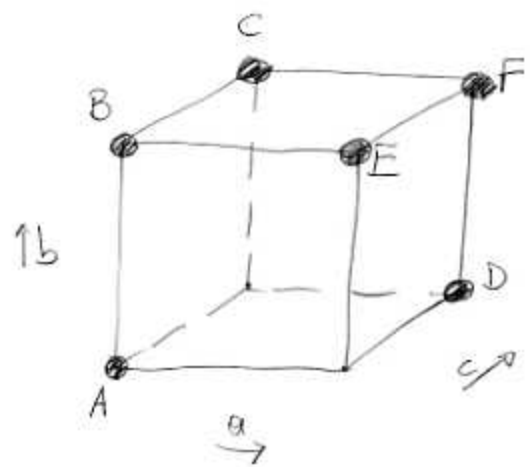
To understand the table consider the following two examples

number	4	7
binary representation	1 0 0	1 1 1
display		
S3	0	1

First step) Consider all the rows for which the function evaluates to 1

0	0	0
0	1	0
0	1	1
1	0	1
1	1	0
1	1	1

A
B
C
D
E
F



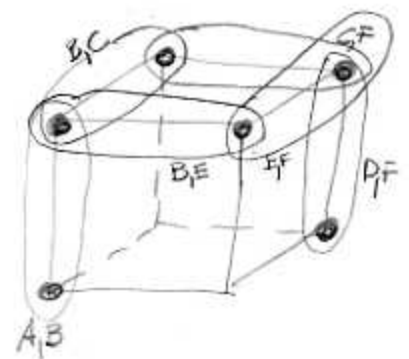
↑ labels

Second step) During this step the Q.M. algorithm tries to find

all possible pairs of adjacent points. When a pair is found, the variable that changes is substituted with the symbol $-$. Also we mark the two points that originated the new group, to remember that the new group actually covers the previous two points. In order to do this, we look at all possible pair of point. If only one variable changes between the two minterms then we generate a new element substituting a dash to that variable:

A	0	0	0	✓		A, B	0	-	0
B	0	1	0	✓		B, C	0	1	-
C	0	1	1	✓		B, E	-	1	0
D	1	0	1	✓	→	C, F	-	1	1
E	1	1	0	✓		D, F	1	-	1
F	1	1	1	✓		E, F	1	1	-

mark ↗



we have basically found all groups of 2 adjacent points.

Third step) Now we want to find all possible groups of 4 points. We then look at all elements generated in the second step. We group them in pairs if they have a dash in the same position and if, among all other variables, only one changes:

$A_1 B$ 0 - 0

$B_1 C$ 0 1 - \checkmark

$B_1 E$ - 1 0 \checkmark

$C_1 F$ - 1 1 $\checkmark \rightarrow$

$D_1 F$ 1 - 1

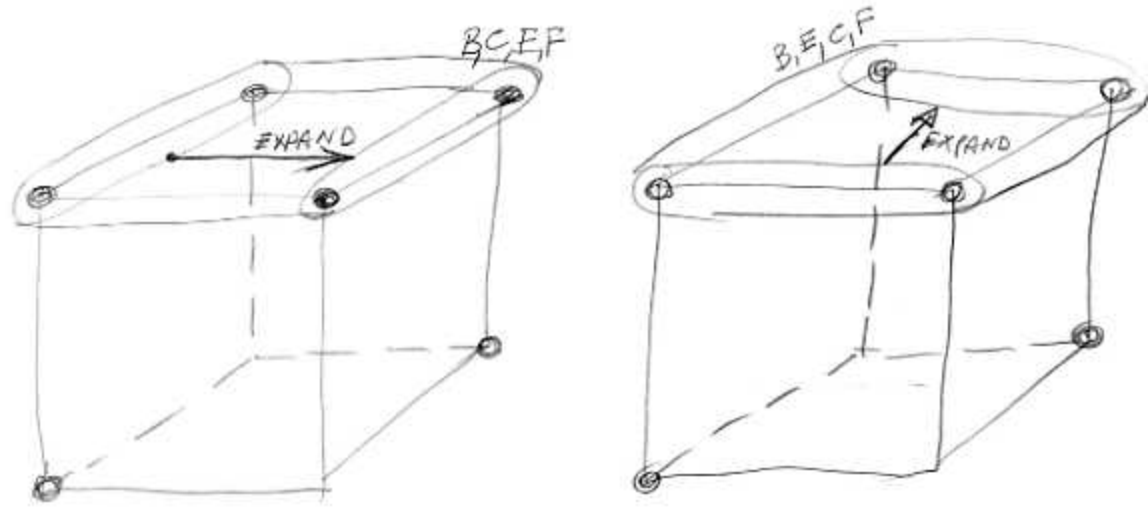
$E_1 F$ 1 1 - \checkmark

$B_1 C_1 E_1 F$ - 1 -

$B_1 E_1 C_1 F$ - 1 -

Now we have only one term so the algorithm cannot go ahead. In general it should be continued until no more pairs are possible (so after this step, look for groups of 8 points, 16 points and so on)

What we have done in step three is to expand 2 points group into 4 points groups:



The terms that are not marked are :

A, B	0 - 0	P1	these are called <u>prime implicants</u>
D, F	1 - 1	P2	
BC, EF, BE, CF	- 1 -	P3	

The last step) Requires to build a table whose rows are the minterms and whose columns are the prime implicants

An entry (i, j) in the table is marked if minterm i is covered by prime implicant j .

