EE123
Digital Signal Processing

Lecture 15

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Announcements

- Ham exam W 7-10+, Banato Auditorium
  - Please come on time
- Midterm this Friday
  - Open everything -- no laptop, no internet
- Lab:
  - Who is having trouble still?

Topics

- Last time
  - Ideal Sampling model C/D
  - Impulse sampling $x_c(t) \Rightarrow x_s(t)$
  - Impulses to discrete samples $x_s(nT) \Rightarrow x[n]$
  - Relationship $X_c(j\Omega) \Leftrightarrow X_s(j\Omega) \Leftrightarrow X(e^{j\omega})$
- Today
  - Ideal reconstruction D/C
  - D.T processing of C.T signals
  - C.T processing of D.T signals (ha?????)

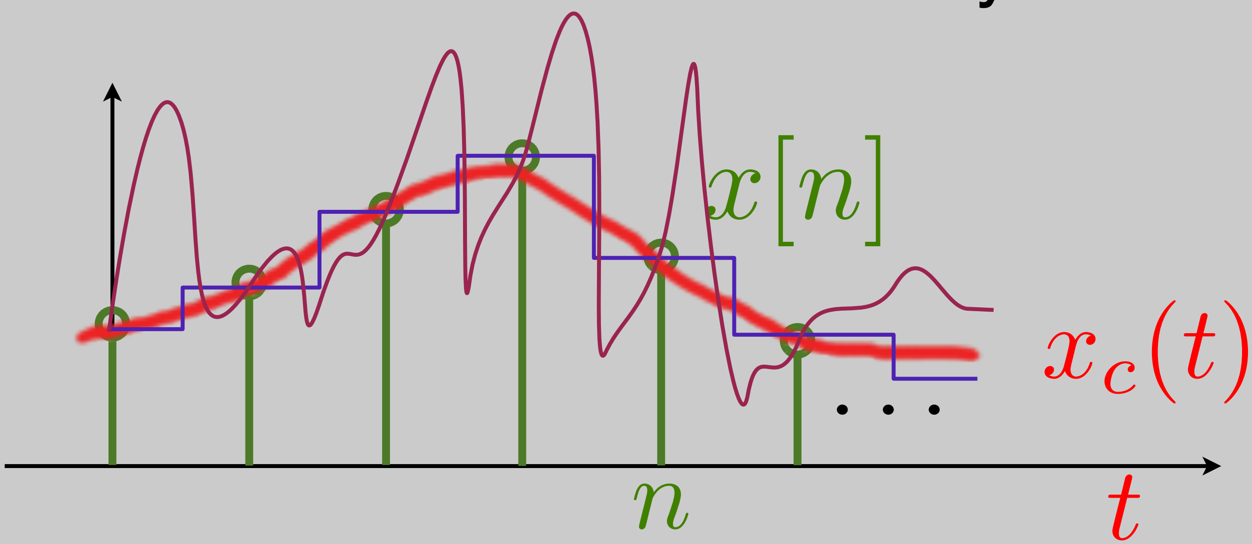
Reconstruction of Bandlimited Signals

- Nyquist Sampling Thm: suppose $x_c(t)$ is bandlimited

$$X_c(j\Omega) = 0 \quad \forall \quad |\Omega| \geq \Omega_N$$

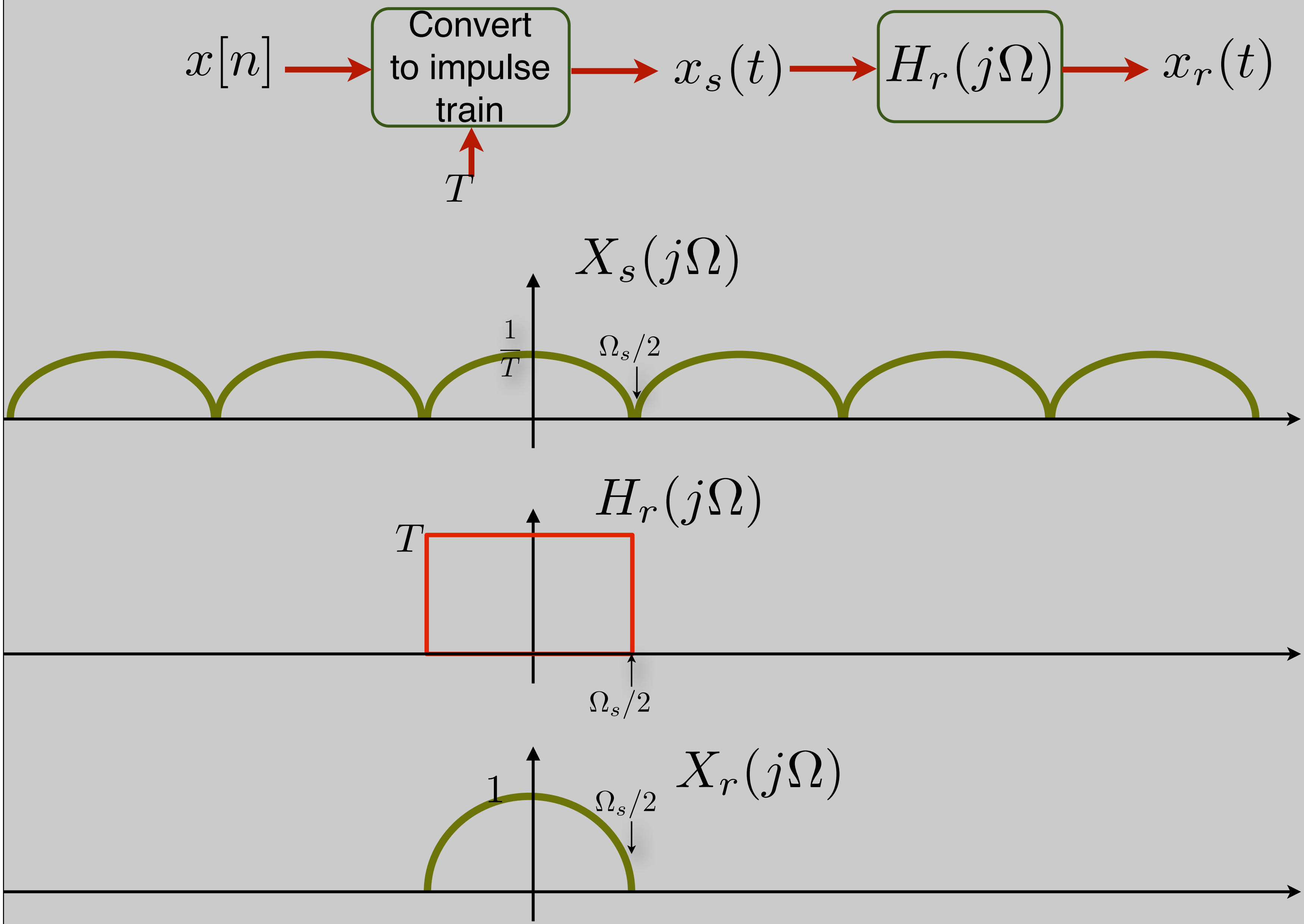
if $\Omega_s \geq 2\Omega_N$, then $x_c(t)$ can be uniquely determined from its samples $x[n] = x_c(nT)$

