

1 *Curve Fitting*

The purpose of this exercise is to observe the *bias-variance* tradeoff that is endemic in all system identification problems.

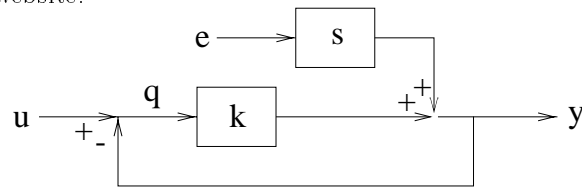
We are given input-output data from some process. We have reason to believe that this process is not *dynamic*. This data may be found at [www-inst.EECS.Berkeley.EDU/ ee290h/homeworks](http://www-inst.EECS.Berkeley.EDU/ee290h/homeworks).

Find a good polynomial fit to this data. Remember to use only part of the data for modeling and the rest for model verification.

2 *Maximum Likelihood Estimation*

In this exercise, you will work through the details of a maximum likelihood estimation. You will first try a clever *ad hoc* method, and discover the dangers of intuition in estimation. Then, you will revisit the problem using maximum likelihood estimation.

Shown below is the block diagram of a simple feedback process. The noise process  $e$  is white and  $\mathcal{N}(0, 1)$ . The parameters  $s$  and  $k$  are to be estimated. Suppose we have available an  $L$  sample input-output data record  $\{u_t^d, y_t^d\}_{t=1}^L$ . This data was generated using the true parameter values  $k^o = 7$  and  $s^o = 2$ , and using a white Gaussian input with zero mean and variance  $\sigma_u^2 = 1.5$ . The data may be found at the EE 290H website.



- (a) Consider the following “clever” idea. Since we have  $u$  and  $y$  available, we know the signal  $q$ . We could then use least squares to get an estimate  $k_{LS}$ . Find a formula for this estimate and evaluate it using the given data.
- (b) You will notice that it isn’t very good at all. Show that for large data records. i.e.  $L \rightarrow \infty$ ,

$$k_{LS} \rightarrow k^o - \frac{(s^o)^2(1+k^o)}{(s^o)^2 + \frac{\sigma_y^2}{\sigma_u^2}}$$

Thus this clever idea works well if the noise-to-signal ratio is small. But in our case, you should expect

$$k_{LS} \approx 1.18$$

which means the idea isn’t clever at all. So lets try maximum likelihood estimation now.

- (c) Find the formula relating  $y$  to  $e$  and  $u$ .
- (d) Find the density function  $p_Y(y, s, k)$  and the log-likelihood function.
- (e) Find the formulae for the maximum likelihood estimates of  $k$  and  $s$ , and also for the estimated parameter variances.

(f) Evaluate our answers above using the given data. Maximum likelihood estimation works very well !

(g) Show that as  $L \rightarrow \infty$  (i.e. as we have more and more data),

$$\hat{s}_{ML} \rightarrow s^o, \text{ and } \hat{k}_{ML} \rightarrow k^o$$

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In proving some of the results in Problem 2, you will need the following facts.

Suppose  $u$  and  $e$  are zero mean white noise processes with variances  $\sigma_u^2$  and  $\sigma_e^2$  respectively. Also suppose that  $u$  and  $e$  are uncorrelated with each other. Then

$$\lim_{L \rightarrow \infty} \frac{1}{L} u'e = \lim_{L \rightarrow \infty} \frac{1}{L} \sum_{t=1}^L u_t e_t = 0$$

$$\lim_{L \rightarrow \infty} \frac{1}{L} u'u = \lim_{L \rightarrow \infty} \frac{1}{L} \sum_{t=1}^L u_t u_t = \sigma_u^2$$