

CS162 Operating Systems and Systems Programming Lecture 4

Synchronization, Atomic operations, Locks

February 3, 2014
Anthony D. Joseph
<http://inst.eecs.berkeley.edu/~cs162>

Why allow cooperating threads?

- People cooperate; computers help/enhance people's lives, so computers must cooperate
 - By analogy, the non-reproducibility/non-determinism of people is a notable problem for “carefully laid plans”
- Advantage 1: Share resources
 - One computer, many users
 - One bank balance, many ATMs
 - » What if ATMs were only updated at night?
 - Embedded systems (robot control: coordinate arm & hand)
- Advantage 2: Speedup
 - Overlap I/O and computation
 - Multiprocessors – chop up program into parallel pieces
- Advantage 3: Modularity
 - Chop large problem up into simpler pieces
 - » To compile, for instance, gcc calls `cpp` | `cc1` | `cc2` | `as` | `ld`
 - » Makes system easier to extend

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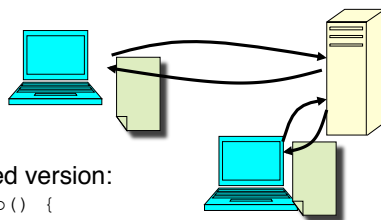
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Threaded Web Server



- Multithreaded version:


```
serverLoop() {
    connection = AcceptCon();
    ThreadCreate (ServiceWebPage (), connection);
}
```
- Advantages of threaded version:
 - Can share file caches kept in memory, results of CGI scripts, other things
 - Threads are *much* cheaper to create than processes, so this has a lower per-request overhead
- What if too many requests come in at once?

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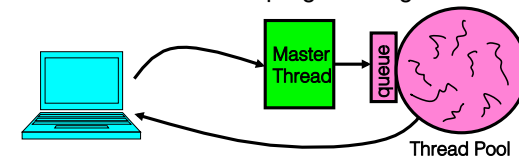
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Thread Pools

- Problem with previous version: Unbounded Threads
 - When web-site becomes too popular – throughput sinks
- Instead, allocate a bounded “pool” of threads, representing the maximum level of multiprogramming



```
master() {
    allocThreads (slave, queue);
    while (TRUE) {
        con=AcceptCon();
        Enqueue (queue, con);
        wakeUp (queue);
    }
}

slave (queue) {
    while (TRUE) {
        con=Dequeue (queue);
        if (con==null)
            sleepOn (queue);
        else
            ServiceWebPage (con);
    }
}
```

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ATM Bank Server

Fun Fact: Over 95% of ATMs run WinXP

- ATM server problem:
 - Service a set of requests
 - Do so without corrupting database
 - Don't hand out too much money

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ATM bank server example

- Suppose we wanted to implement a server process to handle requests from an ATM network:

```

BankServer() {
    while (TRUE) {
        ReceiveRequest(&op, &acctId, &amount);
        ProcessRequest(op, acctId, amount);
    }
}

ProcessRequest(op, acctId, amount) {
    if (op == deposit) Deposit(acctId, amount);
    else if ...
}

Deposit(acctId, amount) {
    acct = GetAccount(acctId); /* may use disk I/O */
    acct->balance += amount;
    StoreAccount(acct); /* Involves disk I/O */
}
  
```

- How could we speed this up?
 - More than one request being processed at once
 - Multiple threads (multi-proc, or overlap comp and I/O)

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Can Threads Help?

- One thread per request!
- Requests proceed to completion, blocking as required:

```

Deposit(acctId, amount) {
    acct = GetAccount(acctId); /* May use disk I/O */
    acct->balance += amount;
    StoreAccount(acct); /* Involves disk I/O */
}
  
```

- Unfortunately, shared state can get corrupted:

Thread 1	Thread 2
load r1, acct->balance	load r1, acct->balance
	add r1, amount2
	store r1, acct->balance
add r1, amount1	
store r1, acct->balance	

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Problem is at the lowest level

- Most of the time, threads are working on separate data, so scheduling doesn't matter:

Thread A	Thread B
x = 1;	y = 2;

- However, What about (Initially, y = 12):

Thread A	Thread B
x = 1;	y = 2;
x = y+1;	y = y*2;

– What are the possible values of x?

Thread A	Thread B
x = 1;	
x = y+1;	
	y = 2;
	y = y*2

x=13

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Problem is at the lowest level

- Most of the time, threads are working on separate data, so scheduling doesn't matter:

Thread A
x = 1;

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Thread A
x = 1;
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Thread B
y = 2;
y = y*2;

- What are the possible values of x?

