

1. (20 pts) Z transform review

Bob gets a loan with principal  $p[0] = \$200,000$ . The loan is interest only with an annual interest rate of 8%. The loan is negative amortization if the annual payment is less than  $0.08p[n]$ . If the annual payment is greater than  $0.08p[n]$ , the principal balance is reduced. At year  $n = 0$ , Bob has an annual salary of  $s[0] = \$100,000$ . Bob's salary increases by 4% per year, and he uses 10% of his gross salary to pay interest and principal on the loan. Solve for  $p[n]$  using Z-transforms. When does the loan get paid off?

2. (30 pts) Steady State Error

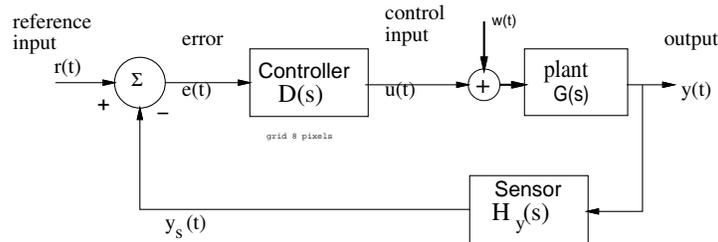
For the system below, let  $D(s) = 1$ ,  $G(s) = \frac{10(s+10)}{s(s+2)}$ ,  $w(t) = 0$ , and  $H_y(s) = s + 4$ .

- What is the system type?
- What input waveform  $r(t)$  would yield a constant non-zero error in steady state? (e.g. step, ramp, parabola, or ?)
- What is the steady state error for a unit input of  $r(t)$  from b)?

3. (25 pts) PID control

For the system below, let  $D(s) = k_p + \frac{k_I}{s} + k_D s$ ,  $H_y(s) = 1$ , and  $G(s) = \frac{1}{s^2 + 2\zeta\omega_n s + \omega_n^2}$ .

- With  $r(t) = 0$ , determine the system type (0, 1, 2, ...) and trend of  $e(t)$  as  $t \rightarrow \infty$  with respect to step disturbance input  $W(s)$ .
- With  $w(t) = 0$ , determine the system type (0, 1, 2, ...) and trend of  $e(t)$  as  $t \rightarrow \infty$  with respect to step and ramp reference inputs  $R(s)$ .



4. (25 pts) 2nd order step response

A memory system can be made using a mechanical head positioning system to read data stored on a surface, e.g. the IBM millipede [1]. The head positioning system can be approximately modelled by the transfer function from applied force  $F(s)$  to output position  $X(s)$ :

$$\frac{X(s)}{F(s)} = \frac{1}{ms^2 + bs + k}$$

Assume that  $m = 10^{-11} kg$ ,  $b = 2 \times 10^{-6} N \cdot sec \cdot m^{-1}$  and  $k = 0.2 N \cdot m^{-1}$ .

- Find the pole locations and sketch in the  $s$ -plane, and find  $\zeta$ ,  $\omega_n$ ,  $\theta = \sin^{-1} \zeta$ , and  $\omega_d$ .
- For a  $1 \mu N$  step, determine peak overshoot ( $\mu m$ ), time to peak, and time for settling to within  $1 nm$  of final value.
- Repeat b) for  $1 nN$  step.

Reference:

- Pantazi, A.; et al. "Probe-based ultrahigh-density storage technology," *IBM Journal of Research and Development*, vol.52, no.4.5, pp.493,511, July 2008  
 doi: 10.1147/rd.524.0493