

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & a_{15} & a_{16} & a_{17} & a_{18} & a_{19} & a_{1,10} \\ a_{21} & a_{22} & a_{23} & a_{24} & a_{25} & a_{26} & a_{27} & a_{28} & a_{29} & a_{2,10} \\ a_{31} & a_{32} & a_{33} & a_{34} & a_{35} & a_{36} & a_{37} & a_{38} & a_{39} & a_{3,10} \\ a_{41} & a_{42} & a_{43} & a_{44} & a_{45} & a_{46} & a_{47} & a_{48} & a_{49} & a_{4,10} \\ a_{51} & a_{52} & a_{53} & a_{54} & a_{55} & a_{56} & a_{57} & a_{58} & a_{59} & a_{5,10} \\ a_{61} & a_{62} & a_{63} & a_{64} & a_{65} & a_{66} & a_{67} & a_{68} & a_{69} & a_{6,10} \\ a_{71} & a_{72} & a_{73} & a_{74} & a_{75} & a_{76} & a_{77} & a_{78} & a_{79} & a_{7,10} \\ a_{81} & a_{82} & a_{83} & a_{84} & a_{85} & a_{86} & a_{87} & a_{88} & a_{89} & a_{8,10} \\ a_{91} & a_{92} & a_{93} & a_{94} & a_{95} & a_{96} & a_{97} & a_{98} & a_{99} & a_{9,10} \\ a_{10,1} & a_{10,2} & a_{10,3} & a_{10,4} & a_{10,5} & a_{10,6} & a_{10,7} & a_{10,8} & a_{10,9} & a_{10,10} \end{bmatrix}}_{\mathbf{A}} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \\ x_9 \\ x_{10} \end{bmatrix}}_{\mathbf{x}} = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \\ b_5 \\ b_6 \\ b_7 \\ b_8 \\ b_9 \\ b_{10} \end{bmatrix}}_{\mathbf{b}}$$

CRAMER'S RULE

If $\det \mathbf{A} \neq 0$, then the solution $\mathbf{x} = [x_i]$ of the system of linear equations

$$\mathbf{Ax} = \mathbf{b}$$

is given by

$$x_i = \frac{\Delta_i}{\Delta}$$

$$i = 1, 2, \dots, n$$

where $\Delta = \det \mathbf{A}$ and $\Delta_i = \det \mathbf{A}_{(i)}$, where $\mathbf{A}_{(i)}$ is the matrix obtained by replacing the i th column of \mathbf{A} by \mathbf{b} .

Determinant of \mathbf{A}

For a 3×3 matrix

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\begin{aligned} \det \mathbf{A} &= a_{11}(a_{22}a_{33} - a_{23}a_{32}) \\ &\quad - a_{21}(a_{12}a_{33} - a_{13}a_{32}) \\ &\quad + a_{31}(a_{12}a_{23} - a_{22}a_{13}) \triangleq \Delta \end{aligned}$$

Remark

An extension of the above procedure can be used to find $\det \mathbf{A}$ of any $n \times n$ matrix \mathbf{M} . However, for $n > 3$, it is too cumbersome and error prone to compute **determinants** manually. Almost every numerical analysis software includes a subroutine to compute determinants.

Determinant of \mathbf{A}

Given

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & & & \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}$$

$$\det \mathbf{A} = \sum_{j=1}^n a_{jk} A_{jk}$$

for any $k = 1, 2, \dots, n$

Minor and Cofactor of a_{ij} of \mathbf{A}

Definition:

The determinant of the $(n-1) \times (n-1)$ matrix formed by deleting the i th row and the j th column of the $n \times n$ matrix \mathbf{A} is called the **minor** of element a_{ij} of \mathbf{A} , and is denoted by M_{ij} .

