

Modeling Spring/Mass System: By Neil Warren and James Johnston

Step 1: Write Differential Equation -

$$m*d^{2}[x(t)]/dt^{2}=k*x(t)+B*dx/dt+force(t)$$

Step 2: Define Initial Conditions - x(0) = 0 & d[x(0)]/dt = 0

Step 3: Apply Laplace Transform $f^{(n)}(t) = s^{nF}(s) - s^{(n-1)}f(0) - s^{(n-2)}f'(0) - \ldots - f^{(n-1)}(0)$

Which yields:
$$s^2 * m*X(s) = force(s) + B*s*X(s) + k*X(s)$$

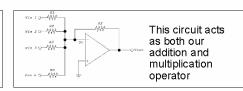
Step 4: Solve for Laplace Transform of Solution:

$$X(s)=(s^2*m)^{-1}*force(s)+B*(s*m)^{-1}*X(s)+k*(s^2*m)^{-1}*X(s)$$

Step 5: Identify Circuit Building Blocks:



This circuit acts as our -1/s operator when appropriate R and C values added.



Another Way Of Looking At The Problem:

To further simplify the problem of modelling the equation using circuitry, we convert the equation into a system representation. This provides an intermediate step between the circuitry and the differential equation.