Thread A
x = 1;
x = y+1;

Thread B
y = 2;
y = y*2;

x=5

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Problem is at the lowest level

- Most of the time, threads are working on separate data, so scheduling doesn't matter:

Thread A
x = 1;

Thread B
y = 2;

- However, What about (Initially, y = 12):

Thread A
x = 1;
x = y+1;

Thread B
y = 2;
y = y*2;

- What are the possible values of x?

Thread A
x = 1;
x = y+1;

Thread B
y = 2;
y = y*2;

x=3

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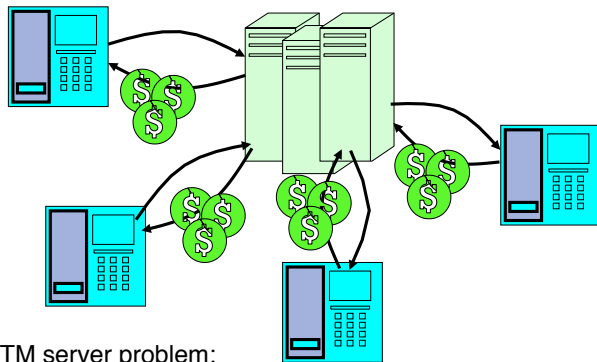
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Recap: ATM Bank Server



- ATM server problem:
 - Service a set of requests
 - Do so without corrupting database
 - Don't hand out too much money

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Recap: Challenge of Threads

- Speed up server by using multiple threads (one per request)
 - Can use multi-processor, or overlap comp and I/O
- Requests proceed to completion, blocking as required:

```
Deposit(acctId, amount) {
    acct = GetAccount(actId); /* May use disk I/O */
    acct->balance += amount;
    StoreAccount(acct);      /* Involves disk I/O */
}
```

- Unfortunately, shared state can get corrupted:

<u>Thread 1</u>	<u>Thread 2</u>
load r1, acct->balance	load r1, acct->balance
	add r1, amount2
	store r1, acct->balance
add r1, amount1	
store r1, acct->balance	

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Recap: Problem is at the lowest level

- Most of the time, threads are working on separate data, so scheduling doesn't matter:

Thread A
x = 1;
Thread B
y = 2;

- However, What about (Initially, y = 12):

Thread A
x = 1;
x = y+1;
Thread B
y = 2;
y = y*2;

- What are the possible values of x?



x=13

Preemption can occur at any time!

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Recap: Problem is at the lowest level

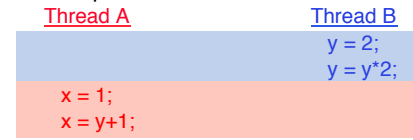
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- However, What about (Initially, y = 12):

Thread A
x = 1;
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Thread B
y = 2;
y = y*2;

- What are the possible values of x?



x=5

Preemption can occur at any time!

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Recap: Problem is at the lowest level

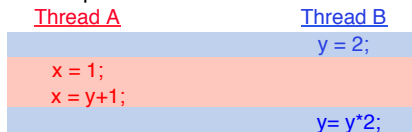
- Most of the time, threads are working on separate data, so scheduling doesn't matter:

Thread A
x = 1;
Thread B
y = 2;

- However, What about (Initially, y = 12):

Thread A
x = 1;
x = y+1;
Thread B
y = 2;
y = y*2;

- What are the possible values of x?



x=3

Preemption can occur at any time!

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Goals for Today

- Concurrency examples and sharing
- Synchronization
- Hardware Support for Synchronization

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Correctness Requirements

- Threaded programs must work for all interleavings of thread instruction sequences
 - Cooperating threads inherently non-deterministic and non-reproducible
 - Really hard to debug unless carefully designed!
- Example: Therac-25
 - Machine for radiation therapy
 - Software control of electron accelerator and electron beam/X-ray production
 - Software control of dosage
 - Software errors caused overdoses and the death of several patients
 - A series of race conditions on shared variables and poor software design
 - "They determined that data entry speed during editing was the key factor in producing the error condition: If the prescription data was edited at a fast pace, the overdose occurred."