In our case :

	P_1	P_2	P_3
A	X		
B	X		X
C			X
D		X	
E			X
F		X	X

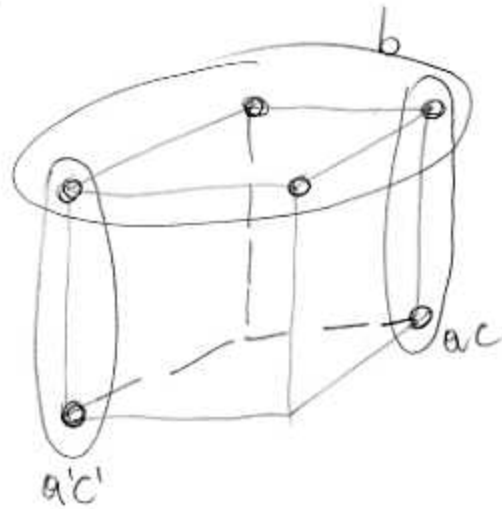
Now we have to find the minimum number of columns such that there is an X in every row. This problem is called unate covering and it is an NP-complete problem.

In our case we need all three prime implicants to cover the minterms

so the minimum formula for S_3 is:

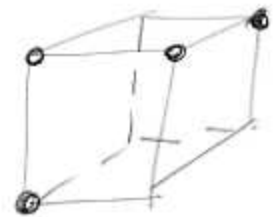
$$S_3 = \underbrace{a'c'}_{P_1} + \underbrace{ac}_{P_2} + \underbrace{b}_{P_3}$$

which represents the following groups:



As an example of the last step where some prime implicants may disappear consider the function:

a	b	c		f
0	0	0		1
0	0	1		0
0	1	0		1
0	1	1		0
1	0	0		0
1	0	1		0
1	1	0		1
1	1	1		1



A	0	0	0
B	0	1	0
C	1	1	0
D	1	1	1

→

A,B	0-0	P ₁
B,C	-10	P ₂
C,D	11-	P ₃

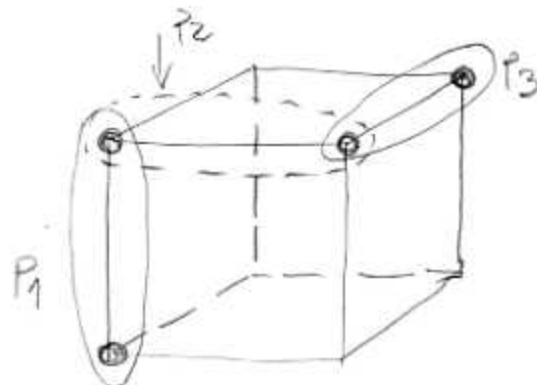
↑

no other pairs
are possible
(basically there are
no 4 points groups)

	P ₁	P ₂	P ₃
A	X		
B	X	X	
C		X	X
D			X

In this case P₁ and P₃ cover all
the minterms and P₂ is not needed:

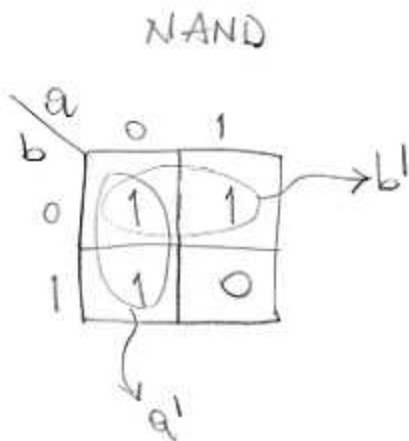
$$f = a'c' + ab$$



Karnaugh maps

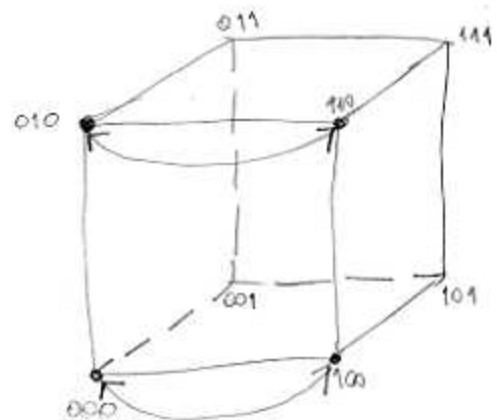
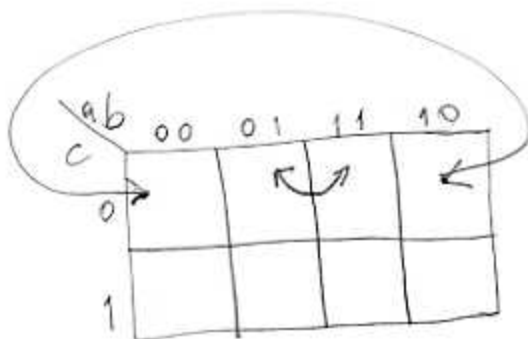
It is a 2 dimensional representation of a Boolean function.

