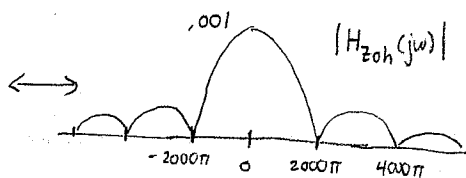
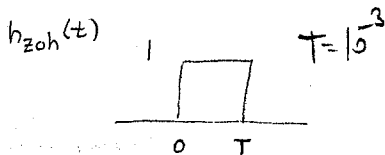
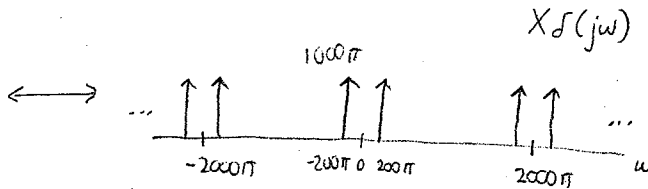
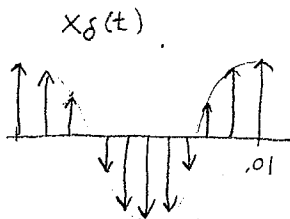
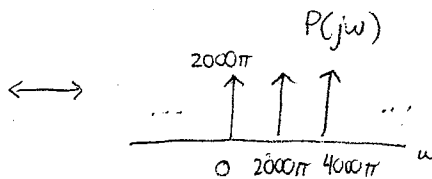
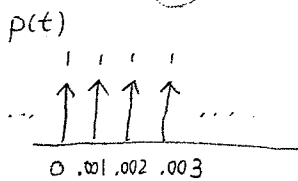
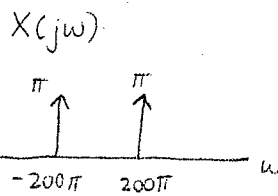
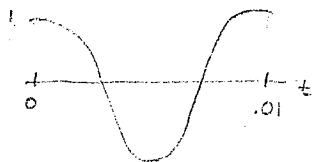
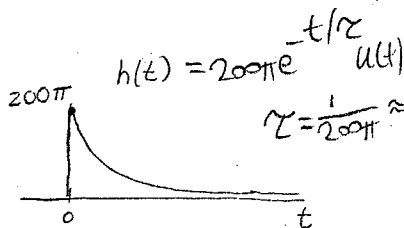
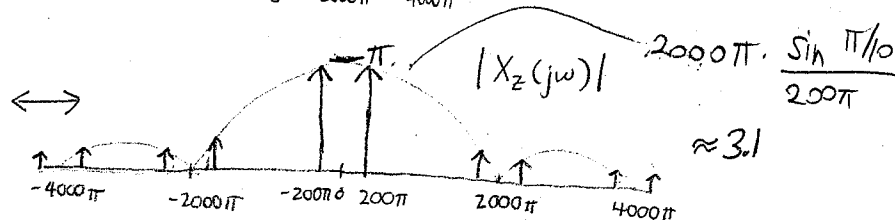
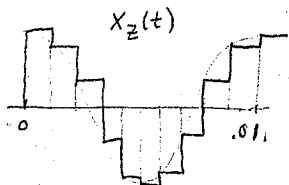


EERO Fall 20/4 PS #7

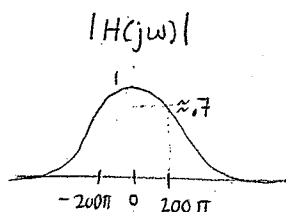
① a) $X(t) = \cos(200\pi t)$



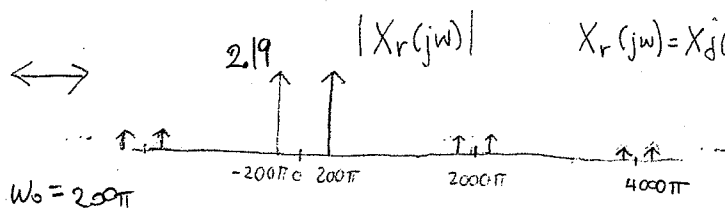
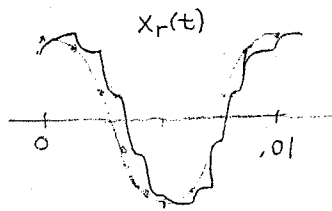
$$H_{zoh}(j\omega) = e^{-j\omega/2000} \frac{\sin \omega/2000}{\omega/2}$$



