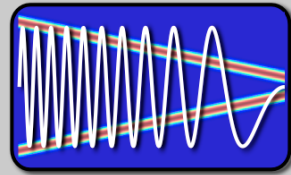


EE123



Digital Signal Processing

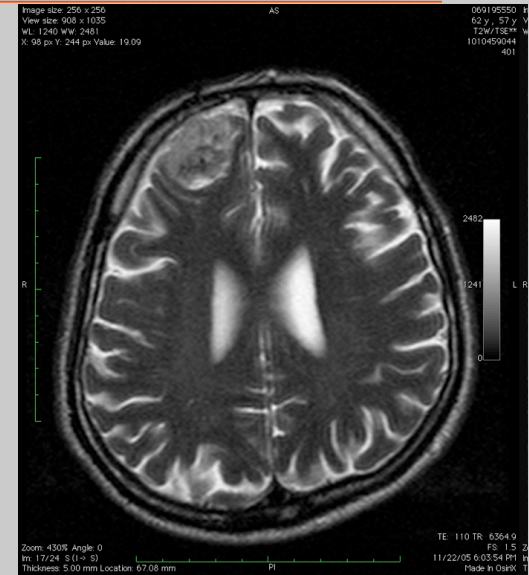
Lecture 26

Based on lecture notes by Prof. Murat Arcaç

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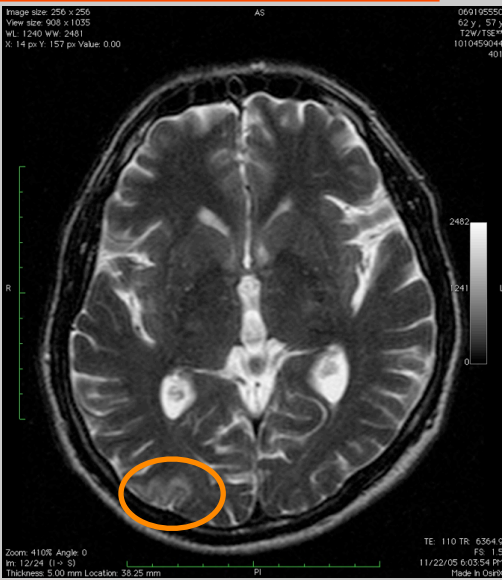
Why I Love MRI



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Where's the stroke?



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Where is the stroke?



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Lab 3 - Part I

- Purpose is to test your radio interface
 - Learn about what you can do
 - Work with the SDR and the radio
- Start working on it now!



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Buffered Audio I/O processing

```
• Qin = Queue.Queue()
• Qout = Queue.Queue()
• # create a pyaudio object
• p = pyaudio.PyAudio()

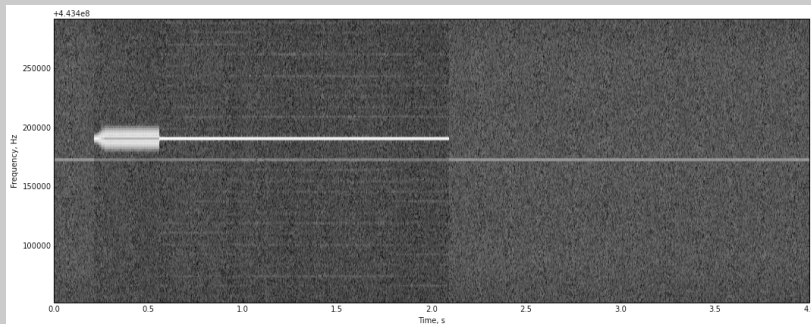
• # find the device numbers for builtin I/O and the USB
• din, dout, dusb = audioDevNumbers(p)
• # initialize a recording thread. The USB device only supports 44.1KHz sampling rate
• t_rec = threading.Thread(target = record_audio, args = (Qin, p, 44100, dusb ))
• # initialize a playing thread.
• t_play = threading.Thread(target = play_audio, args = (Qout, p, 44100, dout ))
• # start the recording and playing threads
• t_rec.start()
• t_play.start()
• # record and play about 10 seconds of audio 430*1024/44100 = 9.98 s
• for n in range(0, 430):
•     samples = Qin.get()
•     # You can add code here to do processing on samples in chunks of 1024
•     # you will have to implement an overlap add, or overlap an save to get
•     # continuity between chunks
•     Qout.put(samples)
• p.terminate()
```

