

CS-184: Computer Graphics

Lecture #25: Modeling w/ Points

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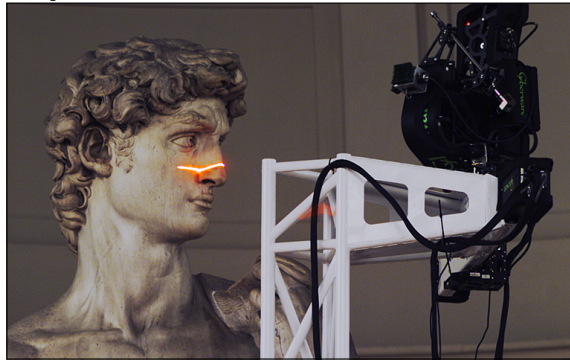
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Today

- Points as a graphics primitive

A Thought Experiment

- Laser scanners
 - Millions to *billions* of points
- Typical image
 - At most a few million pixels
- More points than pixels...



3

“Point-Based Graphics”

- Surfaces represented only by points
 - Maybe normals also
 - No topology
- How can we do
 - Rendering
 - Modeling operations
 - Simulation

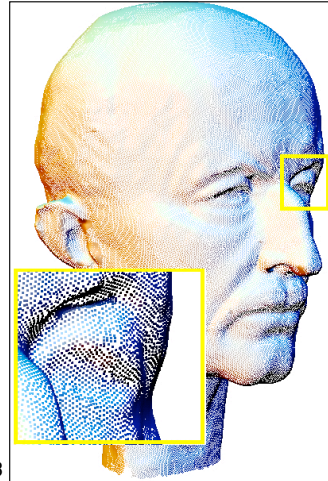
4

Rendering

- For each point draw a little “splat”
 - Use associated normal for shading
 - Possibly apply texture

If “splats” are small compared to spacing then gaps result

Splatting too many points would waste time

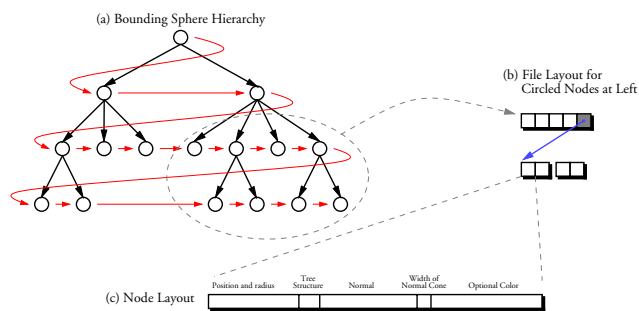


Ohtake, et al., SIGGRAPH 2003

5

Rendering

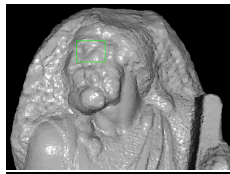
- “QSplat” algorithm
 - Build hierarchical tree of the points
 - Use bounding spheres to estimate size of clusters
 - Render clusters based on screen size
 - Use cluster-normals for internal nodes



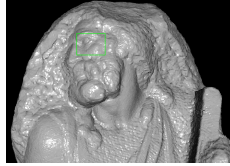
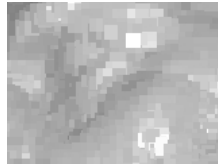
From Rusinkiewicz and Levoy, SIGGRAPH 2000.

6

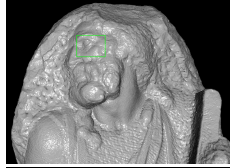
Rendering



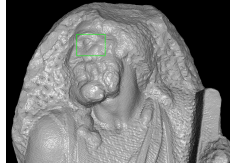
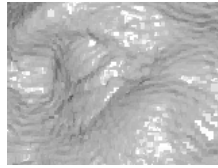
15-pixel cutoff
130,712 points
132 ms



