

CS150 Project
Checkpoint 1

Keypad and LCD Interface

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- 1) Physical Interface
- 2) Keypad
- 3) LCD (Optrex DMC-24227)
- 4) Design Structure and FSM
- 5) Design implementation
- 6) Hints and cautions

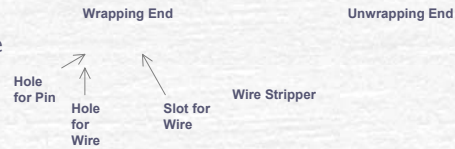
1) Establishing the physical interface: wire wrapping

- Materials needed: wire wrap, wire wrap tool, and a little practice.

- Wire wraps available from the IEEE office at 204a Cory. (Next door)

- Pins are given in chkpt1 specification.

- Wire wrap according to diagram on the right.



2) Keypad

- 4x4 keypad, each pin is connected to a specific row or column.
- Remember to connect a pull-down resistor to each output line of the keypad into your design.
- You will need to cycle through each row and check the columns for any button presses.

	C0	C1	C2	C3
R0	1	2	3	A
R1	4	5	6	B
R2	7	8	9	C
R3	*	0	#	D

3) LCD (Optrex DMC-24227)

- Based off Hitachi HD44780 controller chip.
- We will be using 4-bit mode, 5 by 7 dot matrix

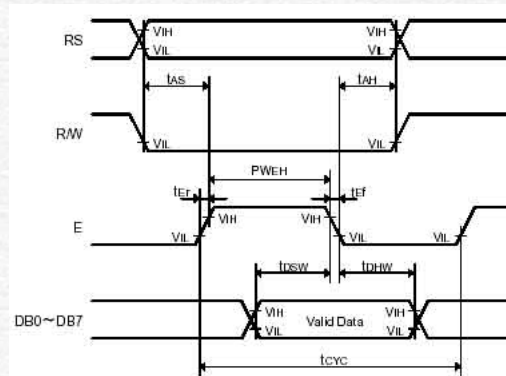


Fig.1 Write Operation Timing

$V_{CC}=5.0V \pm 10\%$

Parameter	Symbol	Conditions	Min.	Max.	Units
Enable Cycle Time	t_{cyc}	Fig. 1, 2	500	—	ns
Enable Pulse Width	$PWEH$	Fig. 1, 2	230	—	ns
Enable Rise/Fall Time	t_{Er}, t_{Ef}	Fig. 1, 2	—	20	ns
Address Setup Time	t_{AS}	Fig. 1, 2	40	—	ns
Address Hold Time	t_{AH}	Fig. 1, 2	10	—	ns
Write Data Setup Time	t_{DSW}	Fig.1	80	—	ns
Write Data Hold Time	t_{DHW}	Fig.1	10	—	ns
Read Data Delay Time	t_{DDR}	Fig.2	—	160	ns
Read Data Hold Time	t_{DHR}	Fig.2	5	—	ns

- The enable pulse can be created using a 490 Hz clock.
- In the 4-bit mode, the control bytes are sent on consecutive enable cycles. The most significant 4 bits (DB[7:4]) are sent first, followed by the remaining 4 bits of the byte (DB[3:0]).

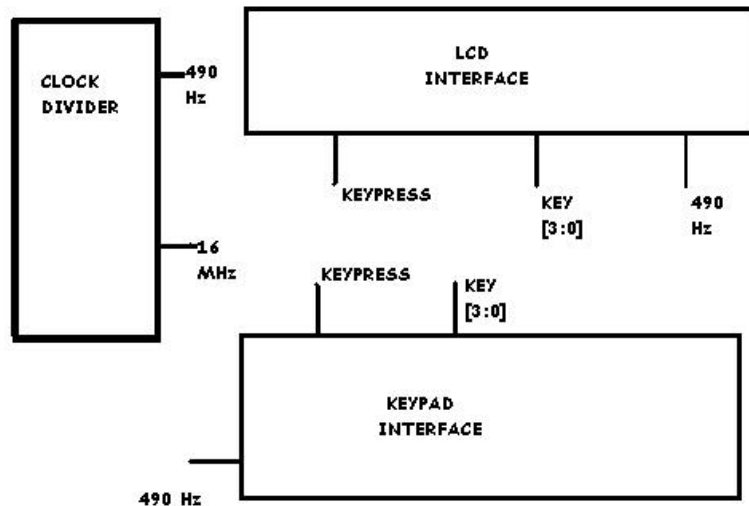
- When sending instructions to the LCD, you will need to remember to send the RS, R/W and enable signals along with the databytes.

