

CS-184: Computer Graphics

Lecture #20: Motion Capture

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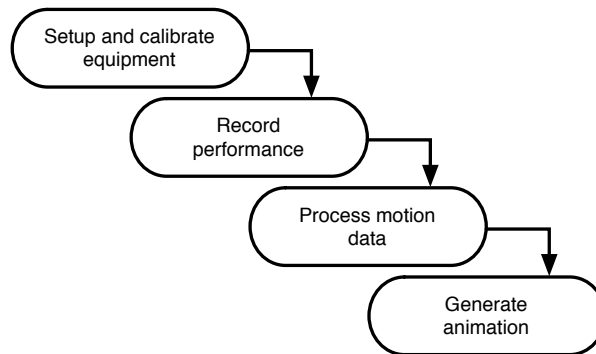
Today

- Motion Capture

Motion Capture

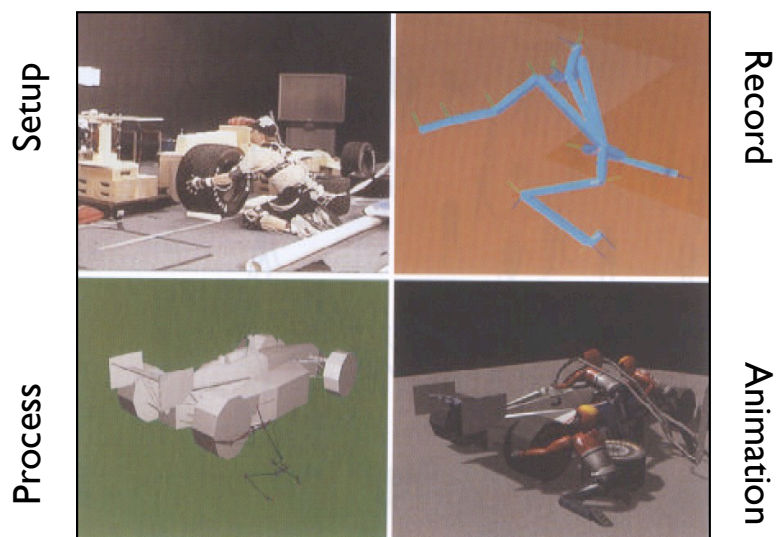
- Record motion from physical objects
- Use motion to animate virtual objects

Simplified Pipeline:



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Basic Pipeline



From Rose, et al., 1998

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What types of objects?

- Human, whole body
- Portions of body
- Facial animation
- Animals
- Puppets
- Other objects

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Capture Equipment

- Passive Optical
 - Reflective markers
 - IR (typically) illumination
 - Special cameras
 - Fast, high res., filters
 - Triangulate for positions



Images from Motion Analysis



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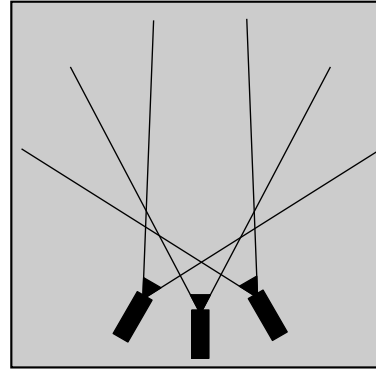
Capture Equipment

- **Passive Optical Advantages**

- Accurate
- May use many markers
- No cables
- High frequency

- **Disadvantages**

- Requires lots of processing
- Expensive systems
- Occlusions
- Marker swap
- Lighting / camera limitations



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Capture Equipment

- **Active Optical**

- Similar to passive but uses LEDs
- Blink IDs, no marker swap
- Number of markers trades off w/ frame rate



Phoenix Technology

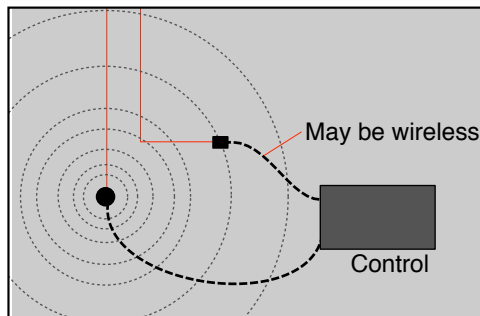


Phase Space

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Capture Equipment

- Magnetic Trackers
 - Transmitter emits field
 - Trackers sense field
 - Trackers report position and orientation