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Testing VOX transmit

- You want to find the pulse length that is:
 - Long enough to activates the VOX
 - Short enough that radio does not start transmitting the tone
 - Add zeros so the signal sent immediately after will be heard -- good to have extra delay to let squelch on reciev radio to open

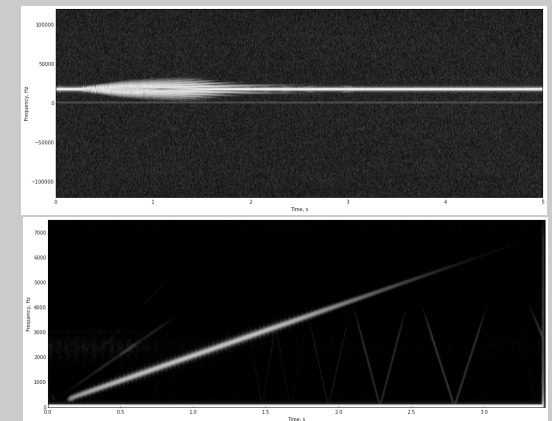


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Measure Frequency Response

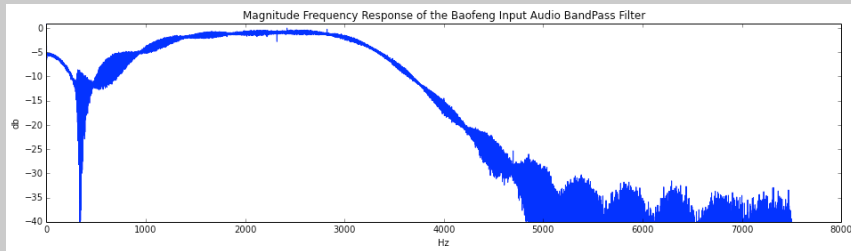
- Of the Radio Audio input
 - Play a chirp
 - Listen using SDR
 - Demodulate



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Frequency Response



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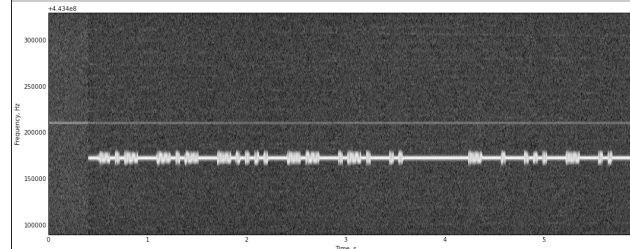
Morse Code Function

- Write a function
 - Converts text to morse
 - Transmit and receive

International Morse Code

1. The length of a dot is one unit.
2. A dash is three units.
3. The space between parts of the same letter is one unit.
4. The space between letters is three units.
5. The space between words is seven units.

A	•—	U	•••—
B	•••—	V	••••
C	—•••	W	•—••
D	••—•	X	•••—•
E	•	Y	••—••
F	••••	Z	—••••
G	—•		
H	••••		
I	••		
J	•—•••		
K	•—•		
L	•••—•	1	•••••
M	—•—	2	••••••
N	—••	3	•••••••
O	—•••	4	••••••••
P	•—•••	5	•••••••••
R	••—••	6	••••••••••
S	•••••	7	•••••••••••
T	—	8	••••••••••••
		9	•••••••••••••
		0	••••••••••••••