For a two variables Boolean function is basically equivalent to the cube representation:



$$f = a' + b' - (ab)'$$

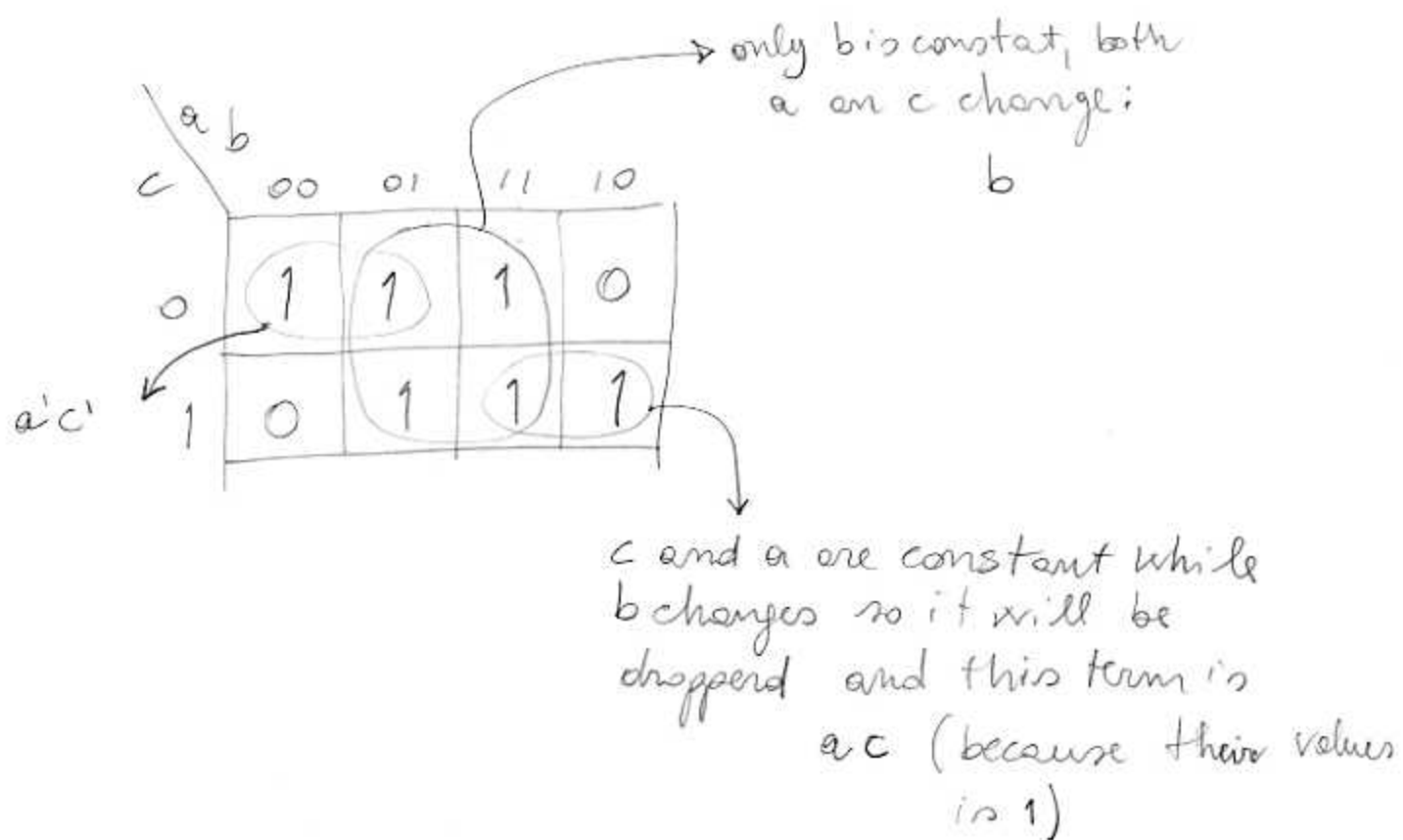
In the case of 3 variables then we can put 2 variables on the columns and 1 on the rows:



Note that only one variable changes from one cell to the other and the reason can be understood by looking at the cube representation. All cells in the K-map are now adjacent!!!

Now we can use K-maps to group adjacent ones and simplify Boolean functions.

For S_3 , for instance:



$$f = ac + a'b + b$$

In K-maps then we have to group ones in as bigger groups as possible. Remember that the number of ones in a group has to be a power of 2 (2, 4, 8, 16 ---). Also consider the fact that K-maps are basically folded, so:

		ab			
		00	01	11	10
c	0	1	1	0	1
	1	1	0	0	1

$$f = b' + a'c'$$