

CS 188: Artificial Intelligence

Fall 2007

Lecture 18: Bayes Nets III
10/30/2007

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Announcements

- Project shift:
 - Project 4 moved back a little
 - Instead, mega-mini-homework, worth 3x, graded
- Contest is live

Inference

- Inference: calculating some statistic from a joint probability distribution

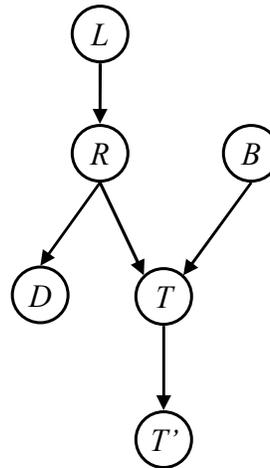
- Examples:

- Posterior probability:

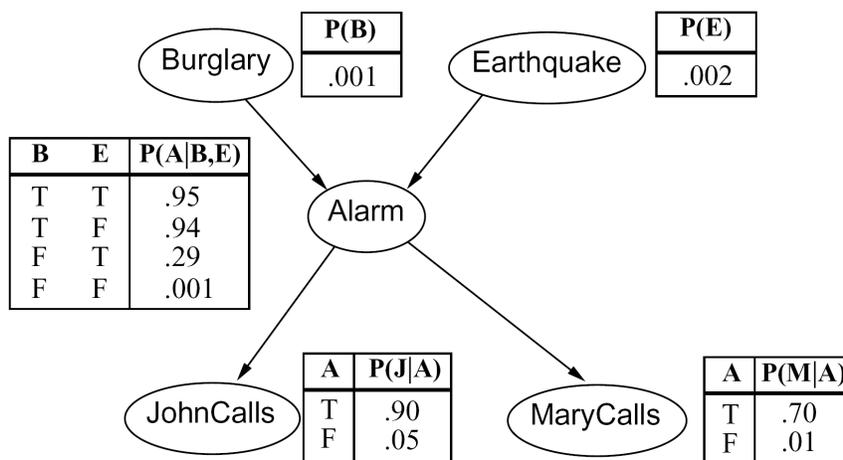
$$P(Q|E_1 = e_1, \dots, E_k = e_k)$$

- Most likely explanation:

$$\operatorname{argmax}_q P(Q = q|E_1 = e_1 \dots)$$



Reminder: Alarm Network



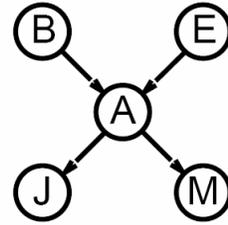
Normalization Trick

$$P(B|j, m) = \frac{P(B, j, m)}{P(j, m)}$$

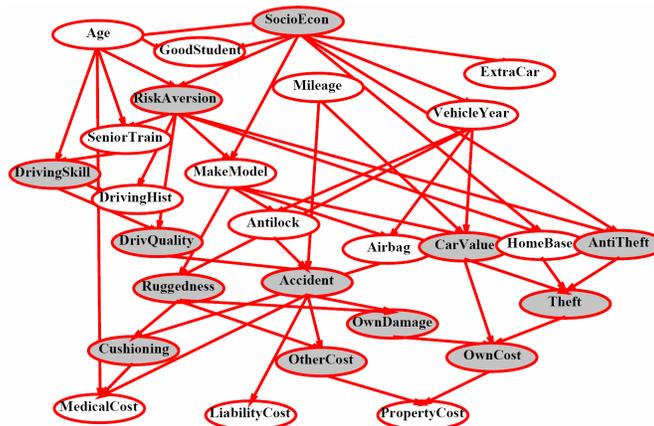
$$P(b, j, m) = \sum_{e, a} P(b, e, a, j, m)$$

$$P(\bar{b}, j, m) = \sum_{e, a} P(\bar{b}, e, a, j, m)$$

$$\begin{pmatrix} P(b, j, m) \\ P(\bar{b}, j, m) \end{pmatrix} \xrightarrow{\text{Normalize}} \begin{pmatrix} P(b|j, m) \\ P(\bar{b}|j, m) \end{pmatrix}$$

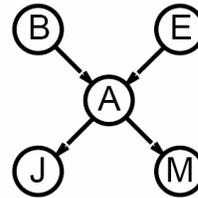


Inference by Enumeration?