- Bandlimitedness is the key to uniqueness



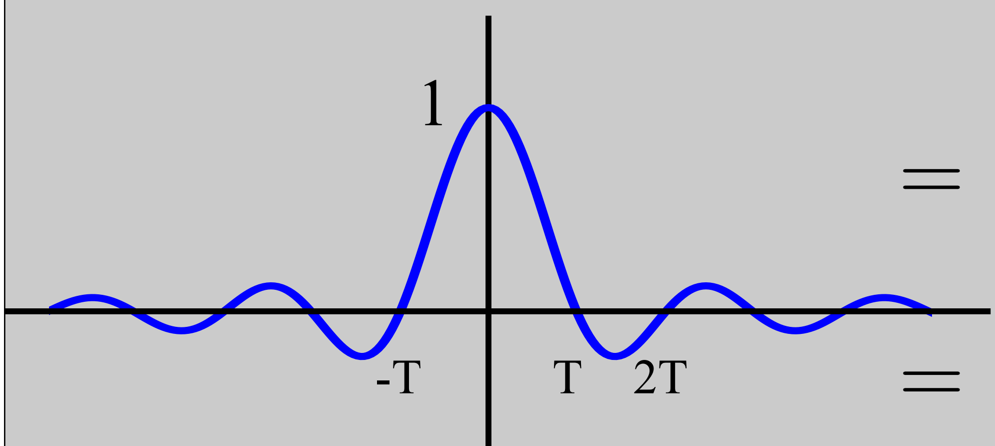
multiple signals go through the samples, but only one is bandlimited!

Reconstruction in Frequency Domain



Reconstruction in Time Domain

$$
\begin{aligned}
h_r(t) &= \frac{1}{2\pi}\int_{-\Omega_s/2}^{\Omega_s/2} T e^{j\Omega t}\, d\Omega \\
&= \frac{T}{2\pi}\frac{1}{jt} s^{j\Omega t}\Big|_{-\Omega_s/2}^{\Omega_s/2} \\
&= \frac{T}{\pi t}\frac{e^{j\frac{\Omega_s}{2}t} - e^{-j\frac{\Omega_s}{2}t}}{2j} \\
&= \frac{T}{\pi t}\sin(\frac{\Omega_s}{2}t) = \frac{T}{\pi t}\sin(\frac{\pi}{T}t) \\
&= \mathrm{sinc}(\frac{t}{T})
\end{aligned}
$$



