Q1. Memory consistency models

Consider the following two threads executing on two different cores. Initially \(M[A] = 0, M[B] = 0, M[C] = 0\).

\[
\begin{align*}
\text{P1:} & \quad \text{P2:} \\
\text{li} & \quad \text{li} \\
x1, 1 & \quad x1, 2 \\
\text{lw} & \quad \text{sw} \\
x2, A & \quad x1, B \\
\text{sw} & \quad \text{lw} \\
x1, C & \quad x2, C \\
\text{lw} & \quad \text{sw} \\
x3, B & \quad x1, A
\end{align*}
\]

We are interested in the final values of \(P1.x2, P1.x3,\) and \(P2.x2\).

1. Give all possible sets of values of \(P1.x2, P1.x3,\) and \(P2.x2\) under sequential consistency (SC).

2. Give all new possible sets of values if we relax Write → Read ordering and the instruction orderings that caused them.
3. Give all new possible sets of values if we relax Write → Write ordering and the instruction orderings that caused them.

4. Give all new possible sets of values if we relax Read → Read and Read → Write ordering constraints and the instruction orderings that caused them.
**Q2. Synchronization**

We want to write a multithreaded program that uses a producer-consumer model. A producer thread computes some value and sends it to a consumer thread through a queue. The queue is an array in memory with a head pointer and a tail pointer. The producer pushes an item onto the queue by writing to the address pointed to by the tail pointer and then incrementing the tail. The consumer pulls an item from the queue by reading from the address pointed to by the head pointer and then incrementing the head. The queue is empty if the head pointer and tail pointer are the same.

[Diagram of queue with head and tail pointers]

Assuming that the queue is infinitely long, and each item is eight bytes, the assembly code for the producer and consumer program is as follows.

<table>
<thead>
<tr>
<th>Producer</th>
<th>Consumer</th>
</tr>
</thead>
<tbody>
<tr>
<td># address of tail pointer in x1</td>
<td># address of tail pointer in x1</td>
</tr>
<tr>
<td># data to be written in x2</td>
<td># address of head pointer in x2</td>
</tr>
<tr>
<td>ld x3, 0(x1)</td>
<td>ld x3, 0(x2)</td>
</tr>
<tr>
<td>sd x2, 0(x3)</td>
<td>spin:</td>
</tr>
<tr>
<td>addi x3, x3, 8</td>
<td>ld x4, 0(x1)</td>
</tr>
<tr>
<td>sd x3, 0(x1)</td>
<td>beq x3, x4, spin</td>
</tr>
</tbody>
</table>

This code will be correct if the memory system is sequentially consistent and there is only one producer and one consumer.
1. Would this still be correct if we had a relaxed memory model? What problems could occur?

2. What is the minimum set of fence instructions that needs to be added to make these programs work with a relaxed memory model?
3. Now assume we have multiple producers sharing the same queue. We want to rewrite the producer code to make it thread safe. Assume we no longer have to worry about the order of storing to the queue vs. storing the tail pointer.

We can use an atomic fetch-and-add, a compare-and-swap, or a test-and-set instruction as our synchronization primitive. Write the producer code using each of these. Assume as before that register x1 contains the address of the tail pointer and register x2 contains the data to be stored. Pseudocode for these primitives is shown below.

<table>
<thead>
<tr>
<th>Primitive</th>
<th>Pseudocode</th>
</tr>
</thead>
</table>
| Atomic Add          | amoadd rd, rs1, (rs2)  
 rd <= M[rs2]  
 M[rs2] <= rd + rs1 |
| Compare and Swap    | cas rd, rs1, rs2, (rs3)  
 if (rs1 == M[rs3])  
 M[rs3] <= rs2  
 rd <= 1  
 else  
 rd <= 0 |
| Test and Set        | ts rd, (rs)  
 rd <= M[rs]  
 M[rs] <= 1 |

4. Which of these methods is most efficient (least number of memory transactions)? Which is the least efficient?