$$\tau = \frac{1}{200\pi} \approx 1.6 \text{ms}$$



$$H(j\omega) = \int_0^\infty h(t) e^{-j\omega t} dt = \int_0^\infty 200\pi e^{-200\pi t} e^{-j\omega t} dt = \frac{200\pi}{200\pi + j\omega}$$



$$X_r(j\omega) = X_\delta(j\omega) H_{zoh}(j\omega) H(j\omega)$$

b) Note that $X_r(t)$ is periodic, so an impulse in $X_r(j\omega)$ at $\omega_k = 200\pi k$ with magn. B_k corresponds to Fourier series coefficient a_k with magn $\frac{B_k}{2\pi}$.

$$P_{fund} = |a_1|^2 + |a_{-1}|^2 = 2|a_1|^2 = 2 \cdot \left(\frac{B_1}{2\pi}\right)^2 \approx 0.241883$$

$$a_0 = \frac{1}{2\pi} \sum_r(j9200\pi) = \frac{1}{2\pi} \sum_r(j1800\pi) \cdot H(j1800\pi) = \frac{1}{2\pi} (0.24)(0.11) = 6 \times 10^{-3}$$

$$P_{all} = \sum_k |a_k|^2 = \sum_k \left(\frac{B_k}{2\pi}\right)^2 = \sum_{k=1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20, \dots} \left[\frac{1}{4\pi^2} \cdot \left[1000\pi \cdot \frac{\sin \omega_k/2000}{\omega_k/2} \cdot \frac{200\pi}{\sqrt{(200\pi)^2 + \omega_k^2}} \right]^2 \right] \approx 0.241996 = 6 \times 10^{-3}$$

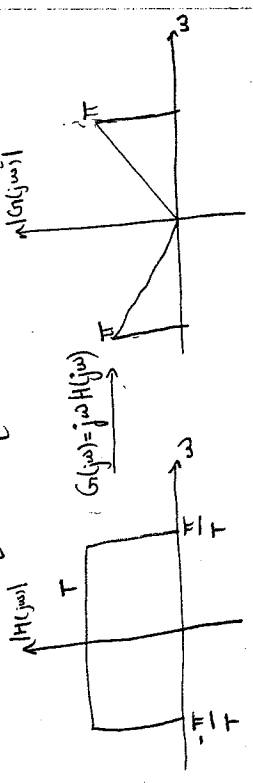
Fraction of power not at $\pm 100 \text{Hz} \approx 0.05\% = \frac{P_{all} - P_{fund}}{P_{all}}$

The ideal LPF interpolator in first diagram is $h(t) = \frac{T}{\pi} \frac{\sin(\pi t/T)}{t}$

So,

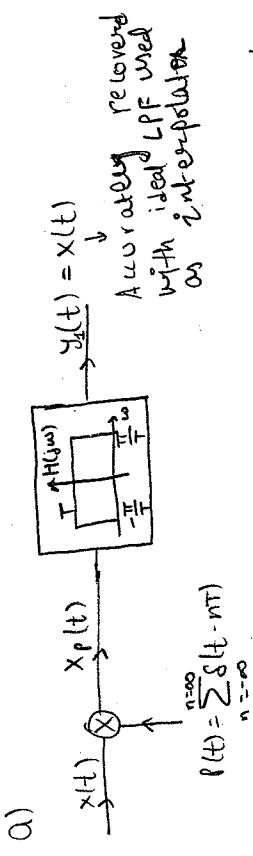
$$g(t) = \frac{T}{\pi} \frac{d}{dt} \left[\sin\left(\frac{\pi t}{T}\right) t^{-1} \right]$$

$$g(t) = \frac{T}{\pi} \left[-\frac{\sin(\pi t/T)}{t^2} + \frac{\pi \cos(\pi t/T)}{t} \right]$$

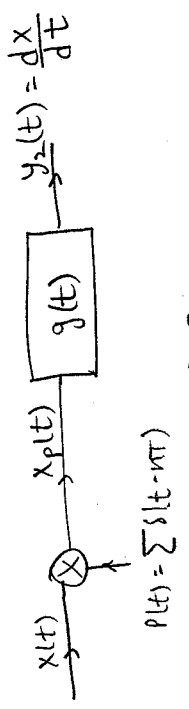


b) → Based on the above, $g(t) = \frac{dh}{dt}$ ensures that $y_2(t) = \frac{dy_1}{dt}$, referring to diagrams shown earlier. → For ideal reconstruction, i.e. $y(t) = x(t)$, $h(t)$ is unique thus $g(t)$ is also unique.