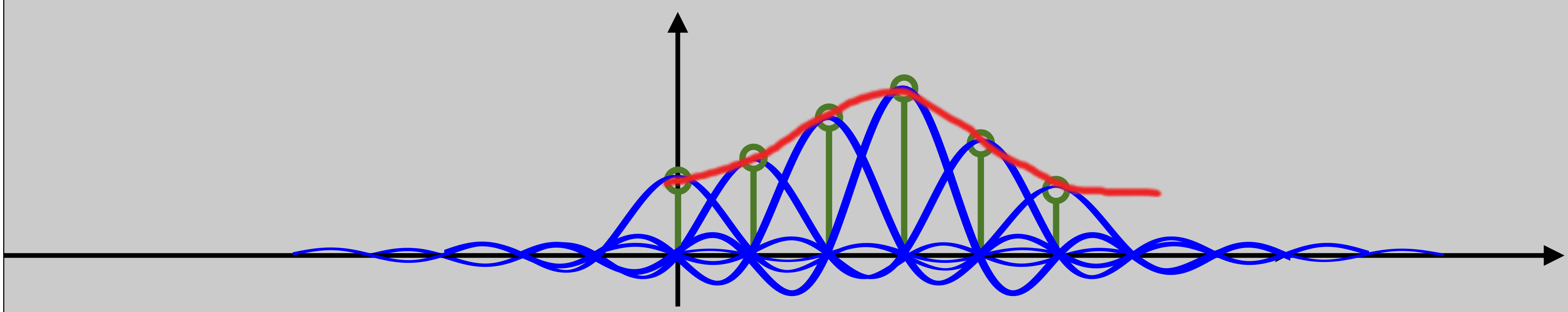
Reconstruction in Time Domain

$$x_r(t) = x_s(t) * h_r(t) = \left(\sum_n x[n]\delta(t - nT)\right) * h_r(t)$$

$$= \sum_n x[n]h(t - nT)$$

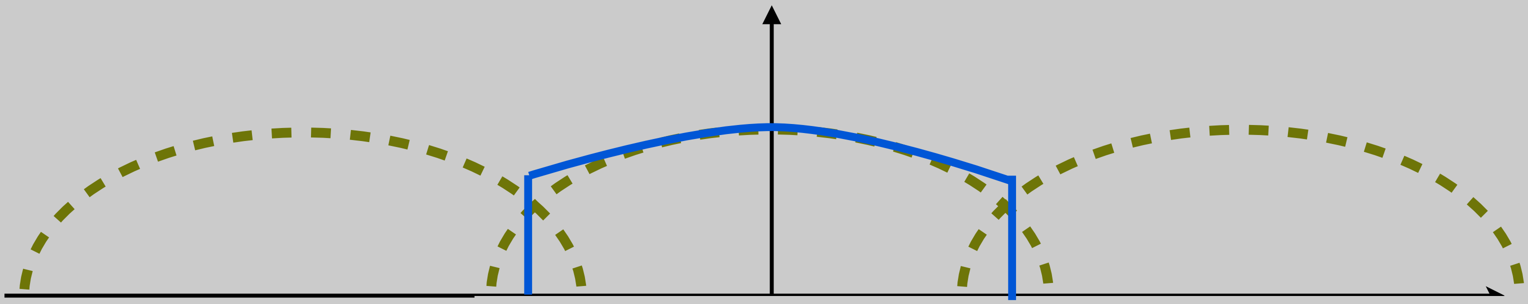
The sum of “sincs gives $x_r(t)$ ⇒ Unique signal