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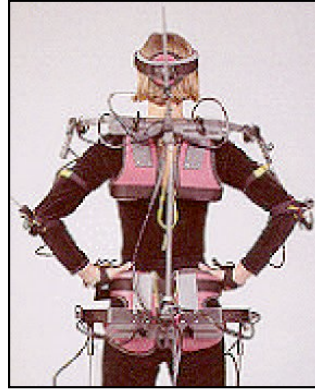
Capture Equipment

- Electromagnetic Advantages
 - 6 DOF data
 - No occlusions
 - Less post processing
 - Cheaper than optical
- Disadvantages
 - Cables
 - Problems with metal objects
 - Low(er) frequency
 - Limited range
 - Limited number of trackers

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Capture Equipment

- Electromechanical

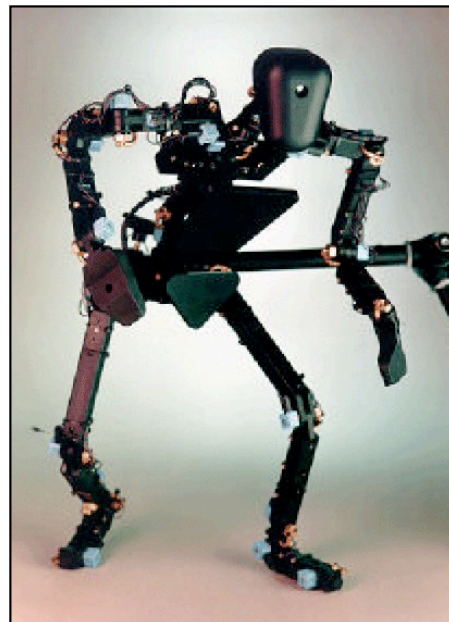


Analogus

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Capture Equipment

- Puppets



Digital Image Design

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Performance Capture

- Many studios regard *Motion Capture* as evil
 - Synonymous with low quality motion
 - No directive / creative control
 - Cheap
- *Performance Capture* is different
 - Use mocap device as an expressive input device
 - Similar to digital music and MIDI keyboards

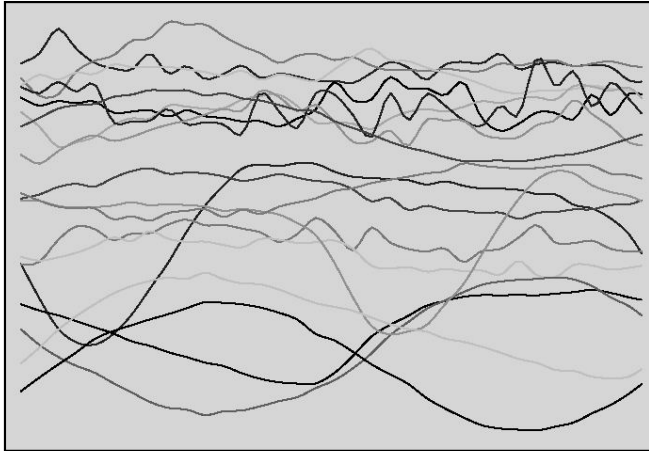
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Manipulating Motion Data

- Basic tasks
 - Adjusting
 - Blending
 - Transitioning
 - Retargeting
- Building graphs

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Nature of Motion Data



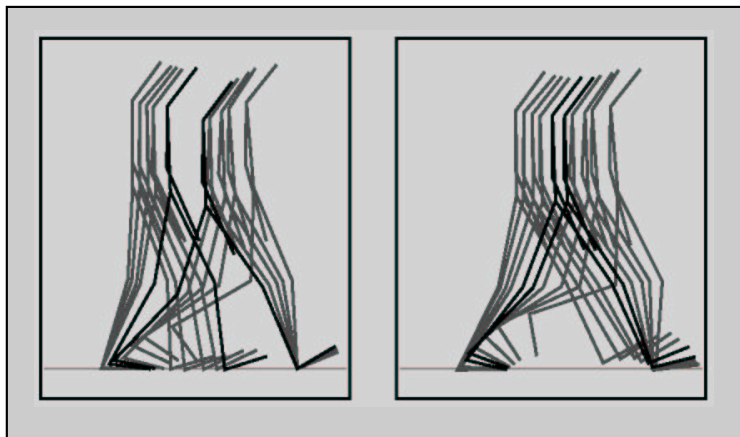
Witkin and Popovic, 1995

Subset of motion curves from
captured walking motion.

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Adjusting

- IK on single frames will not work



Gleicher, SIGGRAPH 98

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Adjusting

- Define desired motion function in parts

The diagram shows the equation $m(t) = m_0(t) + d(t)$ inside a light gray box. Three arrows point from text labels to the terms in the equation: an arrow from 'Result after adjustment' points to $m(t)$, an arrow from 'Initial sampled data' points to $m_0(t)$, and an arrow from 'Adjustment' points to $d(t)$.