Nesting Sums

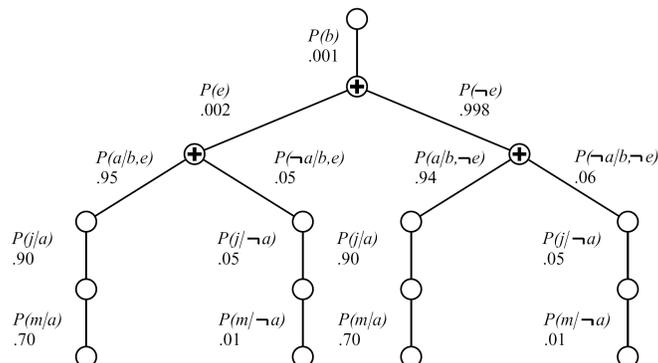
- Atomic inference is extremely slow!
- Slightly clever way to save work:
 - Move the sums as far right as possible
 - Example:



$$\begin{aligned}
 P(b, j, m) &= \sum_{e, a} P(b, e, a, j, m) \\
 &= \sum_{e, a} P(b)P(e)P(a|b, e)P(j|a)P(m|a) \\
 &= P(b) \sum_e P(e) \sum_a P(a|b, e)P(j|a)P(m|a)
 \end{aligned}$$

Evaluation Tree

- View the nested sums as a computation tree:

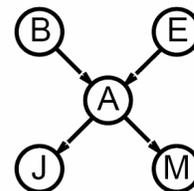


- Still repeated work: calculate $P(m | a)$ $P(j | a)$ twice, etc.

Variable Elimination: Idea

- Lots of redundant work in the computation tree
- We can save time if we cache all partial results
 - Join on one hidden variable at a time
 - Project out that variable immediately
- This is the basic idea behind variable elimination

Basic Objects



- Track objects called **factors**
- Initial factors are local CPTs

$$\begin{array}{ccc}
 \underbrace{P(B)} & \underbrace{P(J|A)} & \underbrace{P(A|B, E)} \\
 f_B(B) & f_J(A, J) & f_A(A, B, E)
 \end{array}$$

- During elimination, create new factors
- Anatomy of a factor:

4 numbers, one for each value of D and E

$$f_{A\bar{B}\bar{C}D}(D, E)$$

Variables introduced

Variables summed out

Argument variables, always non-evidence variables

Basic Operations

- First basic operation: **join factors**
- Combining two factors:
 - **Just like a database join**
 - Build a factor over the union of the domains
- Example:

$$f_1(A, B) \times f_2(B, C) \longrightarrow f_3(A, B, C)$$

$$f_3(a, b, c) = f_1(a, b) \cdot f_2(b, c)$$

$$"P(a, b|c) = P(a|b) \cdot P(b|c)"$$

Basic Operations

- Second basic operation: **marginalization**
- Take a factor and sum out a variable
 - Shrinks a factor to a smaller one
 - A **projection** operation
- Example:

$$f_{\bar{A}B}(b) = \sum_a f_{AB}(a, b)$$

$$"P(b) = \sum_a P(a, b)"$$

Example

$$\begin{aligned}P(b, j, m) &= \underbrace{P(b)}_B \sum_e \underbrace{P(e)}_E \sum_a \underbrace{P(a|b, e)}_A \underbrace{P(j|a)}_J \underbrace{P(m|a)}_M \\&= f_B(b) \sum_e f_E(e) \sum_a f_A(a, b, e) f_J(a) f_M(a) \\&= f_B(b) \sum_e f_E(e) \sum_a f_{AJM}(a, b, e) \\&= f_B(b) \sum_e f_E(e) f_{\bar{A}JM}(b, e)\end{aligned}$$

Example

$$\begin{aligned}P(b, j, m) &= f_B(b) \sum_e f_E(e) f_{\bar{A}JM}(b, e) \\&= f_B(b) \sum_e f_{\bar{A}EJM}(b, e) \\&= f_B(b) f_{\bar{A}\bar{E}JM}(b) \\&= f_{\bar{A}\bar{B}\bar{E}JM}(b)\end{aligned}$$

General Variable Elimination

- Query: $P(Q|E_1 = e_1, \dots, E_k = e_k)$
- Start with initial factors:
 - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
 - Pick a hidden variable H
 - Join all factors mentioning H
 - Project out H
- Join all remaining factors and normalize

Example

$$P(B|j, m) \propto P(B, j, m)$$

$P(B)$	$P(E)$	$P(A B, E)$	$P(j A)$	$P(m A)$
$f_B(B)$	$f_E(E)$	$f_A(A, B, E)$	$f_J(A)$	$f_M(A)$