2)



This diagram illustrates the problem we've looked at thus far in the course. The following diagram represents the scenario under consideration here.



$$x_p(t) = \sum_{n=-\infty}^{\infty} x(nT) \delta(t-nT)$$

$$y_1(t) = g(t) * \sum_{n=-\infty}^{\infty} x(nT) \delta(t-nT)$$

$$y_2(t) = \sum_{n=-\infty}^{\infty} x(nT) g(t-nT)$$

note that in the first diagram,

$$y_1(t) = \sum_{n=-\infty}^{\infty} x(nT) h(t-nT)$$

So, to obtain $y_2(t) = \frac{dx}{dt}$, we we

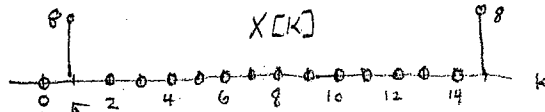
$$g(t) = \frac{dh}{dt}$$

③ a) $x(t) = \cos(2\pi \cdot 1000 t)$

$x[n] = x(nT) = \cos(2\pi \cdot 1000 n \cdot \frac{1}{16000}) = \cos(\frac{\pi}{8} n) = \frac{1}{2} e^{j\frac{\pi}{8} n} + \frac{1}{2} e^{-j\frac{\pi}{8} n}, n=0,1,\dots,15$

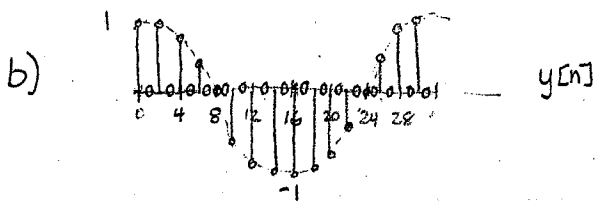
Recall that $x[n] = \frac{1}{16} \sum_{k=0}^{15} X[k] e^{j\frac{\pi}{8} kn}$

By inspection, we can see that $X[k] = \begin{cases} 8 & k=1, 15 \\ 0 & \text{otherwise} \end{cases}$



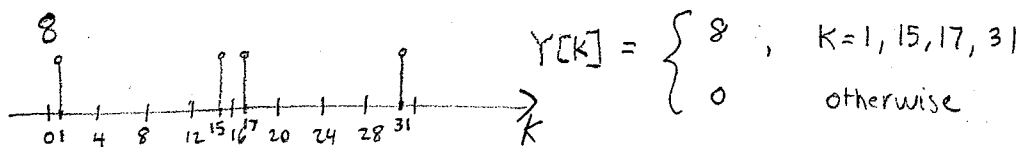
spacing of samples: $\frac{2\pi}{N} = \frac{\pi}{8} \Rightarrow \frac{2\pi}{T_0} = 1 \text{ kHz}$

$k=4$ corresponds to $\frac{2\pi k}{N} = \frac{\pi}{2} = 4 \cdot \frac{2\pi}{T_0} = 4 \text{ kHz}$



$$\begin{aligned} Y[k] &= \sum_{n=0}^{31} y[n] e^{-j\frac{2\pi}{32} kn} \\ &= \sum_{\substack{n=0 \\ n \text{ even}}}^{30} y[n] e^{-j\frac{\pi}{16} kn} \\ &= \sum_{\substack{n=0 \\ n \text{ even}}}^{30} x[n/2] e^{-j\frac{\pi}{16} kn} \quad m=n/2 \\ &= \sum_{m=0}^{15} x[m] e^{-j\frac{\pi}{8} km} \\ &= X[k], \quad k=0,1,\dots,31 \end{aligned}$$

← Note that for $k=16,\dots,31, X[k] = X[k-16]$



spacing of samples: $\frac{2\pi}{N} = \frac{\pi}{16}$, $k=32$ corresponds to $\frac{2\pi}{T'}$, where