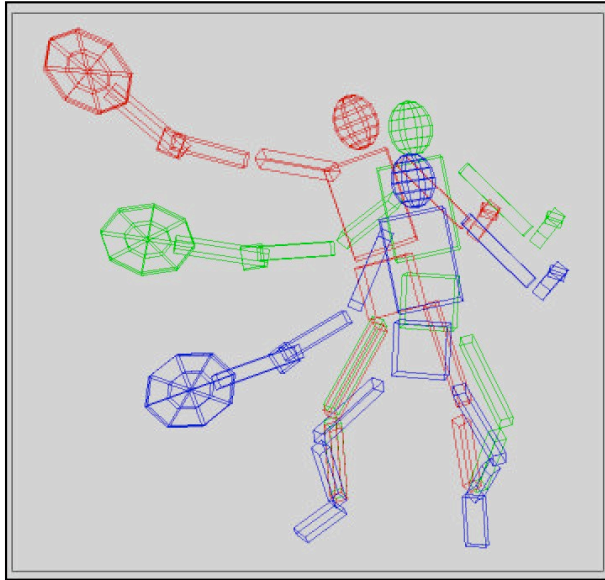
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Adjusting

- Select adjustment function from “some nice space”
 - Example C2 B-splines
- Spread modification over reasonable period of time
 - User selects support radius

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Adjusting



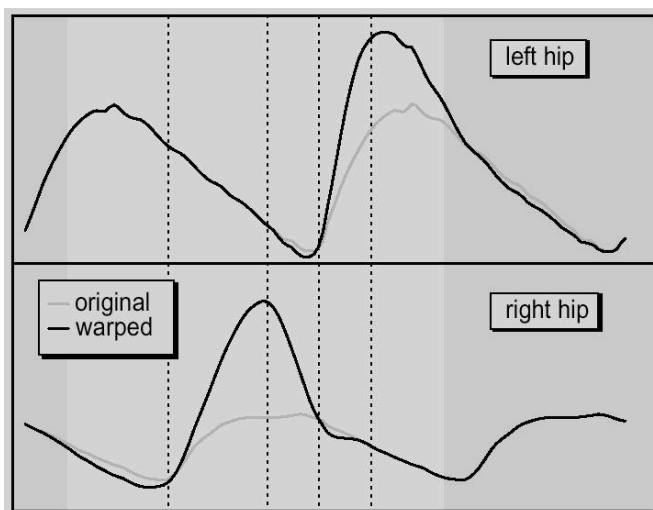
IK uses control points of the B-spline now

Example:
position racket
fix right foot
fix left toes
balance

Witkin and Popovic SIGGRAPH 95

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Adjusting



Witkin and Popovic SIGGRAPH 95

What if adjustment periods overlap?

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Blending

- Given two motions make a motion that combines qualities of both

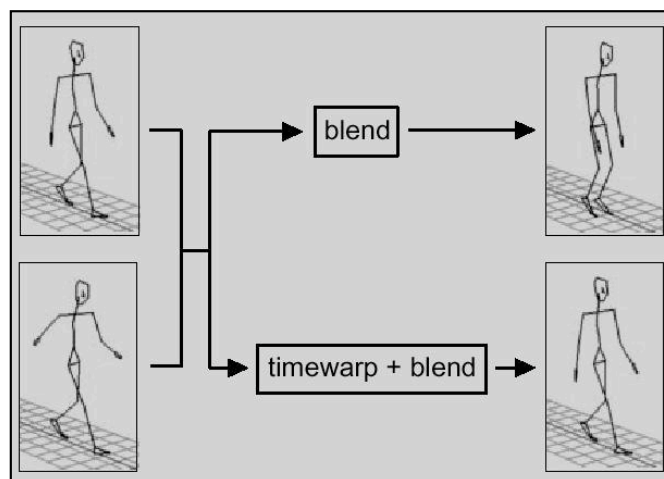
$$\mathbf{m}_\alpha(t) = \alpha \mathbf{m}_a(t) + (1 - \alpha) \mathbf{m}_b(t)$$