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Projects

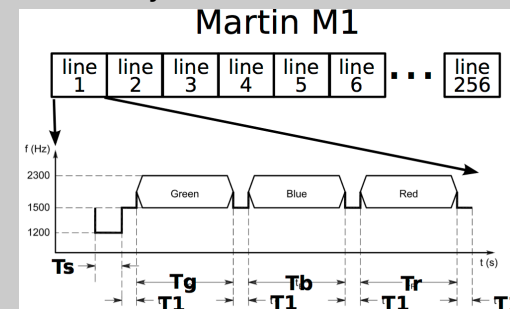
- Select a project by next Friday
 - Submit 2 paragraph project proposal on b-space
 - Includes Topic and the scope of the project
- Project Deliverables
 - Software
 - Demo
 - A few slides / Poster

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Project Topics

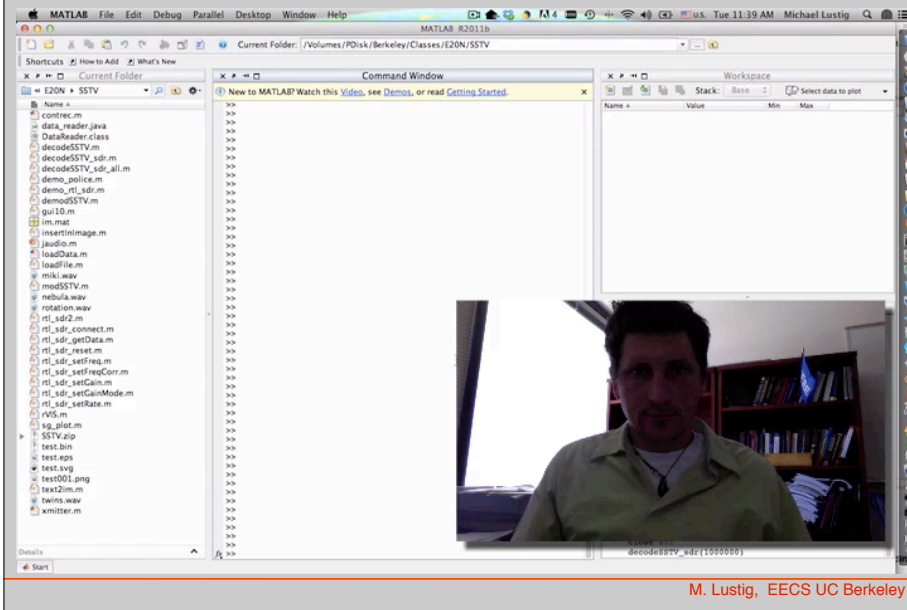
- Default: SSTV Transceiver System
 - Implement a Xeiwer for one of the ham SSTV protocols. For example Martin M1/ Scottie S1-4
 - Transmitter straightforward
 - Good receiver system makes all the difference



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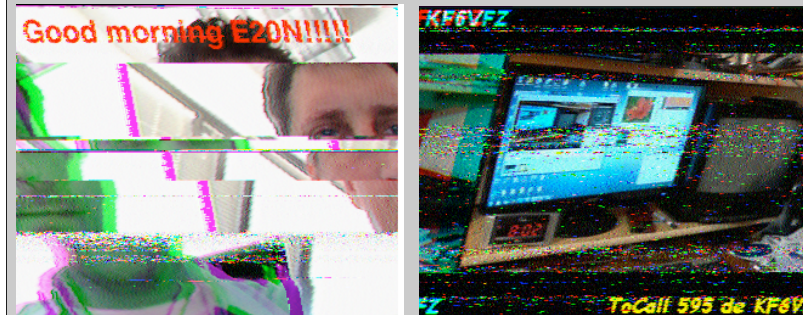
Example From last Year



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A Lot about the receiver.....



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More project ideas

- DTMF/Voice Controlled something
 - Message board
 - Answering system
 - Voice Mail
- Cross-band FM repeater chat room with a control channel
 - SDR receives large band
 - Transmits combined signals on another channel
 - Need to register or have a code to join... maybe?