bandlimited by Ω_s



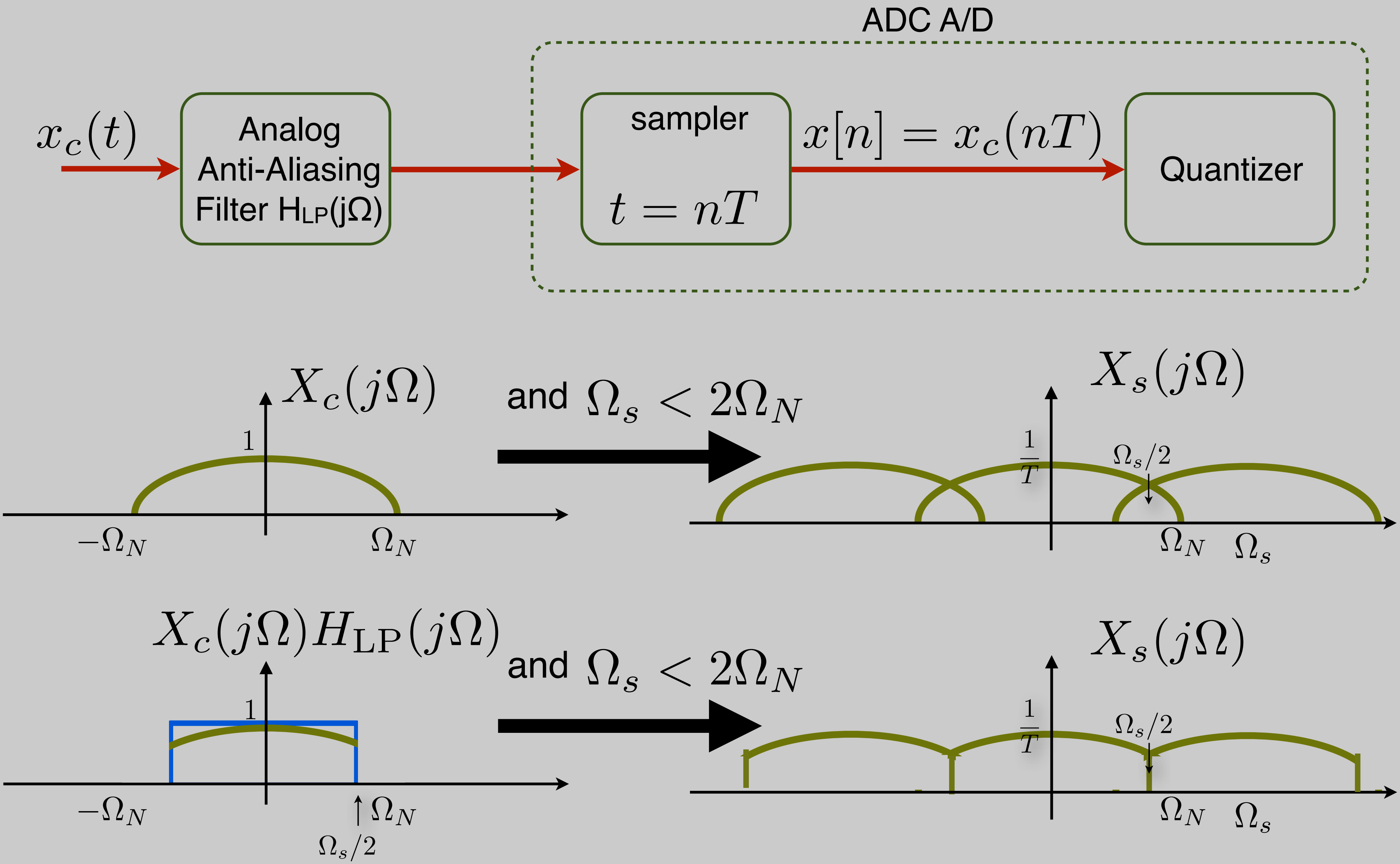
Aliasing

- If $\Omega_N > \Omega_s/2$, $x_r(t)$ an aliased version of $x_c(t)$

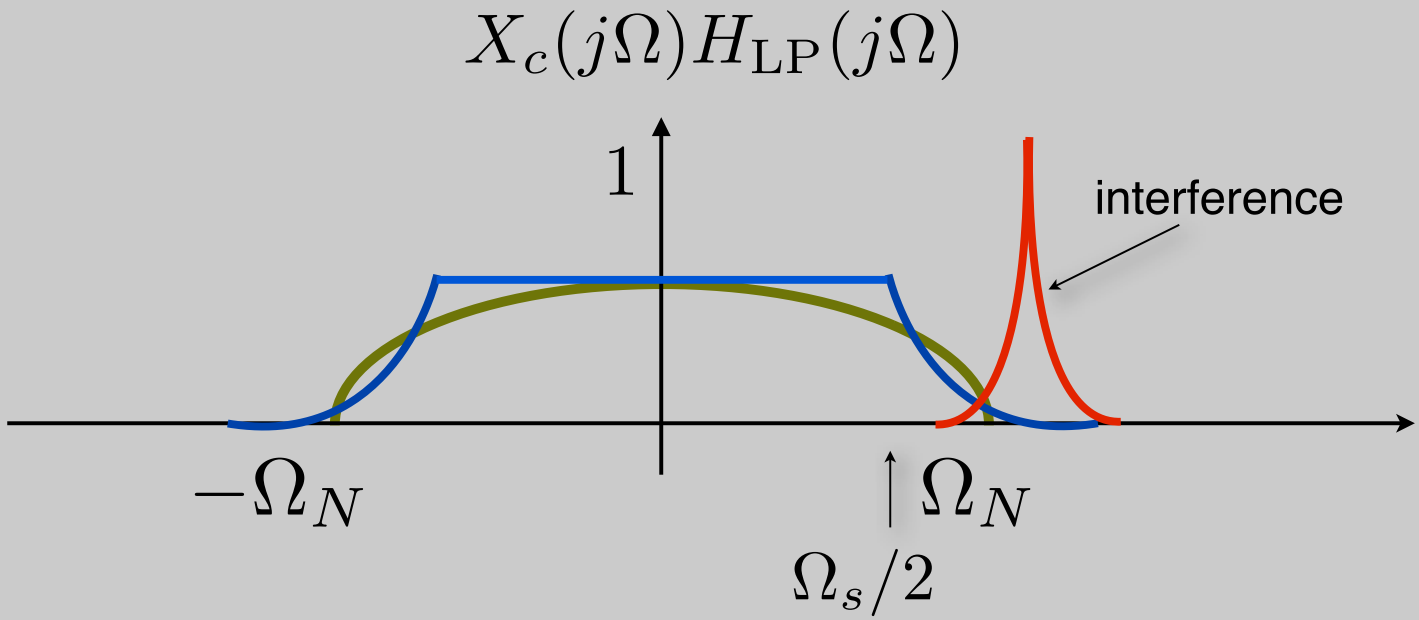


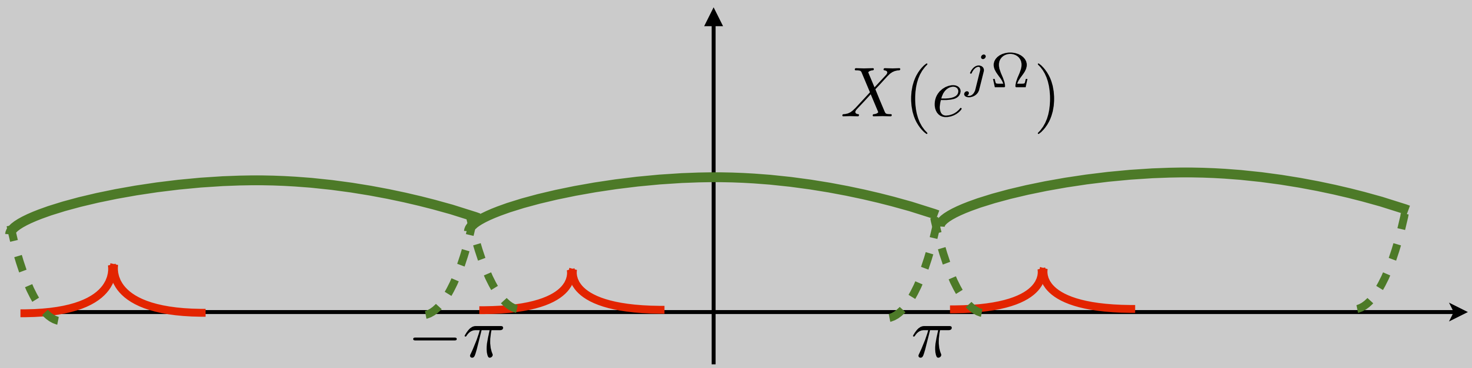
$$X_r(j\Omega) = \begin{cases} TX_s(j\Omega) & \text{if} \quad |\Omega| \leq \Omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