- Assume same DOFs
- Assume same parameter mappings

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Blending

- Consider blending *slow-walk* and *fast-walk*

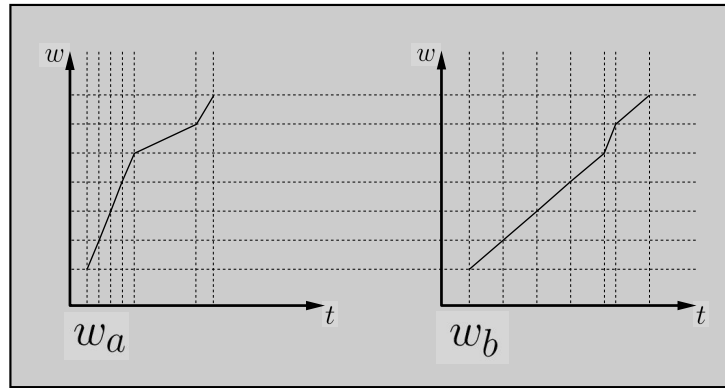


Bruderlin and Williams, SIGGRAPH 95

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Blending

- Define timewarp functions to align features in motion



Normalized time is w

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Blending

- Blend in normalized time

$$\mathbf{m}_\alpha(w) = \alpha \mathbf{m}_a(w_a) + (1 - \alpha) \mathbf{m}_b(w_b)$$

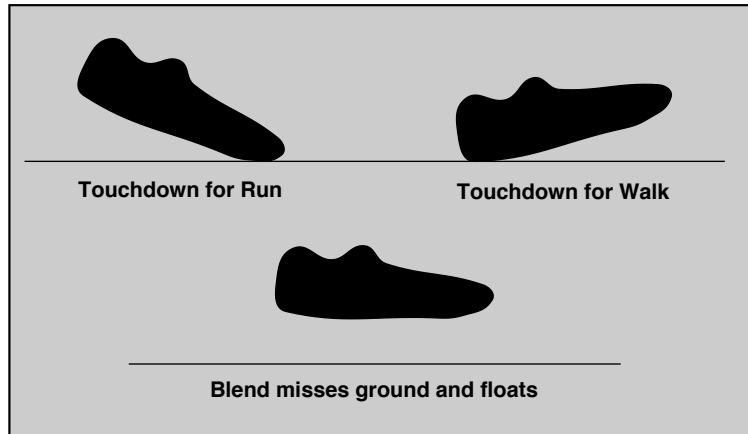
- Blend playback rate

$$\frac{dt}{dw} = \alpha \frac{dt}{dw_a} + (1 - \alpha) \alpha \frac{dt}{dw_b}$$

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Blending

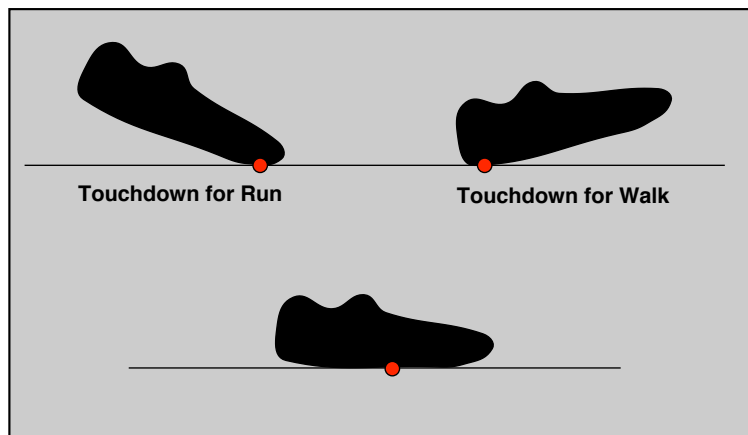
- Blending may still break features in original motions



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Blending

- Add explicit constraints to key points
 - Enforce with IK over time



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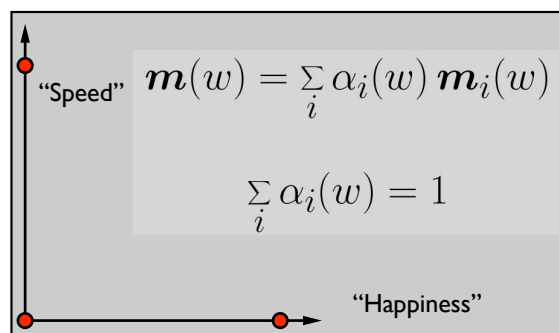
Blending / Adjustment

- Short edits will tend to look acceptable
- Longer ones will often exhibit problems
- Optimize to improve blends / adjustments
 - Add quality metric on adjustment
 - Minimize accelerations / torques
 - Explicit smoothness constraints
 - Other criteria...