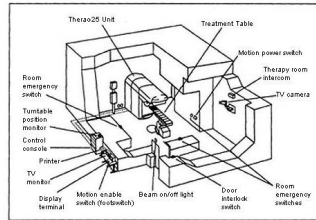


Figure 1. Typical Therac-25 facility

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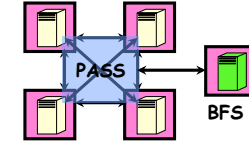
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Space Shuttle Example

- Original Space Shuttle launch aborted 20 minutes before scheduled launch
- Shuttle has five computers:
 - Four run the "Primary Avionics Software System" (PASS)
 - Asynchronous and real-time
 - Runs all of the control systems
 - Results synchronized and compared 440 times per second
 - The Fifth computer is the "Backup Flight System" (BFS)
 - Stays synchronized in case it is needed
 - Written by completely different team than PASS
- Countdown aborted because BFS disagreed with PASS
 - A 1/67 chance that PASS was out of sync one cycle
 - Bug due to modifications in **initialization** code of PASS
 - A delayed init request placed into timer queue
 - As a result, timer queue not empty at expected time to force use of hardware clock
 - Bug not found during extensive simulation



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Atomic Operations

- To understand a concurrent program, we need to know what the underlying atomic operations are!
- Atomic Operation**: an operation that always runs to completion or not at all
 - It is *indivisible*: it cannot be stopped in the middle and state cannot be modified by someone else in the middle
 - Fundamental building block – if no atomic operations, then have no way for threads to work together
- On most machines, memory references and assignments (i.e. loads and stores) of words are atomic
- Many instructions are not atomic
 - Double-precision floating point store often not atomic
 - VAX and IBM 360 had an instruction to copy a whole array

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Concurrency Challenges

- Multiple computations (threads) executing in parallel to
 - share resources, and/or
 - share data
- Fine grain sharing:
 - ↑ increase concurrency → better performance
 - ↓ more complex
- Coarse grain sharing:
 - ↑ Simpler to implement
 - ↓ Lower performance
- Examples:
 - Sharing CPU for 10ms vs. 1min
 - Sharing a database at the row vs. table granularity

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Motivation: “Too much milk”

- Great thing about OS’s – analogy between problems in OS and problems in real life
 - Help you understand real life problems better
 - But, computers are much stupider than people
- Example: People need to coordinate:



Time	Person A	Person B
3:00	Look in Fridge. Out of milk	
3:05	Leave for store	
3:10	Arrive at store	Look in Fridge. Out of milk
3:15	Buy milk	Leave for store
3:20	Arrive home, put milk away	Arrive at store
3:25		Buy milk
3:30		Arrive home, put milk away

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Definitions

- **Synchronization**: using atomic operations to ensure cooperation between threads
 - For now, only loads and stores are atomic
 - We’ll show that is hard to build anything useful with only reads and writes
- **Critical Section**: piece of code that only one thread can execute at once
- **Mutual Exclusion**: ensuring that only one thread executes critical section
 - One thread *excludes* the other while doing its task
 - Critical section and mutual exclusion are two ways of describing the same thing

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More Definitions

- **Lock**: prevents someone from doing something
 - Lock before entering critical section and before accessing shared data
 - Unlock when leaving, after accessing shared data
 - Wait if locked
 - » Important idea: all synchronization involves waiting
- Example: fix the milk problem by putting a lock on refrigerator
 - Lock it and take key if you are going to go buy milk
 - Fixes too much (coarse granularity): roommate angry if only wants orange juice



– Of Course – We don’t know how to make a lock yet

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Too Much Milk: Correctness Properties

- Need to be careful about correctness of concurrent programs, since non-deterministic
 - Always write down **desired** behavior first
 - Impulse is to start coding first, then when it doesn’t work, pull hair out
 - Instead, think first, then code
- What are the correctness properties for the “Too much milk” problem?
 - Never more than one person buys
 - Someone buys if needed
- Restrict ourselves to use only atomic load and store operations as building blocks

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Too Much Milk: Solution #1

- Use a note to avoid buying too much milk:
 - Leave a note before buying (kind of “lock”)
 - Remove note after buying (kind of “unlock”)
 - Don’t buy if note (wait)
- Suppose a computer tries this (remember, only memory read/write are atomic):

```
if (noMilk) {
    if (noNote) {
        leave Note;
        buy milk;
        remove note;
    }
}
```



- Result?

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Too Much Milk: Solution #1

- Still too much milk **but only occasionally!**

<u>Thread A</u>	<u>Thread B</u>
if (noMilk)	
if (noNote) {	
	if (noMilk)
	if (noNote) {
leave Note;	
buy milk;	
remove note;	
}	
	leave Note;
	buy milk;
	...

- Thread can get context switched after checking milk and note but before leaving note!
- Solution makes problem worse since fails **intermittently**
 - Makes it really hard to debug...
 - Must work despite what the thread dispatcher does!