Anti-Aliasing



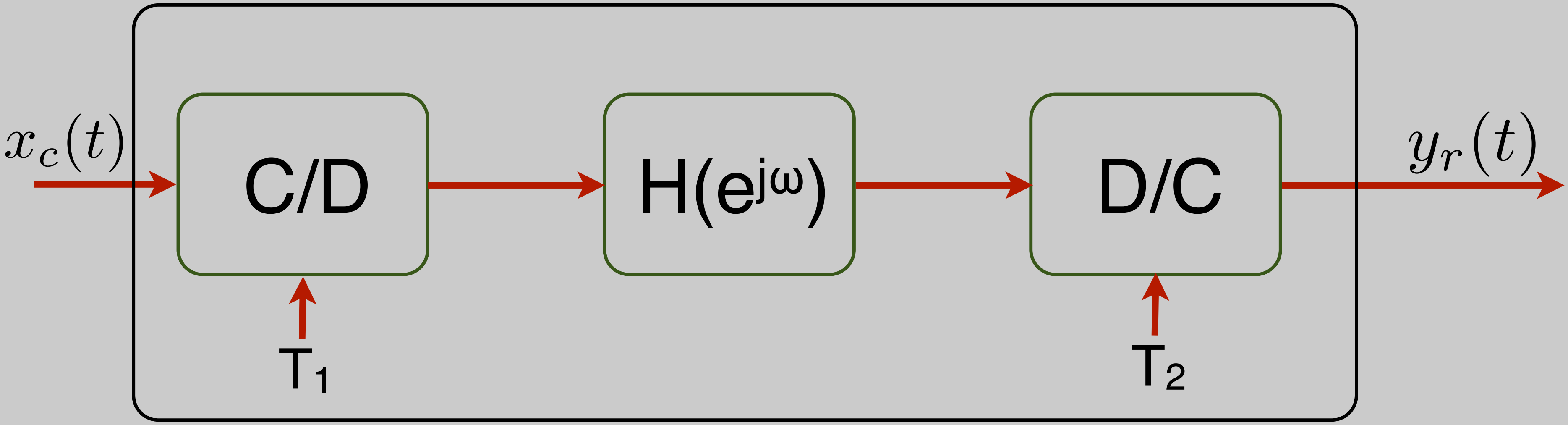
Non Ideal Anti-Aliasing





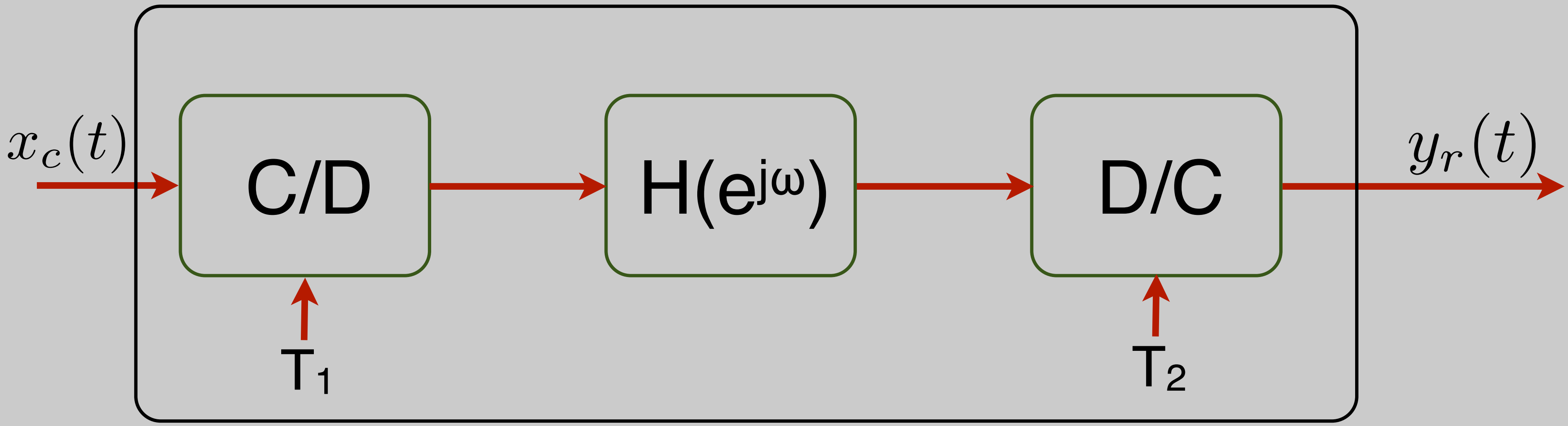
SDR non-perfect anti-Aliasing Demo

Discrete-Time Processing of C-T Signals



- Q: If *h[n]* is LTI, $H(e^{j\omega})$ exists,
  Is the whole system LTI?

Discrete-Time Processing of C-T Signals

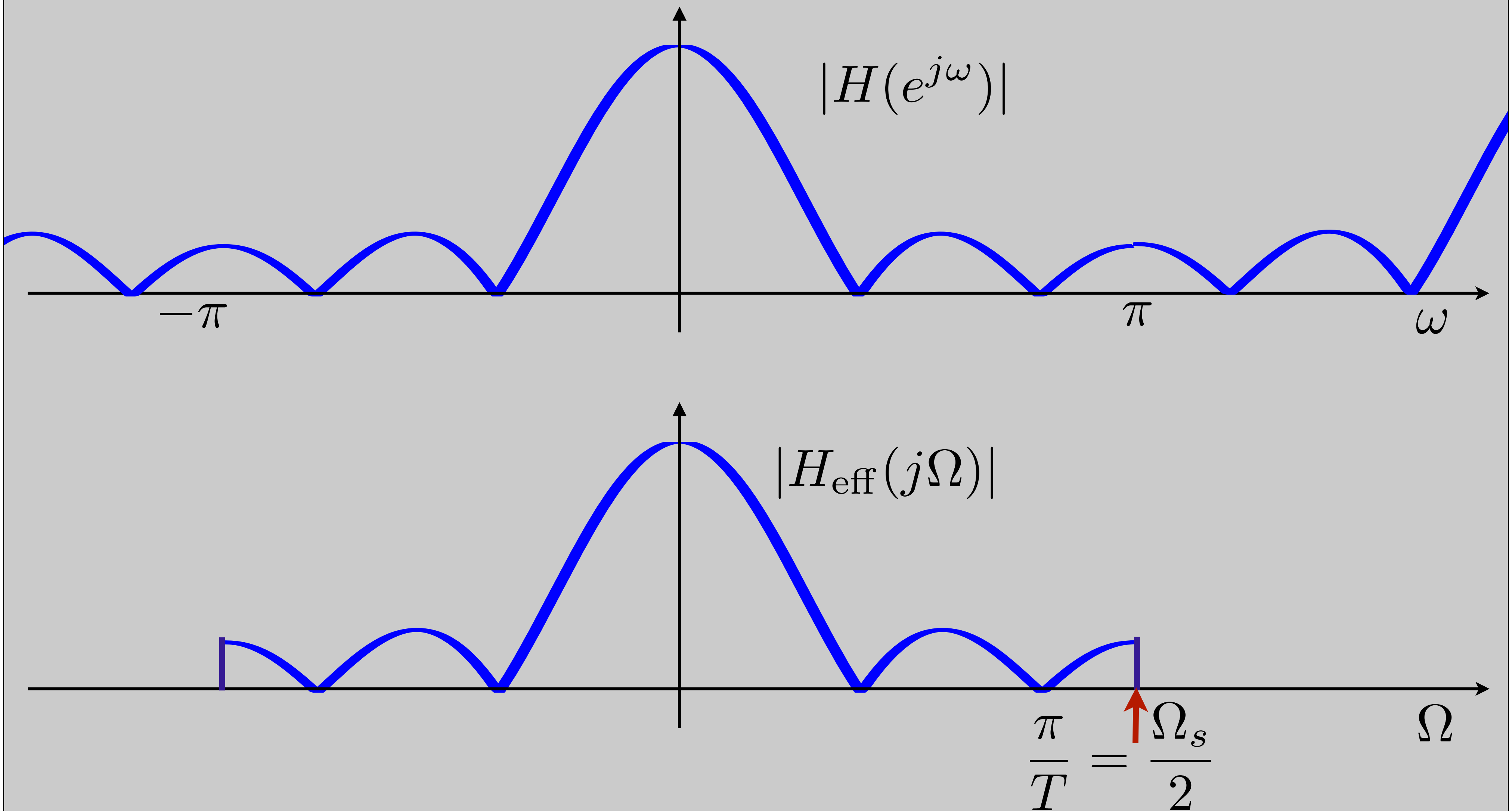


- Q: If *h[n]* is LTI, $H(e^{j\omega})$ exists,
  Is the whole system LTI?
- A: If xc(t) is bandlimited by $\frac{\Omega_s}{2} = \frac{\pi}{T}$ then,