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Multivariate Blending

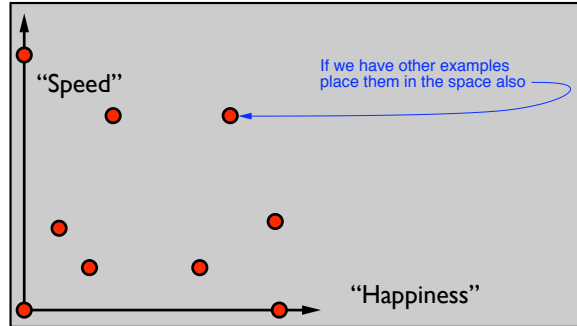
- Extend blending to multivariate interpolation



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Multivariate Blending

- Extend blending to multivariate interpolation

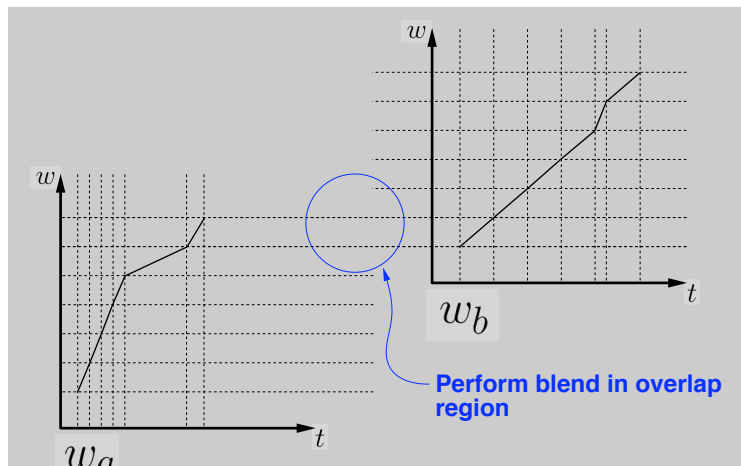


Use standard scattered-data interpolation methods

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Transitions

- Transition from one motion to another



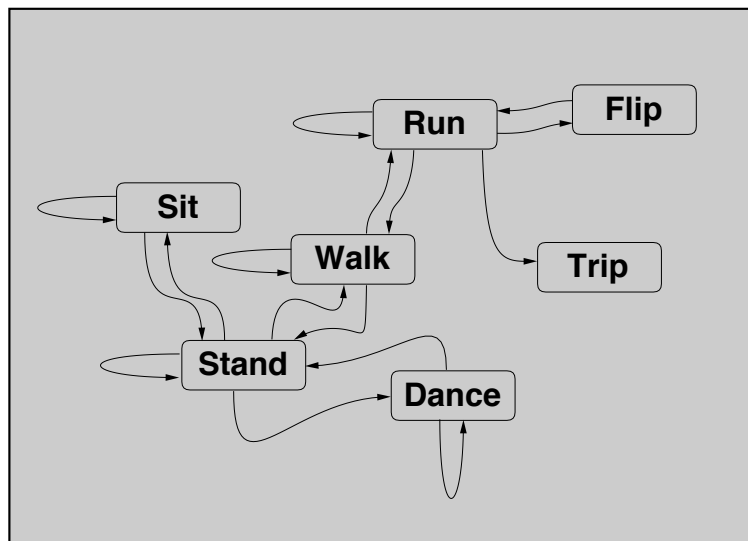
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Cyclification

- Special case of transitioning
- Both motions are the same
- Need to modify beginning and end of a motion simultaneously

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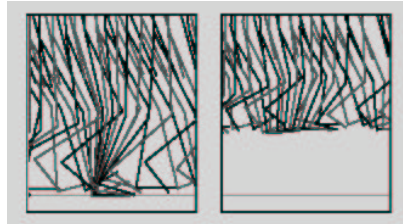
Transition Graphs



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Retargeting

- Adapt motion from one character to another



From Gleicher, SIGGRAPH 1998

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Suggested Reading

- *Fourier principles for emotion-based human figure animation*, Unuma, Anjyo, and Takeuchi, SIGGRAPH 95
- *Motion signal processing*, Bruderlin and Williams, SIGGRAPH 95
- *Motion warping*, Witkin and Popovic, SIGGRAPH 95
- *Efficient generation of motion transitions using spacetime constraints*, Rose et al., SIGGRAPH 96
- *Retargeting motion to new characters*, Gleicher, SIGGRAPH 98
- *Verbs and adverbs: Multidimensional motion interpolation*, Rose, Cohen, and Bodenheimer, IEEE: Computer Graphics and Applications, v. 18, no. 5, 1998

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