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Too Much Milk: Solution #1½

- Clearly the Note is not quite blocking enough
 - Let’s try to fix this by placing note first
- Another try at previous solution:

```
leave Note;
if (noMilk) {
    if (noNote) {
        buy milk;
    }
}
```



- What happens here?
 - Well, with human, probably nothing bad
 - With computer: no one ever buys milk

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Too Much Milk Solution #2

- How about labeled notes?
 - Now we can leave note before checking
- Algorithm looks like this:

<u>Thread A</u>	<u>Thread B</u>
leave note A;	leave note B;
if (noNote B) {	if (noNote A) {
if (noMilk) {	if (noMilk) {
buy Milk;	buy Milk;
}	}
remove note A;	remove note B;

- Does this work?

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Too Much Milk Solution #2

- Possible for neither thread to buy milk!

Thread A

leave note A;

Thread B

```
leave note B;
if (noNote A) {
  if (noMilk) {
    buy Milk;
  }
}
```

```
if (noNote B) {
  if (noMilk) {
    buy Milk;
    ...
  }
}
```

remove note B;

- Really insidious:
 - **Unlikely** that this would happen, but will at worse possible time

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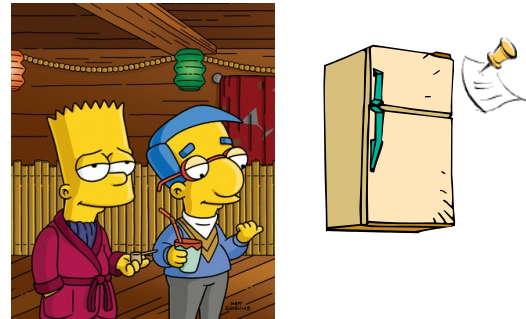
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Too Much Milk Solution #2: problem!



- *I'm not getting milk, You're getting milk*
- This kind of lockup is called "starvation!"

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Administrivia

- Section assignments posted on Piazza
 - Most groups were assigned 1st or 2nd preference
 - Attend assigned sections THIS week
- Nachos Project I begins tomorrow (Threads)
 - Start reading walkthrough and code NOW
 - Download Nachos tar file
 - Set up Java environment, Eclipse, version control
 - More details in sections
- Sections will have weekly quizzes
 - New grade breakdown: 50% projects, 40% exams, 5% participation (lectures/sections/Piazza), 5% quizzes
 - May have quizzes in lectures

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5min Break

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Too Much Milk Solution #3

- Here is a possible two-note solution:

<u>Thread A</u>	<u>Thread B</u>
leave note A;	leave note B;
while (note B) {\X	if (noNote A) {\Y
do nothing;	if (noMilk) {
}	buy milk;
if (noMilk) {	}
buy milk;	remove note B;
}	
remove note A;	

- Does this work? Yes. Both can guarantee that:
 - It is safe to buy, or
 - Other will buy, ok to quit
- At X:
 - if no note B, safe for A to buy,
 - otherwise wait to find out what will happen
- At Y:
 - if no note A, safe for B to buy
 - Otherwise, A is either buying or waiting for B to quit

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Solution #3 discussion

- Our solution protects a single “Critical-Section” piece of code for each thread:

```
if (noMilk) {
    buy milk;
}
```

- Solution #3 works, but it’s really unsatisfactory
 - Really complex – even for this simple an example
 - Hard to convince yourself that this really works
 - A’s code is different from B’s – what if lots of threads?
 - Code would have to be slightly different for each thread
 - While A is waiting, it is consuming CPU time
 - This is called “busy-waiting”
- There’s a better way
 - Have hardware provide better (higher-level) primitives than atomic load and store
 - Build even higher-level programming abstractions on this new hardware support

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High-Level Picture

- The abstraction of threads is good:
 - Maintains sequential execution model
 - Allows simple parallelism to overlap I/O and computation
- Unfortunately, still too complicated to access state shared between threads
 - Consider “too much milk” example
 - Implementing a concurrent program with only loads and stores would be tricky and error-prone
- We’ll implement higher-level operations on top of atomic operations provided by hardware
 - Develop a “synchronization toolbox”
 - Explore some common programming paradigms



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Too Much Milk: Solution #4

- Suppose we have some sort of implementation of a lock (more in a moment)
 - `Lock.Acquire()` – wait until lock is free, then grab
 - `Lock.Release()` – unlock, waking up anyone waiting
 - These must be atomic operations – if two threads are waiting for the lock, only one succeeds to grab the lock

- Then, our milk problem is easy:

```
milklock.Acquire();
if (nomilk)
    buy milk;
milklock.Release();
```

- Once again, section of code between `Acquire()` and `Release()` called a “Critical Section”

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How to Implement Lock?