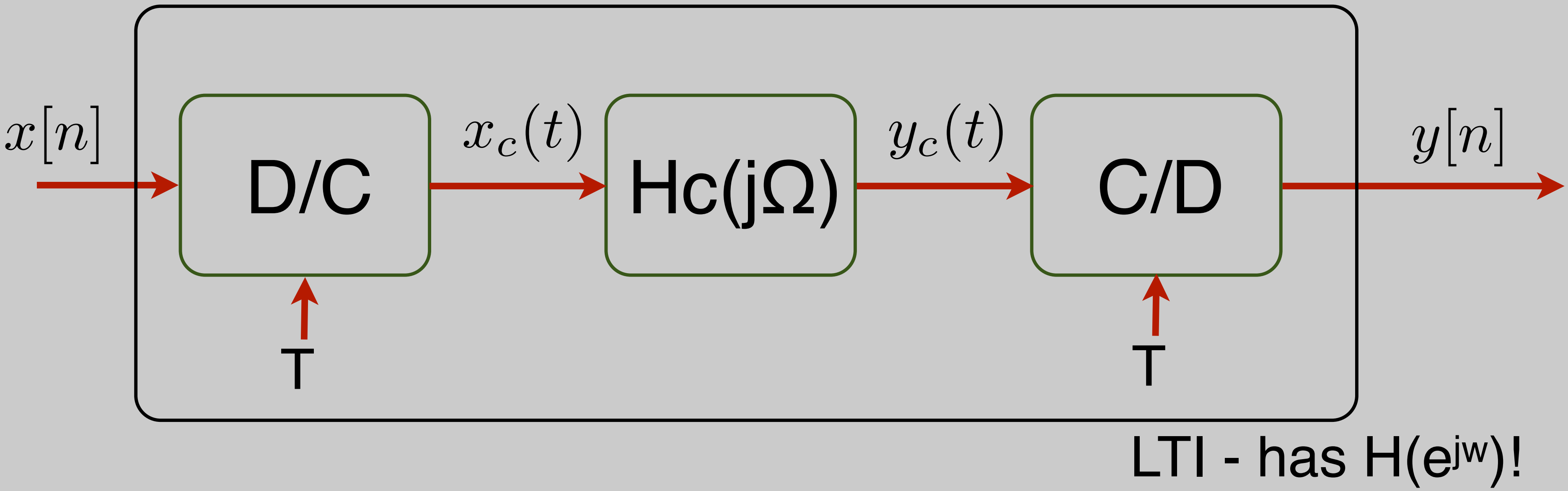
$$\frac{Y_r(j\Omega)}{X_c(j\Omega)} = H_{\text{eff}}(j\Omega) = \begin{cases} H(e^{j\omega})\big|_{\omega=\Omega T} & |\Omega| < \Omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

Example:

- Length 5 moving average



C.T Processing of D.T Signals



- Useful to interpret D.T. systems with no simple interpretation in discrete domain.

- <u>Tool:</u> recall: $$x_c(t) = \sum_{n=-\infty}^{\infty} x[n]\mathrm{sinc}\left(\frac{t-nT}{T}\right)$$

Derivation

$$X_c(j\Omega) = \begin{cases} TX(e^{j\omega})\Big|_{\omega=\Omega T} & |\Omega| \leq \Omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

$$Y_c(j\Omega) = H_c(j\Omega)X_c(j\Omega)$$ ⇒ also bandlimited

so,

$$Y(e^{j\omega}) = \frac{1}{T}\sum_k Y_c(j(\Omega - k\Omega_s))\Bigg|_{\Omega=\frac{\omega}{T}} = \frac{1}{T}Y_c(j\Omega)\Bigg|_{\Omega=\frac{\omega}{T}}$$

no aliasing!