eg. RS R/W DB7 DB6 DB5 DB4
 0 0 0 0 0 0
 0 0 1 0 0 0

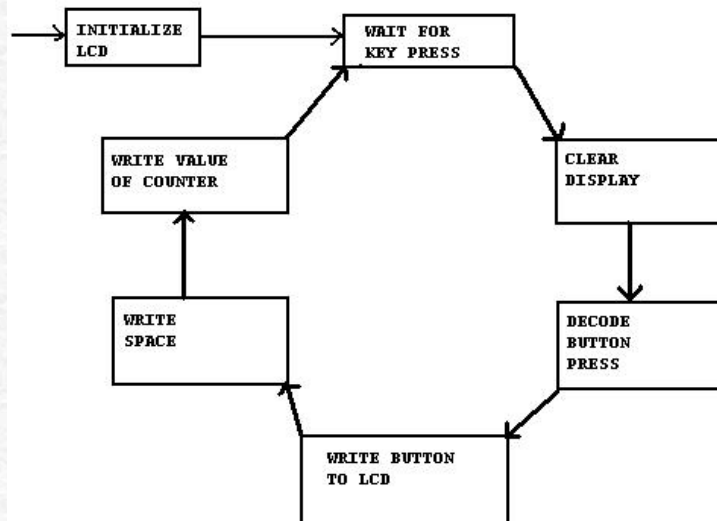
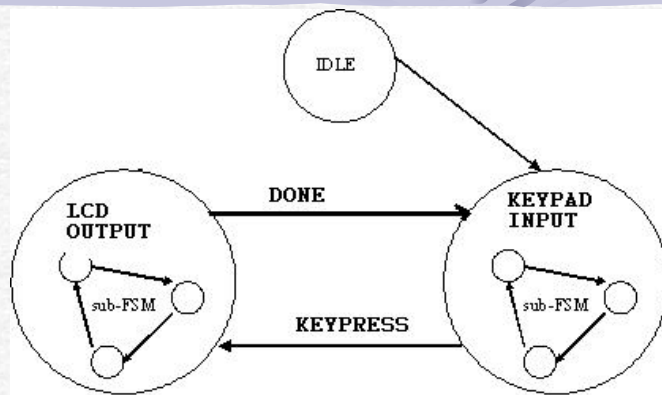
this "Display Off" instruction would be implemented on two enable cycles.

[in 8 bit: you would send 00 0000 1000 with enable]

4) Design Structure

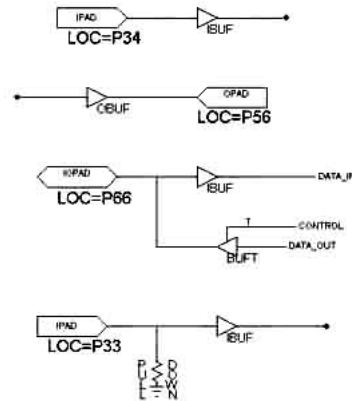


FSM



IPADS & OPADS:

- Make sure there is always a BUF corresponding to the type of PAD connected.
- Avoid the use of copy and paste in your schematics, ESPECIALLY IPADS and OPADS.



6) Hints and Cautions

- Really sit down and plan your FSM before doing anything in Xilinx. Write it down, draw state diagrams... etc - understand what's suppose to happen.
- Minimize as much as possible.
- Look at error messages.
- The oscilloscope is your friend!
- Use a potentiometer for the LCD power (if there's nothing on the screen, give the potentiometer a tweak).