$T' = T/2 = \frac{1}{32 \text{ kHz}}$, $\frac{2\pi}{T'} = 2\pi \cdot 32 \text{ kHz}$, $k=1$ corresponds to $\frac{2\pi}{32 \text{ kHz}} = 1 \text{ kHz}$.

spacing of samples same in frequency domain as for $X[k]$

4) a) $x(t) = \Gamma(t+1)$

$X(s) = \int_{-1/2}^{1/2} e^{-st} dt = -\frac{1}{s} [e^{-s/2} - e^{s/2}]$

converges for any s since finite limits.

$X(s) = -\frac{e^{-s/2}}{s} [1 - e^s]; \text{Re}\{s\} > \infty$

po-axis in ROC

b) $x(t) = e^{-|t|} = e^t u(-t) + e^{-t} u(t)$

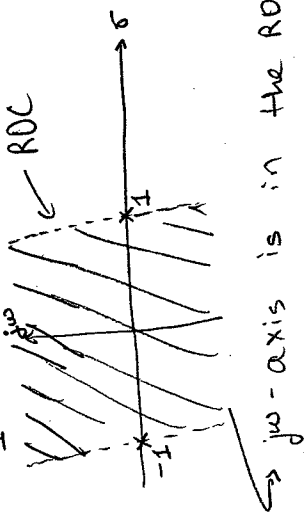
Using table, $\text{Re}\{s\} < -1$ $\text{Re}\{s\} > -1$

$e^{-at} u(t) \xrightarrow{\text{Re}\{s\} > -a} \frac{1}{s+a}$; $\text{Re}\{s\} > -a$

$-e^{-at} u(-t) \xrightarrow{\text{Re}\{s\} < -a} \frac{1}{s+a}$; $\text{Re}\{s\} < -a$

$\therefore X(s) = \frac{1}{s-1} + \frac{1}{s+1} = \frac{-2}{s^2-1}$

ROC: $R_1 \cap R_2 \Rightarrow -1 < \text{Re}\{s\} < 1$



c) $x(t) = e^{2t} \cos(4\pi t) u(t)$

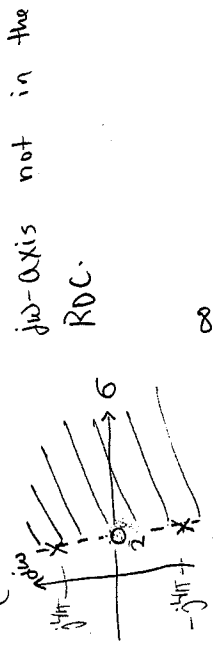
$x(t) = e^{2t} \left[\frac{1}{2} e^{j4\pi t} + \frac{1}{2} e^{-j4\pi t} \right] u(t)$

$x(t) = \left[\frac{1}{2} e^{t(2+j4\pi)} + \frac{1}{2} e^{t(2-j4\pi)} \right] u(t)$

$X(s) = \frac{1/2}{s-2-j4\pi} + \frac{1/2}{s-2+j4\pi}$

$= \frac{1}{2} \left[\frac{s-2+j4\pi + s-2-j4\pi}{(s-2)^2 + 16\pi^2} \right]$

$X(s) = \frac{s-2}{(s-2)^2 + 16\pi^2}; \text{Re}\{s\} > 2$



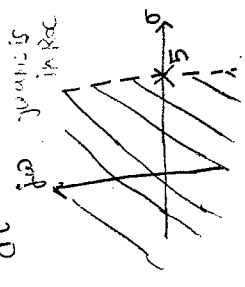
d) $x(t) = e^{5t} u(t); X(s) = \int_0^\infty e^{-(s-5)t} dt$

$X(s) = \frac{1}{s-5}; \text{Re}\{s\} > 5$

$\text{jw-axis not in ROC}$

e) $x(t) = e^{5t} u(-t); X(s) = \int_{-\infty}^0 e^{-(s-5)t} dt$

$X(s) = \frac{-1}{s-5}; \text{Re}\{s\} < 5$



⑤ i. $x(t) = e^{-2t} u(t) \xleftrightarrow{\mathcal{L}} X(s) = \frac{1}{s+2}, \text{Re}\{s\} > -2$