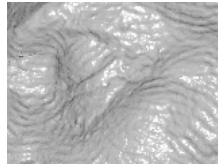
10-pixel cutoff
259,975 points
215 ms



5-pixel cutoff
1,017,149 points
722 ms

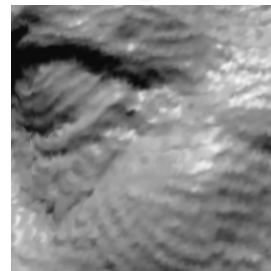
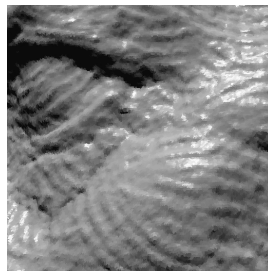
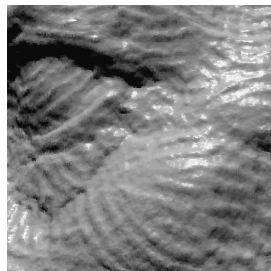
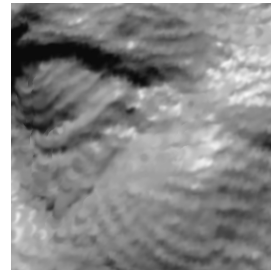
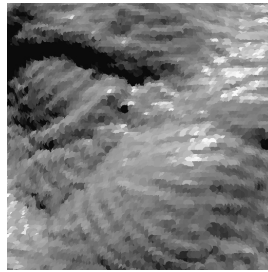
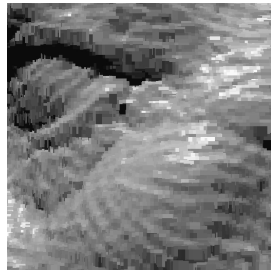


1-pixel cutoff
14,855,967 points
8308 ms



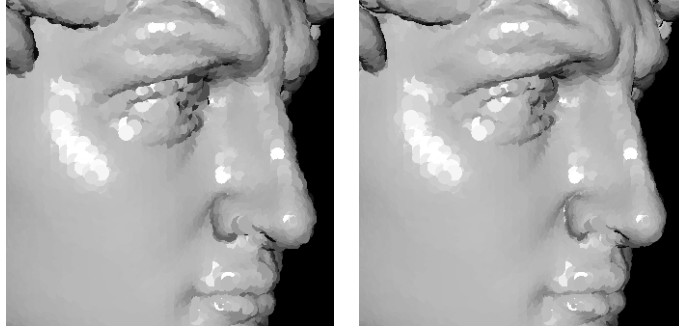
From Rusinkiewicz and Levoy, SIGGRAPH 2000. ⁷

Rendering



From Rusinkiewicz and Levoy, SIGGRAPH 2000. ⁸

Rendering

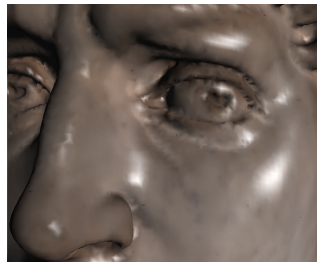


From Rusinkiewicz and Levoy, SIGGRAPH 2000. ⁹

Rendering



(a)
Points



(b)
Polygons – same number of primitives as (a)
Same rendering time as (a)



(c)
Polygons – same number of vertices as (a)
Twice the rendering time of (a)

From Rusinkiewicz and Levoy, SIGGRAPH 2000. ¹⁰

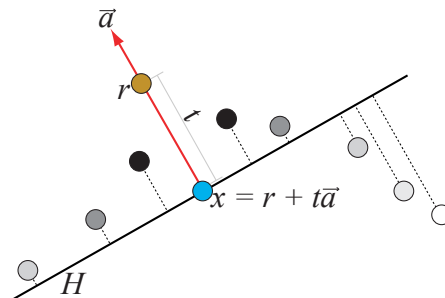
Defining a Surface

- Two related methods
 - Surface is a point attractor
 - Point-set surfaces
 - Implicit surface
 - Multi-level Partition of Unity Implicits
 - Implicit Moving Least-Squares

11

Point-Set Surfaces

- Surface is the attractor of a repeated projection process
 - Find nearby points
 - Fit plane (weighted)
 - Project into plane
 - Repeat
- Does it converge?
- How to weight points?



From Amenta and Kil, SIGGRAPH 2004.

12

Point-Set Surfaces

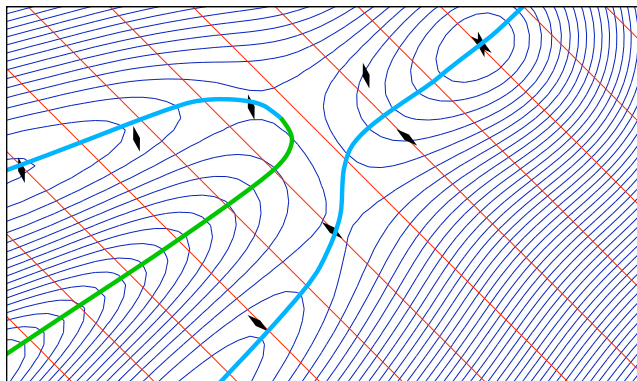
Defining Point-Set Surfaces

Nina Amenta Yong J. Kil

Center for Image Processing and Integrated Computing, U C Davis

13

Point-Set Surfaces



From Amenta and Kil, SIGGRAPH 2004.