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Other Project Ideas

- Come up with a new SSTV Protocol
 - Analog or Digital
- Video Protocol
- Methods to overlay digital information over voice
- Digital Voice - Implement an algorithm or come up with your own

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More Projects

- Simple voice recognition
- Implementation / Invention of ANY useful ham protocol
- High-Quality audio by time-stretching or scrambling

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More Challenging Projects

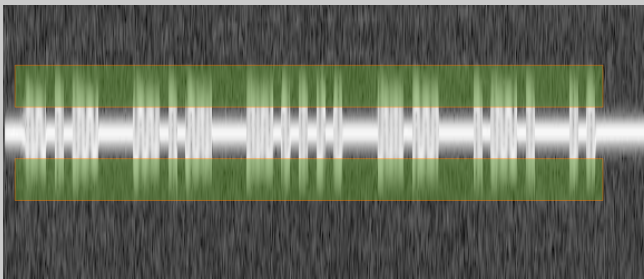
- Separation of two interfering FM signals for repeaters
- A fancy communication channel OFDM/QAM over voice
- Phased Array RTL-Receiver
 - Passive Radar
 - Direction detection
- Weak signal Communication with FM radios and SDR

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Weak Signal

- Can be extremely low-rate
 - Telemetry
 - Bounce
 - Use AM receive with FM transmitters



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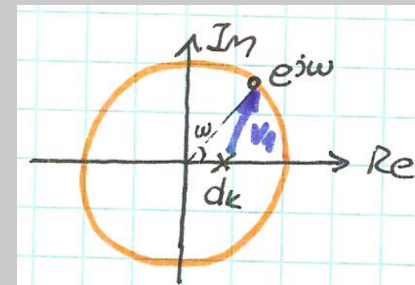
Magnitude Response

Magnitude of products is product of magnitudes

$$|H(e^{j\omega})| = \left| \frac{b_0}{a_0} \right| \cdot \frac{\prod_{k=0}^M |1 - c_k e^{-j\omega}|}{\prod_{k=0}^N |1 - d_k e^{-j\omega}|}$$

Consider one of the poles:

$$|1 - d_k e^{-j\omega}| = |e^{+j\omega} - d_k| = |v_1|$$



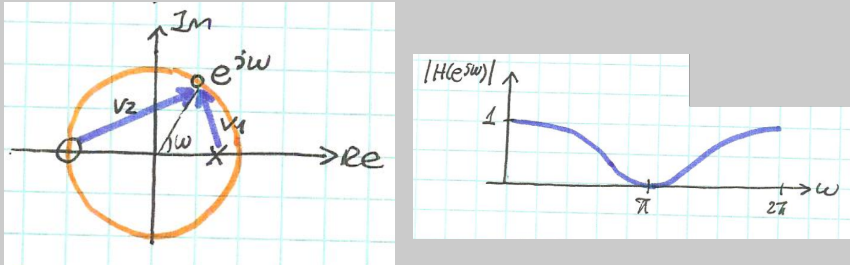
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Magnitude Response Example

Example:
$$H(z) = 0.05 \frac{1 + z^{-1}}{1 - 0.9z^{-1}}$$

$$|H(z)| = 0.05 \frac{|v_2|}{|v_1|}$$



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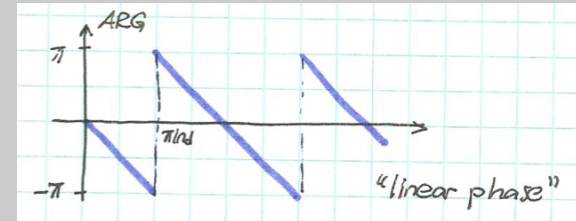
Phase response

Example:
$$H(e^{j\omega}) = e^{j\omega n_d} \leftrightarrow h[n] = \delta[n - n_d]$$

$$|H(e^{j\omega})| = 1$$

$$\arg[H(e^{j\omega})] = -\omega n_d$$

ARG is the wrapped phase
arg is the unwrapped phase



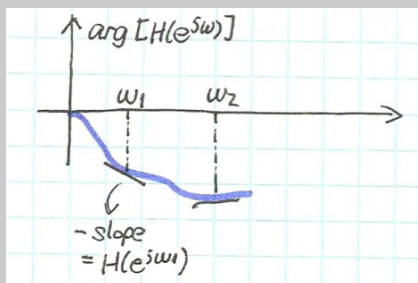
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Group delay