The number

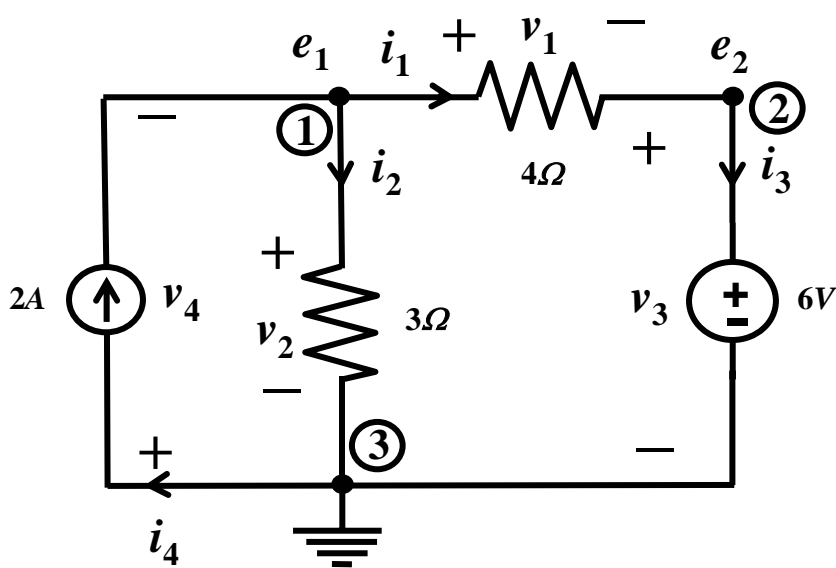
$$A_{ij} = (-1)^{i+j} M_{ij}$$

is called the **cofactor** of a_{ij} .

Remark

The signs $(-1)^{i+j}$ form a checkerboard pattern:

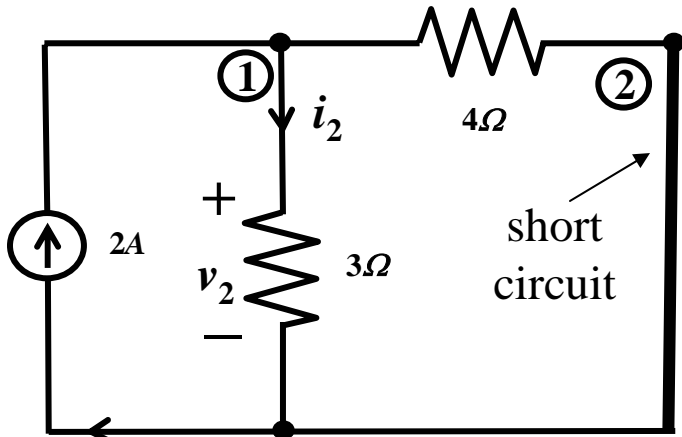
$$\begin{bmatrix} + & - & + & \cdots \\ - & + & - & \cdots \\ + & - & + & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$



Problem :
Find v_2 .

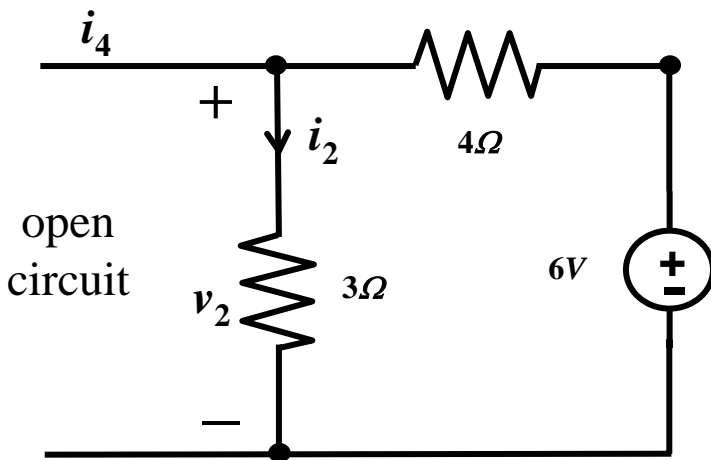
Solution-by-Inspection

Step1. Find voltage component solutions.



The 2 resistors in the simplified circuit are connected in parallel:

$$v_2' = \left(\frac{3 \cdot 4}{3 + 4} \right) (2) \\ = \frac{24}{7} V$$



The simplified circuit is a voltage divider:

$$v_2'' = \left(\frac{3}{3 + 4} \right) (6) \\ = \frac{18}{7} V$$

Step2. Add voltage component solutions.