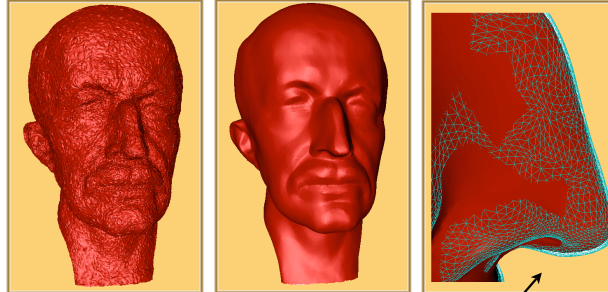
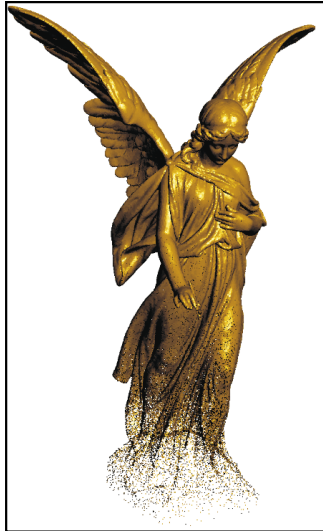
Does this give us a good surface?

New “robust” methods exist for sharp features

14

Point-Set Surfaces

- Some examples



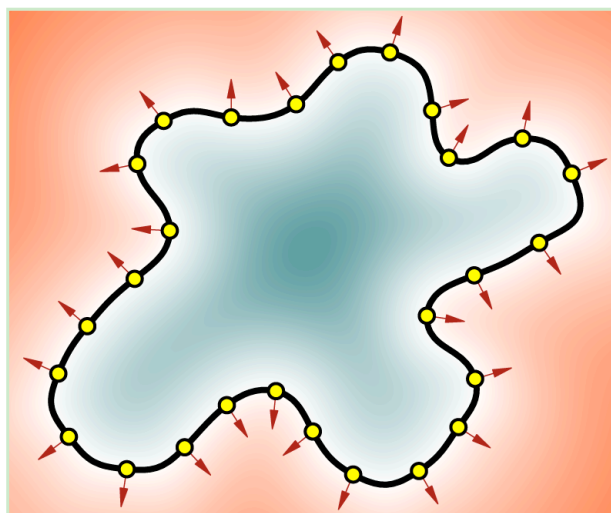
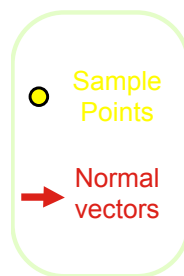
Note shrinkage

From Fleichman, Thesis, 2003.

15

Implicit Moving Least-Squares

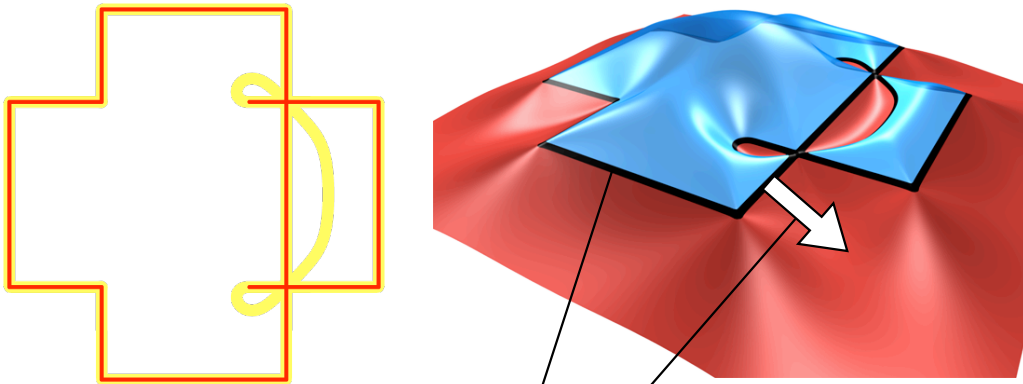
- Define a scalar function that is zero passing through all the points



From Shen, et al., SIGGRAPH, 2004.