To characterize general phase response, look at the group delay:

$$\text{grd}[H(e^{j\omega})] = -\frac{d}{d\omega} \{ \arg[H(e^{j\omega})] \}$$



For linear phase system, the group delay is n_d

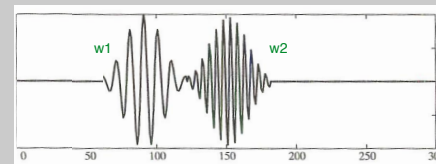
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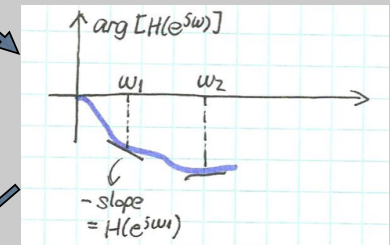
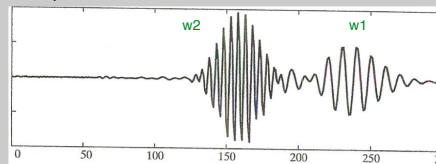
Group delay

$$\text{grd}[H(e^{j\omega})] = -\frac{d}{d\omega} \{ \arg[H(e^{j\omega})] \}$$

Input



Output



For narrowband signals, phase response looks like a linear phase

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Group delay math

$$H(z) = \frac{b_0}{a_0} \frac{\prod_{k=1}^M (1 - c_k z^{-1})}{\prod_{k=1}^N (1 - d_k z^{-1})}$$

arg of products is sum of args

$$\arg [H(e^{j\omega})] = -\sum_{k=1}^N \arg [1 - d_k e^{-j\omega}] + \sum_{k=1}^M \arg [1 - c_k e^{-j\omega}]$$

$$\text{grd} [H(e^{j\omega})] = -\sum_{k=1}^N \text{grd} [1 - d_k e^{-j\omega}] + \sum_{k=1}^M \text{grd} [1 - c_k e^{-j\omega}]$$

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Group delay math

$$\text{grd} [H(e^{j\omega})] = -\sum_{k=1}^N \text{grd} [1 - d_k e^{-j\omega}] + \sum_{k=1}^M \text{grd} [1 - c_k e^{-j\omega}]$$

Look at each factor:

$$\arg [1 - \underbrace{r e^{j\theta}}_{c_k \text{ or } d_k} e^{-j\omega}] = \tan^{-1} \left(\frac{r \sin(\omega - \theta)}{1 - r \cos(\omega - \theta)} \right)$$

$$\text{grd} [1 - r e^{j\theta} e^{-j\omega}] = \frac{r^2 - r \cos(\omega - \theta)}{|1 - r e^{j\theta} e^{-j\omega}|^2}$$

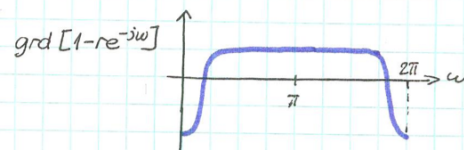
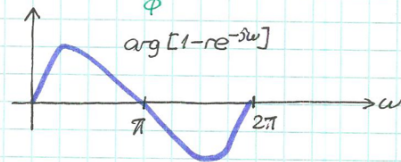
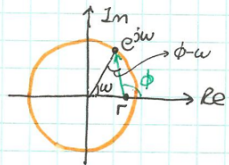
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Look at a zero lying on the real axis

Geometric Interpretation (for $\theta=0$)

$$\arg [1 - r e^{-j\omega}] = \arg [(e^{j\omega} - r) e^{-j\omega}] = \underbrace{\arg [e^{j\omega} - r]}_{\phi} - \underbrace{\arg [e^{j\omega}]}_{\omega}$$



$\theta \neq 0 \Rightarrow$ shift to the right by θ

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