$h(t) = u(t) \xleftrightarrow{\mathcal{L}} H(s) = \frac{1}{s}, \text{Re}\{s\} > 0$

$Y(s) = H(s)X(s) = \frac{1}{s} \cdot \frac{1}{s+2} = \frac{1/2}{s} - \frac{1/2}{s+2}, \text{ROC contains } \text{Re}\{s\} > 0$

$y(t) = \frac{1}{2} u(t) - \frac{1}{2} e^{-2t} u(t)$

ii. $x(t) = e^{-2t} u(t) \xleftrightarrow{\mathcal{L}} X(s) = \frac{1}{s+2}, \text{Re}\{s\} > -2$

$h(t) = e^{-3t} u(t) \xleftrightarrow{\mathcal{L}} H(s) = \frac{1}{s+3}, \text{Re}\{s\} > -3$

$Y(s) = H(s)X(s) = \frac{1}{s+2} \cdot \frac{1}{s+3} = \frac{1}{s+2} - \frac{1}{s+3}, \text{ROC contains } \text{Re}\{s\} > -2$

$y(t) = e^{-2t} u(t) - e^{-3t} u(t)$

iii. $x(t) = u(t) \xleftrightarrow{\mathcal{L}} X(s) = \frac{1}{s}, \text{Re}\{s\} > 0$

$h(t) = \cos(2\pi t) u(t) \xleftrightarrow{\mathcal{L}} H(s) = \frac{s}{s^2 + (2\pi)^2}, \text{Re}\{s\} > 0$

$Y(s) = H(s)X(s) = \frac{1}{s^2 + (2\pi)^2}, \text{ROC contains } \text{Re}\{s\} > 0$

∴ since $\sin(\omega_0 t) u(t) \xleftrightarrow{\mathcal{L}} \frac{\omega_0}{s^2 + \omega_0^2}, \text{Re}\{s\} > 0$

$y(t) = \frac{1}{2\pi} \sin(2\pi t) u(t)$

iv. $x(t) = \cos(2\pi t) u(t) \xleftrightarrow{\mathcal{L}} X(s) = \frac{s}{s^2 + (2\pi)^2}, \text{Re}\{s\} > 0$

$h(t) = \delta(t-1) + \delta(t-.5) \xleftrightarrow{\mathcal{L}} H(s) = e^{-s} + e^{-s/2}, \text{all } s$

$Y(s) = H(s)X(s) = \frac{s}{s^2 + (2\pi)^2} e^{-s} + \frac{s}{s^2 + (2\pi)^2} e^{-s/2}, \text{ROC contains } \text{Re}\{s\} > 0$

$y(t) = \cos(2\pi(t-1)) u(t-1) + \cos(2\pi(t-.5)) u(t-.5)$

v. $x(t) = \cos(2\pi t) u(t) \xleftrightarrow{\mathcal{L}} X(s) = \frac{s}{s^2 + (2\pi)^2}, \text{Re}\{s\} > 0$

$h(t) = \cos(2\pi t) u(t) \xleftrightarrow{\mathcal{L}} H(s) = \frac{s}{s^2 + (2\pi)^2}, \text{Re}\{s\} > 0$

$Y(s) = X(s)H(s) = \frac{s^2}{(s^2 + (2\pi)^2)(s^2 + (2\pi)^2)} = \frac{j/8\pi}{s + j2\pi} + \frac{1/4}{(s + j2\pi)^2} - \frac{j/8\pi}{s - j2\pi} + \frac{1/4}{(s - j2\pi)^2},$

$y(t) = \frac{1}{8\pi} e^{-j2\pi t} u(t) + \frac{1}{4} t e^{-j2\pi t} u(t) - \frac{j}{8\pi} e^{j2\pi t} u(t) + \frac{1}{4} t e^{j2\pi t} u(t) \text{ ROC contains } \text{Re}\{s\} > 0$