$$v_2 = v_2' + v_2'' = \frac{24}{7} + \frac{18}{7} = \frac{42}{7} V$$

Let us rearrange all 10 independent equations as follow:

$$\begin{bmatrix}
 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & -1 \\
 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\
 \hline
 -1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
 \hline
 0 & 0 & -1 & 0 & 0 & 0 & 4 & 0 & 0 & 0 \\
 0 & 0 & 0 & -1 & 0 & 0 & 0 & 3 & 0 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1
 \end{bmatrix}
 \begin{bmatrix}
 e_1 \\
 e_2 \\
 \hline
 v_1 \\
 v_2 \\
 v_3 \\
 v_4 \\
 \hline
 i_1 \\
 i_2 \\
 i_3 \\
 i_4
 \end{bmatrix}
 =
 \begin{bmatrix}
 0 \\
 0 \\
 \hline
 0 \\
 0 \\
 0 \\
 0 \\
 \hline
 0 \\
 0 \\
 6 \\
 2
 \end{bmatrix}$$

$\det \mathbf{A} =$

$$\begin{vmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\ \hline -1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & -1 & 0 & 0 & 0 & 4 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{vmatrix}$$

$\triangleq \Delta$

\mathbf{A}

$\det \mathbf{A}_1 =$

$$\begin{vmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\ \hline 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & -1 & 0 & 0 & 0 & 4 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 3 & 0 & 0 \\ 6 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{vmatrix}$$

$\triangleq \Delta_1$

\mathbf{A}_1

$\det \mathbf{A}_4 =$

$$\left| \begin{array}{cc|cccc|cccc} 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\ \hline -1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & -1 & 0 & 0 & 0 & 4 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 6 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 1 \end{array} \right|$$

 $\triangleq \Delta_4$ \mathbf{A}_4

$\det \mathbf{A}_9 =$

$$\begin{vmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 \\ \hline -1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & -1 & 0 & 0 & 0 & 4 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 1 \end{vmatrix}$$

$\triangleq \Delta_9$

\mathbf{A}_9

$$\begin{aligned}
e_1 &= \frac{\Delta_1}{\Delta} \\
&= \frac{1}{\Delta} \left\{ \begin{array}{l} 0 \cdot A_{11} + 0 \cdot A_{21} + 0 \cdot A_{31} + 0 \cdot A_{41} + 0 \cdot A_{51} \\ + 0 \cdot A_{61} + 0 \cdot A_{71} + 0 \cdot A_{81} + 6 \cdot A_{91} + 2 \cdot A_{10,1} \end{array} \right\} \\
&= \frac{1}{\Delta} (6 \cdot A_{91} + 2 \cdot A_{10,1}), \quad \text{because } a_{11} = a_{21} = \dots = a_{81} = 0
\end{aligned}$$

$$= \underbrace{\frac{A_{91}}{\Delta}}_{k_{11}} (6) + \underbrace{\frac{A_{10,1}}{\Delta}}_{k_{12}} (2)$$

$$= k_{11} \bullet 6 + k_{12} \bullet 2$$

$$= k_{11} \bullet v_{s1} + k_{12} \bullet i_{s1}$$

$$i_9 = \frac{\Delta_9}{\Delta}$$

$$= \frac{1}{\Delta} \left\{ \begin{array}{l} 0 \cdot A_{19} + 0 \cdot A_{29} + 0 \cdot A_{39} + 0 \cdot A_{49} + 0 \cdot A_{59} \\ + 0 \cdot A_{69} + 0 \cdot A_{79} + 0 \cdot A_{89} + 6 \cdot A_{99} + 2 \cdot A_{10,9} \end{array} \right\}$$

$$= \frac{1}{\Delta} (6 \cdot A_{99} + 2 \cdot A_{10,9})$$

$$= \underbrace{\frac{A_{99}}{\Delta}}_{k''_{11}} (6) + \underbrace{\frac{A_{10,9}}{\Delta}}_{k''_{12}} (2)$$

$$= k''_{11} \bullet v_{s1} + k''_{12} \bullet i_{s1}$$

$$v_2 = \frac{\Delta_4}{\Delta}$$

$$= \frac{1}{\Delta} \left\{ \begin{array}{l} 0 \cdot A_{14} + 0 \cdot A_{24} + 0 \cdot A_{34} + 0 \cdot A_{44} + 0 \cdot A_{54} \\ + 0 \cdot A_{64} + 0 \cdot A_{74} + 0 \cdot A_{84} + 6 \cdot A_{94} + 2 \cdot A_{10,4} \end{array} \right\}$$