Choose A

$$\begin{array}{c}
 f_A(A, B, E) \\
 f_J(A) \\
 f_M(A)
 \end{array}
 \xrightarrow{\times}
 f_{AJM}(A, B, E)
 \xrightarrow{\Sigma}
 f_{\bar{A}JM}(B, E)$$

$f_B(B)$	$f_E(E)$	$f_{\bar{A}JM}(B, E)$
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Example

$$f_B(B) \quad f_E(E) \quad f_{\bar{A}JM}(B, E)$$

Choose E

$$f_E(E) \cdot f_{\bar{A}JM}(B, E) \xrightarrow{\times} f_{\bar{A}EJM}(B, E) \xrightarrow{\Sigma} f_{\bar{A}\bar{E}JM}(B)$$

$$f_B(B) \quad f_{\bar{A}\bar{E}JM}(B)$$

Finish

$$f_B(B) \cdot f_{\bar{A}\bar{E}JM}(B) \xrightarrow{\times} f_{\bar{A}B\bar{E}JM}(B) \xrightarrow{\text{Normalize}} P(B|j, m)$$

Variable Elimination

- **What you need to know:**
 - VE caches intermediate computations
 - Polynomial time for tree-structured graphs!
 - Saves time by marginalizing variables as soon as possible rather than at the end
- **We will see special cases of VE later**
 - You'll have to implement the special cases
- **Approximations**
 - Exact inference is slow, especially when you have a lot of hidden nodes
 - Approximate methods give you a (close) answer, faster

Sampling

- Basic idea:

- Draw N samples from a sampling distribution S
- Compute an approximate posterior probability
- Show this converges to the true probability P

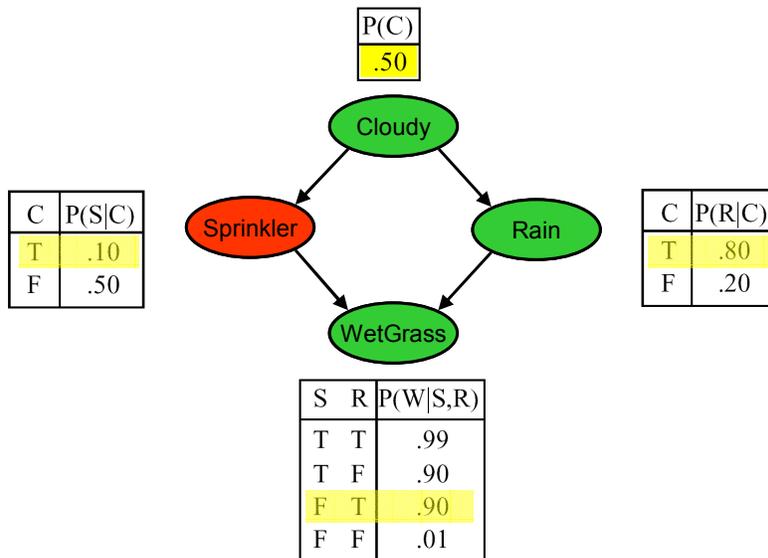
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- Outline:

- Sampling from an empty network
- Rejection sampling: reject samples disagreeing with evidence
- Likelihood weighting: use evidence to weight samples

Prior Sampling



Prior Sampling

- This process generates samples with probability

$$S_{PS}(x_1 \dots x_n) = \prod_{i=1}^n P(x_i | \text{Parents}(X_i)) = P(x_1 \dots x_n)$$

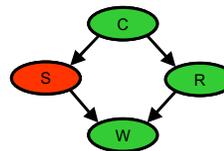
...i.e. the BN's joint probability

- Let the number of samples of an event be $N_{PS}(x_1 \dots x_n)$
- Then $\lim_{N \rightarrow \infty} \hat{P}(x_1, \dots, x_n) = \lim_{N \rightarrow \infty} N_{PS}(x_1, \dots, x_n)/N$
 $= S_{PS}(x_1, \dots, x_n)$
 $= P(x_1 \dots x_n)$
- I.e., the sampling procedure is **consistent**

Example

- We'll get a bunch of samples from the BN:

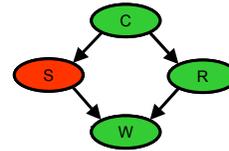
C, ¬S, r, W
 C, S, r, W
 ¬C, S, r, ¬W
 C, ¬S, r, W
 ¬C, S, ¬r, W



- If we want to know $P(W)$
 - We have counts $\langle w:4, \neg w:1 \rangle$
 - Normalize to get $P(W) = \langle w:0.8, \neg w:0.2 \rangle$
 - This will get closer to the true distribution with more samples
 - Can estimate anything else, too
 - What about $P(C | \neg r)$? $P(C | \neg r, \neg w)$?