- **Lock**: prevents someone from accessing something
 - Lock before entering critical section (e.g., before accessing shared data)
 - Unlock when leaving, after accessing shared data
 - Wait if locked
 - » Important idea: all synchronization involves waiting
 - » Should sleep if waiting for long time
- Hardware lock instructions
 - Is this a good idea?
 - What about putting a task to sleep?
 - » How do handle interface between hardware and scheduler?
 - Complexity?
 - » Each feature makes hardware more complex and slower



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Naïve use of Interrupt Enable/Disable

- How can we build multi-instruction atomic operations?
 - Recall: dispatcher gets control in two ways.
 - » Internal: Thread does something to relinquish the CPU
 - » External: Interrupts cause dispatcher to take CPU
 - On a uniprocessor, can avoid context-switching by:
 - » Avoiding internal events (although virtual memory tricky)
 - » Preventing external events by disabling interrupts

- Consequently, naïve Implementation of locks:

```
LockAcquire { disable Ints; }  
LockRelease { enable Ints; }
```

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Naïve use of Interrupt Enable/Disable: Problems

- **Can't let user do this!** Consider following:

```
LockAcquire();  
While(TRUE) {;
```

- Real-Time system—no guarantees on timing!
 - Critical Sections might be arbitrarily long
- What happens with I/O or other important events?
 - “Reactor about to meltdown. Help?”



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Better Implementation of Locks by Disabling Interrupts

- Key idea: maintain a lock variable and impose mutual exclusion only during operations on that variable

```
int value = FREE;
```



```
Acquire() {  
    disable interrupts;  
    if (value == BUSY) {  
        put thread on wait queue;  
        Go to sleep();  
        // Enable interrupts?  
    } else {  
        value = BUSY;  
        enable interrupts;  
    }  
}  
  
Release() {  
    disable interrupts;  
    if (anyone on wait queue) {  
        take thread off wait queue  
        Put at front of ready queue  
    } else {  
        value = FREE;  
    }  
    enable interrupts;  
}
```

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New Lock Implementation: Discussion

- Disable interrupts: avoid interrupting between checking and setting lock value
 - Otherwise two threads could think that they both have lock

```

Acquire() {
    disable interrupts;
    if (value == BUSY) {
        put thread on wait queue;
        Go to sleep();
        // Enable interrupts?
    } else {
        value = BUSY;
    }
    enable interrupts;
}
    
```

} Critical Section

- Note: unlike previous solution, critical section very short
 - User of lock can take as long as they like in their own critical section
 - Critical interrupts taken in time

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Interrupt re-enable in going to sleep

- What about re-enabling ints when going to sleep?

```

Acquire() {
    disable interrupts;
    if (value == BUSY) {
        put thread on wait queue;
        go to sleep();
    } else {
        value = BUSY;
    }
    enable interrupts;
}
    
```

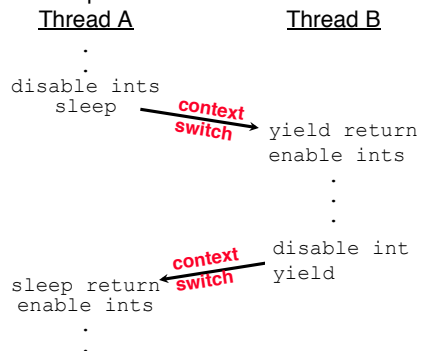
Enable Position
Enable Position
Enable Position

- Before putting thread on the wait queue?
 - Release can check the queue and not wake up thread
- After putting the thread on the wait queue
 - Release puts the thread on the ready queue, but the thread still thinks it needs to go to sleep
 - Misses wakeup and still holds lock (deadlock!)
- Want to put it after sleep(). But, how?

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How to Re-enable After Sleep()?

- Since ints are disabled when you call sleep:
 - Responsibility of the next thread to re-enable ints
 - When the sleeping thread wakes up, returns to acquire and re-enables interrupts



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Summary

- Introduced important concept: Atomic Operations
 - An operation that runs to completion or not at all
 - These are the primitives on which to construct various synchronization primitives
- Showed construction of Locks using interrupts
 - Using careful disabling of interrupts
 - Must be very careful not to waste/tie up machine resources
 - » Shouldn't disable interrupts for long
 - Key ideas: Use a separate lock variable, and use hardware mechanisms to protect modifications of that variable

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