$$= \frac{1}{\Delta} (6 \cdot A_{94} + 2 \cdot A_{10,4})$$

$$= \underbrace{\frac{A_{94}}{\Delta}}_{k'_{11}} (6) + \underbrace{\frac{A_{10,4}}{\Delta}}_{k'_{12}} (2)$$

$$= k'_{11} \bullet v_{s1} + k'_{12} \bullet i_{s1}$$

Let us rearrange all 10 independent equations as follow:

$$\begin{bmatrix}
 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & -1 \\
 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\
 -1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
 0 & 0 & -1 & 0 & 0 & 0 & 4 \frac{d}{dt} & 0 & 0 & 0 \\
 0 & 0 & 0 & 2 \frac{d}{dt} & 0 & 0 & 0 & -1 & 0 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1
 \end{bmatrix}
 \begin{bmatrix}
 e_1 \\
 e_2 \\
 v_1 \\
 v_2 \\
 v_3 \\
 v_4 \\
 i_1 \\
 i_2 \\
 i_3 \\
 i_4
 \end{bmatrix}
 =
 \begin{bmatrix}
 0 \\
 0 \\
 0 \\
 0 \\
 0 \\
 0 \\
 0 \\
 0 \\
 6 \sin \omega t \\
 2 \cos \omega t
 \end{bmatrix}$$

Let us rearrange all 10 independent equations as follow:

$$\begin{bmatrix}
 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & -1 \\
 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\
 \hline
 -1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
 \hline
 0 & 0 & -1 & 0 & 0 & 0 & L_1 \frac{d}{dt} & 0 & 0 & 0 \\
 0 & 0 & 0 & C_2 \frac{d}{dt} & 0 & 0 & 0 & -1 & 0 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1
 \end{bmatrix}
 \begin{bmatrix}
 e_1 \\
 e_2 \\
 \hline
 v_1 \\
 v_2 \\
 v_3 \\
 v_4 \\
 \hline
 i_1 \\
 i_2 \\
 i_3 \\
 i_4
 \end{bmatrix}
 =
 \begin{bmatrix}
 0 \\
 0 \\
 \hline
 0 \\
 0 \\
 0 \\
 0 \\
 \hline
 0 \\
 0 \\
 6 \sin \omega t \\
 2 \cos \omega t
 \end{bmatrix}$$

$$\begin{array}{c}
 \left[\begin{array}{cccc|cccc}
 -1 & 0 & 0 & 0 & 4\frac{d}{dt} & 0 & 0 & 0 \\
 0 & 2\frac{d}{dt} & 0 & 0 & 0 & -1 & 0 & 0 \\
 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1
 \end{array} \right]
 \begin{array}{c}
 \left[\begin{array}{c}
 v_1 \\
 v_2 \\
 v_3 \\
 v_4 \\
 \hline
 i_1 \\
 i_2 \\
 i_3 \\
 i_4
 \end{array} \right]
 =
 \begin{array}{c}
 \left[\begin{array}{c}
 0 \\
 0 \\
 6\sin \omega t \\
 2\cos \omega t
 \end{array} \right] \\
 \underbrace{\hspace{10em}}_{\mathbf{u}} \\
 \uparrow \\
 \text{independent} \\
 \text{source} \\
 \text{vector}
 \end{array}
 \end{array}
 \end{array}$$

$$\boxed{\mathbf{H}_v \mathbf{v} + \mathbf{H}_i \mathbf{i} = \mathbf{u}}$$

$$\underbrace{\begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & C_2 \frac{d}{dt} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}}_{\mathbf{H}_v} \quad \underbrace{\begin{bmatrix} L_1 \frac{d}{dt} & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}}_{\mathbf{H}_i} \quad \underbrace{\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ \dots \\ i_1 \\ i_2 \\ i_3 \\ i_4 \end{bmatrix}}_{\substack{\mathbf{v} \\ \mathbf{i}}} = \underbrace{\begin{bmatrix} 0 \\ 0 \\ 6 \sin \omega t \\ 2 \cos \omega t \end{bmatrix}}_{\mathbf{u}}$$

\uparrow
 independent source vector



$$\boxed{\mathbf{H}_v \mathbf{v} + \mathbf{H}_i \mathbf{i} = \mathbf{u}}$$