16

Implicit Moving Least-Squares



Function is zero on boundary
Decreases in outward direction

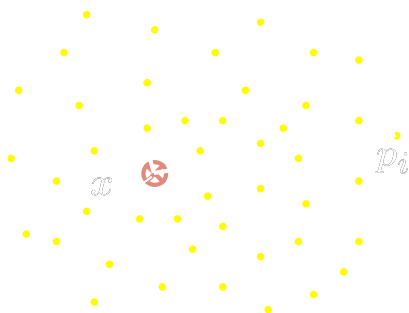
From Shen, et al., SIGGRAPH, 2004.

17

Moving Least-Square Interpolation

Standard Least Square

$$\begin{bmatrix} b^T(p_1) \\ \vdots \\ b^T(p_N) \end{bmatrix} c = \begin{bmatrix} \phi_1 \\ \vdots \\ \phi_N \end{bmatrix}$$



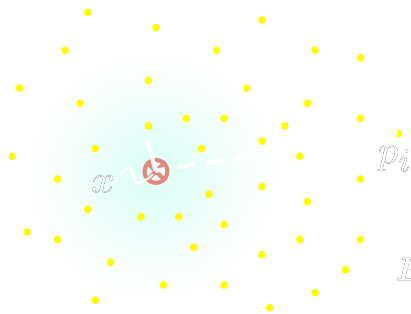
$$B^T B c = B^T \phi$$

18

Moving Least-Square Interpolation

Moving Least Square

$$\begin{bmatrix} w(x, p_1) \\ \vdots \\ w(x, p_N) \end{bmatrix} \begin{bmatrix} b^T(p_1) \\ \vdots \\ b^T(p_N) \end{bmatrix} c = \begin{bmatrix} w(x, p_1) \\ \vdots \\ w(x, p_N) \end{bmatrix} \begin{bmatrix} \phi_1 \\ \vdots \\ \phi_N \end{bmatrix}$$



$$w(r) = \frac{1}{(r^2 + \epsilon^2)}$$

$$B^T (W(x))^2 B c(x) = B^T (W(x))^2 \phi$$

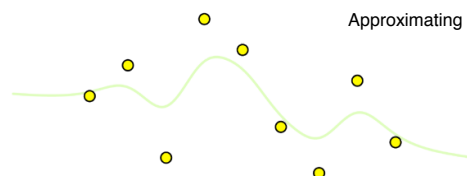
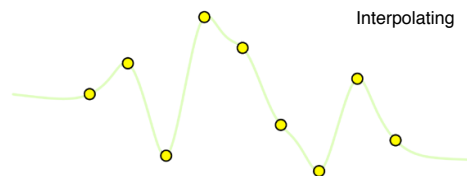
19