$= \frac{1}{4\pi} \sin(2\pi t) u(t) + \frac{1}{2} \cos(2\pi t) t u(t)$

sv detail

$$\frac{S^2}{(s+j2\pi)(s-j2\pi)(s+j2\pi)(s-j2\pi)} = \frac{S^2}{(s+j2\pi)^2 (s-j2\pi)^2} = Y(s)$$

$$Y(s) = \frac{A}{s+j2\pi} + \frac{B}{(s+j2\pi)^2} + \frac{C}{s-j2\pi} + \frac{D}{(s-j2\pi)^2}$$

$$(s+j2\pi)^2 Y(s) \Big|_{s=-j2\pi} = B = \frac{(-j2\pi)^2}{(-j2\pi-j2\pi)^2} = \frac{(2\pi)^2}{(4\pi)^2} = 1/4$$

$$(s-j2\pi)^2 Y(s) \Big|_{s=j2\pi} = D = \frac{(+j2\pi)^2}{(+j2\pi-j2\pi)^2} = 1/4$$

= 0 for $s = -2\pi j$

$$\frac{d}{ds} [(s+j2\pi)^2 Y(s)] = \frac{d}{ds} \left[A(s+j2\pi) + \frac{d}{ds} \left[\frac{B}{1} + \frac{C(s+j2\pi)^2}{s-j2\pi} + \frac{D(s+j2\pi)^2}{(s-j2\pi)^2} \right] \right]$$

$s = -2\pi j$

$$= A = \frac{d}{ds} \left[\frac{S^2}{(s-j2\pi)^2} \right] \Big|_{s=-j2\pi} = \frac{-2S^2(s-j2\pi)^{-3}}{+2S(s-j2\pi)^{-2}} \Big|_{s=-j2\pi}$$

$$\frac{d}{ds} [(s-j2\pi)^2 Y(s)] \Big|_{s=j2\pi} = C$$

$$= \frac{S}{(s-j2\pi)^2} \left[\frac{-2S}{s-j2\pi} + 2 \right]$$

$$= \frac{-j2\pi}{(-j2\pi)^2} \cdot \left[\frac{j4\pi}{-j2\pi} + 2 \right] = \frac{-j}{-8\pi} \left[\frac{-j}{-8\pi} \right]$$

$$= \frac{j}{8\pi} = A$$

$$= \frac{S}{(s+2\pi j)^2} \left[2 - \frac{2S}{s+2\pi j} \right] \Big|_{s=j2\pi} = \frac{-j}{8\pi}$$

8/10

⑥ $\frac{d^2 y}{dt^2} + 300 \frac{dy}{dt} + 2 \times 10^4 y(t) = 10^3 x(t)$

$$\frac{dy}{dt} \xrightarrow{\mathcal{L}} sY(s) - y(0^-) = sY(s) - 1$$

$$\frac{d^2 y}{dt^2} \xrightarrow{\mathcal{L}} s^2 Y(s) - s y(0^-) - \dot{y}(0^-) = s^2 Y(s) - s + 2$$

$$s^2 Y(s) - s + 2 + 300sY(s) - 300 + 2 \times 10^4 Y(s) = \frac{1000}{s}$$

[note $x(t) = u(t) \xrightarrow{\mathcal{L}} \frac{1}{s}$]

$$Y(s) [s^2 + 300s + 2 \times 10^4] = \frac{1000}{s} + s + 298$$

$$Y(s) = \frac{s^2 + 298s + 1000}{(s^2 + 300s + 2 \times 10^4)s} \xrightarrow{(s+100)(s+200)}$$

Partial Fraction Decomposition:

$$Y(s) = \frac{A}{s} + \frac{B}{s+100} + \frac{C}{s+200}$$

$$A(s+100)(s+200) + Bs(s+200) + Cs(s+100) = s^2 + 298s + 1000$$

$$s=0 \Rightarrow A(100)(200) = 1000 \rightarrow A = 1/20$$

$$s=-100 \Rightarrow B(-100)(100) = -18800 \rightarrow B = +47/25$$

$$s=-200 \Rightarrow C(-200)(-100) = -18600 \rightarrow C = -93/100$$

9/10

$$Y(s) = \frac{1/20}{s} + \frac{47/25}{s+100} - \frac{93/100}{s+200}$$

$$\therefore y(t) = \left[\frac{1}{20} + \frac{47}{25} e^{-100t} - \frac{93}{100} e^{-200t} \right] u(t)$$

$$y(t) = \left[0.05 + 1.88 e^{-100t} - 0.93 e^{-200t} \right] u(t)$$