Rejection Sampling

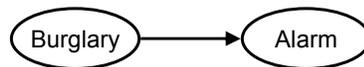
- Let's say we want $P(C)$
 - No point keeping all samples around
 - Just tally counts of C outcomes
- Let's say we want $P(C|s)$
 - Same thing: tally C outcomes, but ignore (reject) samples which don't have $S=s$
 - This is rejection sampling
 - It is also consistent (correct in the limit)



$C, \neg S, r, W$
 C, S, r, W
 $\neg C, S, r, \neg W$
 $C, \neg S, r, W$
 $\neg C, S, \neg r, W$

Likelihood Weighting

- Problem with rejection sampling:
 - If evidence is unlikely, you reject a lot of samples
 - You don't exploit your evidence as you sample
 - Consider $P(B|a)$

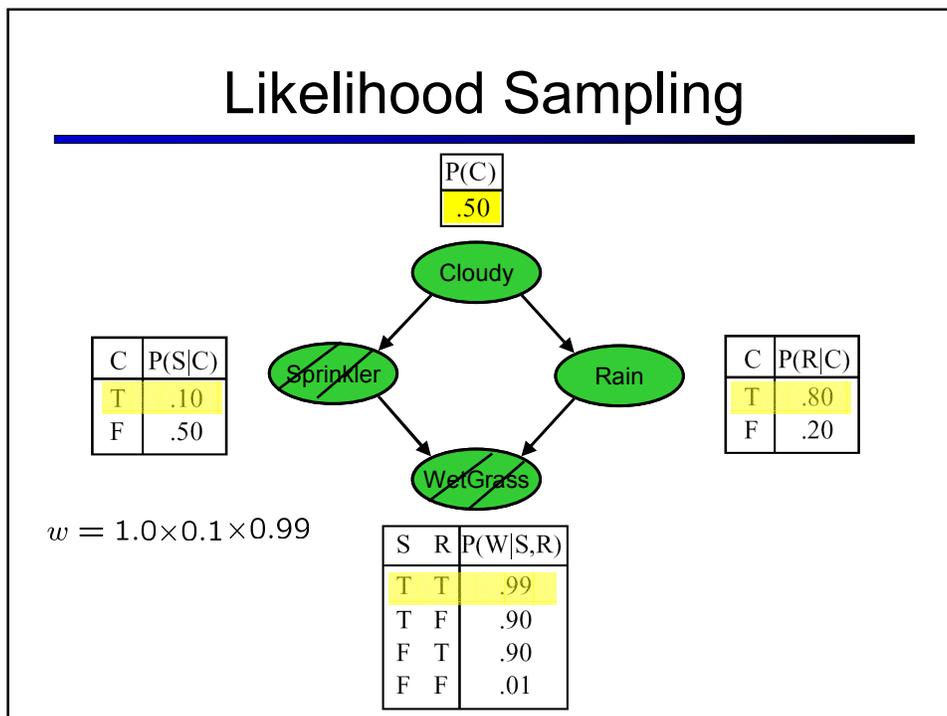


- Idea: fix evidence variables and sample the rest



- Problem: sample distribution not consistent!
- Solution: weight by probability of evidence given parents

Likelihood Sampling



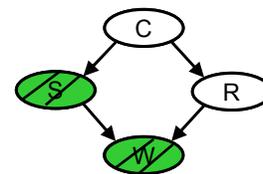
Likelihood Weighting

- Sampling distribution if z sampled and e fixed evidence

$$S_{WS}(z, e) = \prod_{i=1}^l P(z_i | \text{Parents}(Z_i))$$

- Now, samples have weights

$$w(z, e) = \prod_{i=1}^m P(e_i | \text{Parents}(E_i))$$



- Together, weighted sampling distribution is consistent

$$\begin{aligned}
 S_{WS}(z, e)w(z, e) &= \prod_{i=1}^l P(z_i | \text{Parents}(Z_i)) \prod_{i=1}^m P(e_i | \text{Parents}(E_i)) \\
 &= P(z, e)
 \end{aligned}$$

Likelihood Weighting

- Note that likelihood weighting doesn't solve all our problems
- Rare evidence is taken into account for downstream variables, but not upstream ones
- A better solution is Markov-chain Monte Carlo (MCMC), more advanced
- We'll return to sampling for robot localization and tracking in dynamic BNs