Derivation

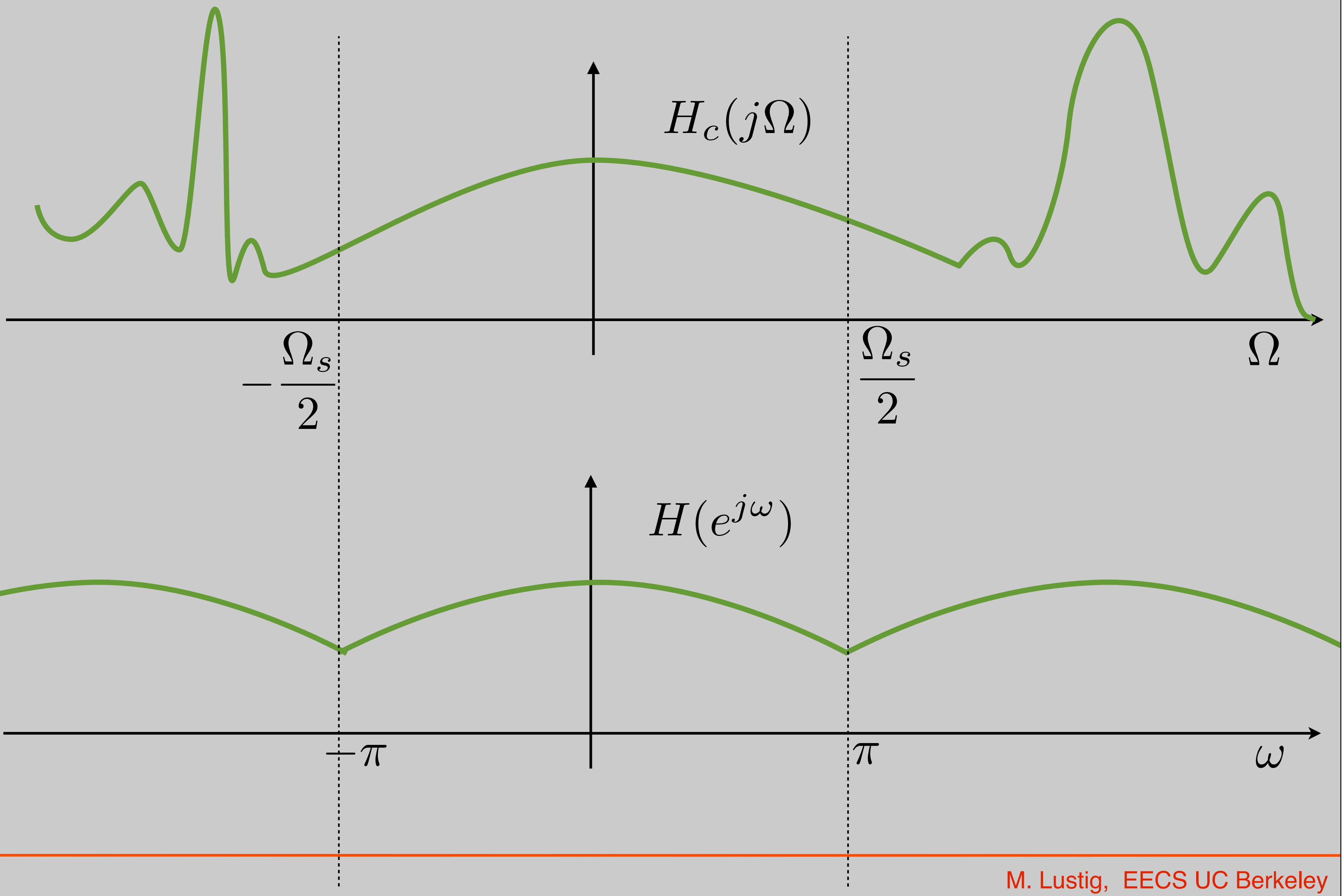
$$Y_c(j\Omega) = H_c(j\Omega)X_c(j\Omega)$$

$$Y(e^{j\omega}) = \frac{1}{T}\sum_k Y_c(j(\Omega - k\Omega_s))\bigg|_{\Omega=\frac{\omega}{T}} = \frac{1}{T}Y_c(j\Omega)\bigg|_{\Omega=\frac{\omega}{T}}$$

Combining the result:

$$Y(e^{j\omega}) = \underbrace{H_c(j\Omega)|_{\Omega=\frac{\omega}{T}}}_{H(e^{j\omega})} X(e^{j\omega}) \qquad |\omega| < \pi$$

Example:



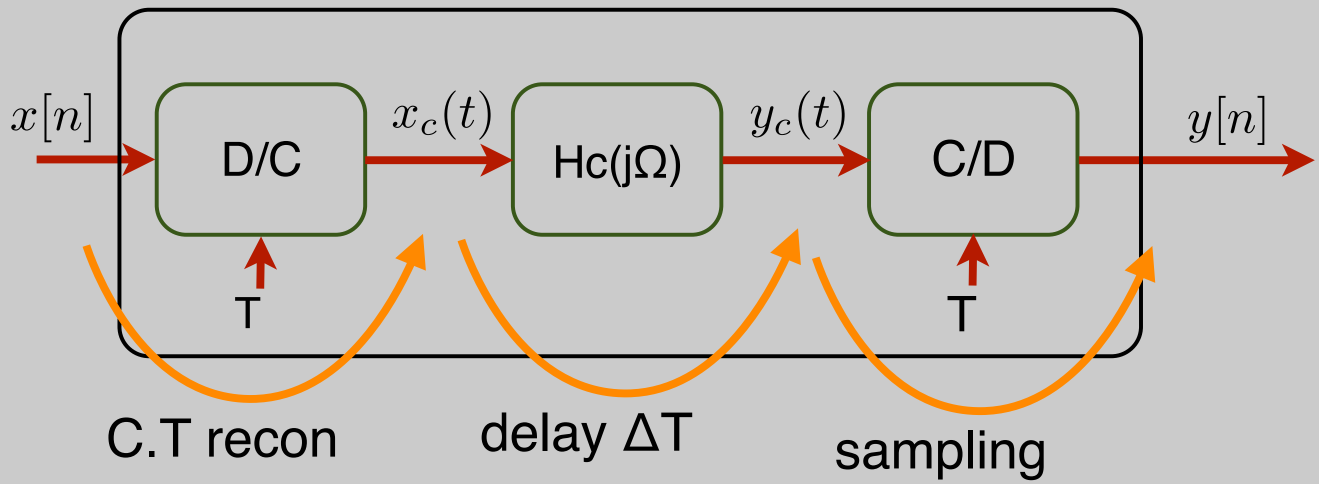
$H_c(j\Omega)$
$-\frac{\Omega_s}{2}$
$\frac{\Omega_s}{2}$
Ω
$H(e^{j\omega})$
$-\pi$
π
ω

Example:

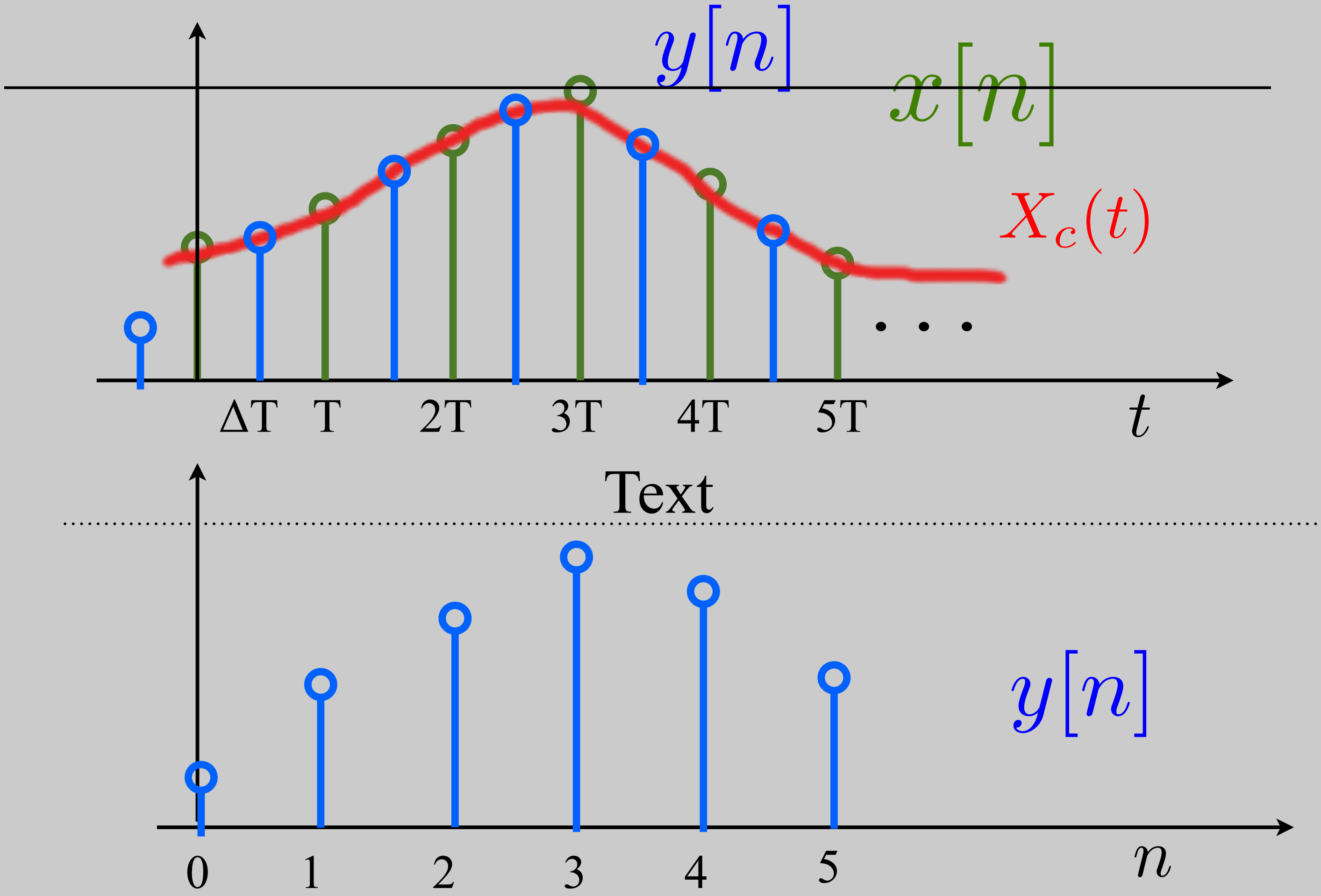
Non-integer delay: $$H(e^{j\omega}) = e^{-j\omega\Delta}$$

- What is the time-domain operation when Δ is not an integer (Δ=1/2)?

Let: $H_c(j\Omega) = e^{-j\Omega\Delta T}$ <u>delay of ΔT in time</u>



Example: Non Integer Delay



Example: Non Integer Delay

- The block diagram is only for interpretation!

$$y_c(t) = x_c(t - \Delta)$$

$$\begin{aligned} y[n] &= y_c(nT) = x_c(nT - T\Delta) \\ &= \sum_k x[k]\mathrm{sinc}\left(\frac{t - kT - T\Delta}{T}\right)\Bigg|_{t=nT} \end{aligned}$$

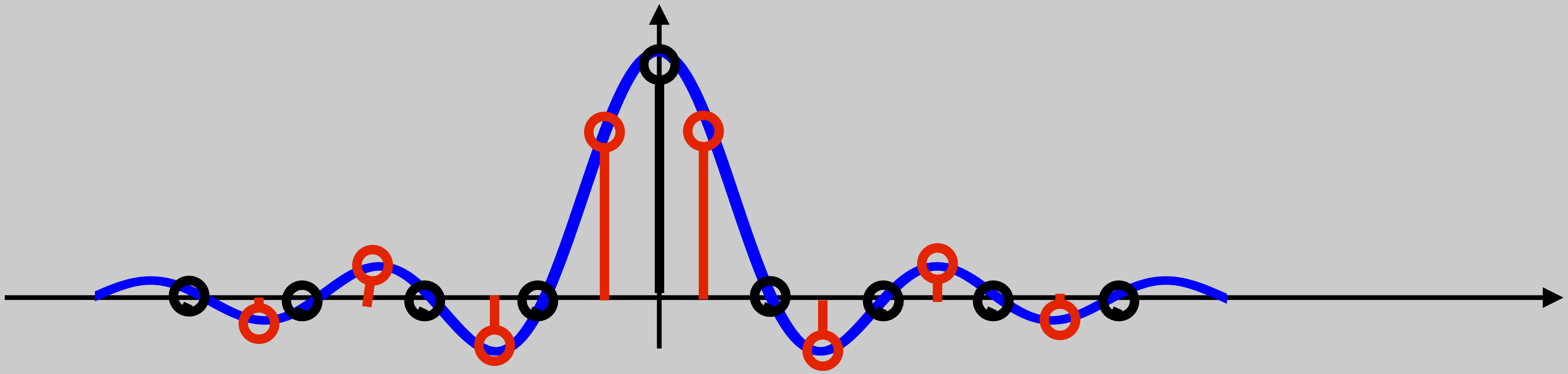
T's cancel!

$$= \sum_k x[k]\mathrm{sinc}(n - k - \Delta)$$

Example: Non Integer Delay

$$h[n] = \text{sinc}(n - \Delta)$$

Example: a discrete delta is a representation of a sampled sinc



shifted by partial samples results in many coefficients!