Moving Least-Square Interpolation

Least Square

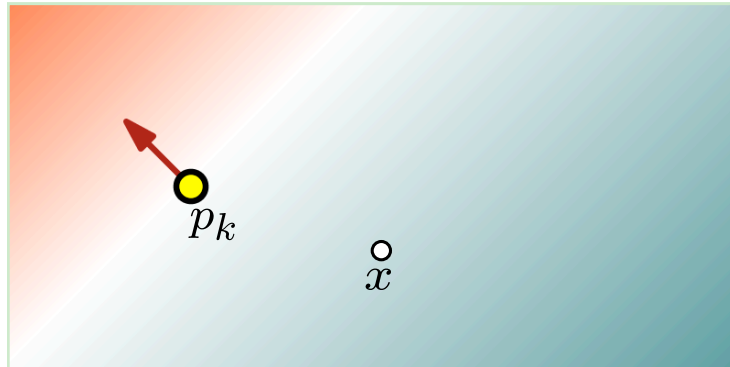


Moving Least Square



20

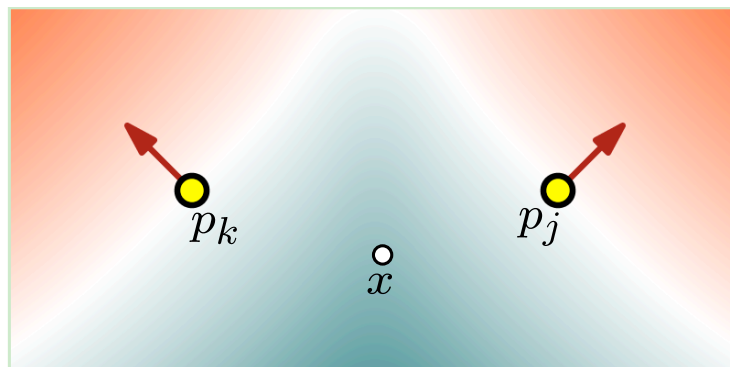
Interpolating Functions



$$\begin{aligned}
 S_k(\mathbf{x}) &= \phi_k + (\mathbf{x} - \mathbf{p}_k)^\top \hat{\mathbf{n}}_k \\
 &= \psi_{0k} + \psi_{xk}x + \psi_{yk}y + \psi_{zk}z
 \end{aligned}$$

21

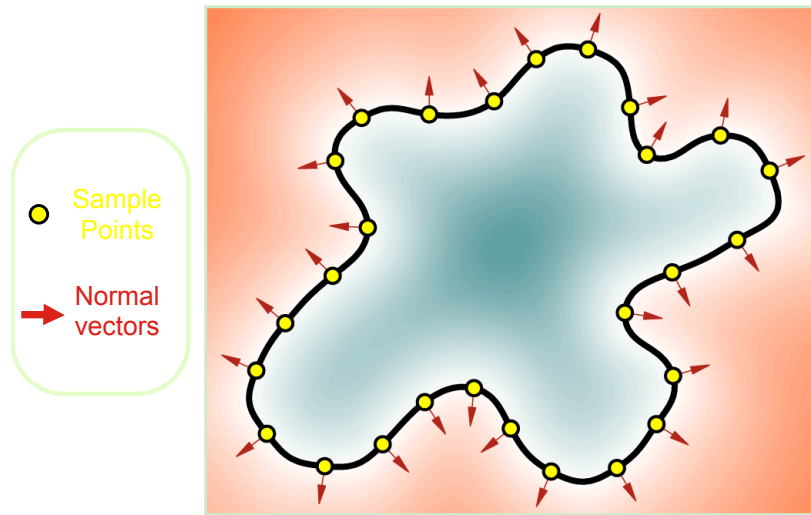
Interpolating Functions



$$\begin{bmatrix} w(\mathbf{x}, \mathbf{p}_1) \\ \vdots \\ w(\mathbf{x}, \mathbf{p}_i) \end{bmatrix} \mathbf{c}_1 = \begin{bmatrix} w(\mathbf{x}, \mathbf{p}_1) \\ \vdots \\ w(\mathbf{x}, \mathbf{p}_N) \end{bmatrix} \begin{bmatrix} S_1(\mathbf{x}) \\ \vdots \\ S_N(\mathbf{x}) \end{bmatrix}$$

22

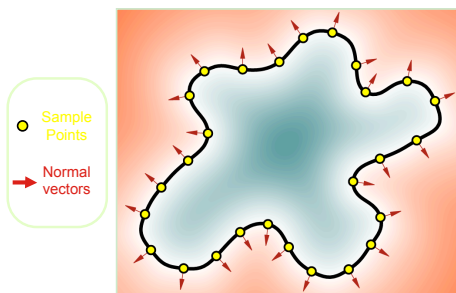
Implicit Moving Least-Squares



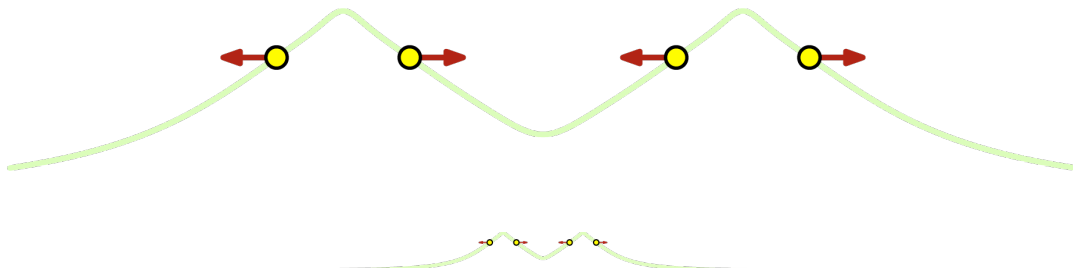
From Shen, et al., SIGGRAPH, 2004.

23

Implicit Moving Least-Squares

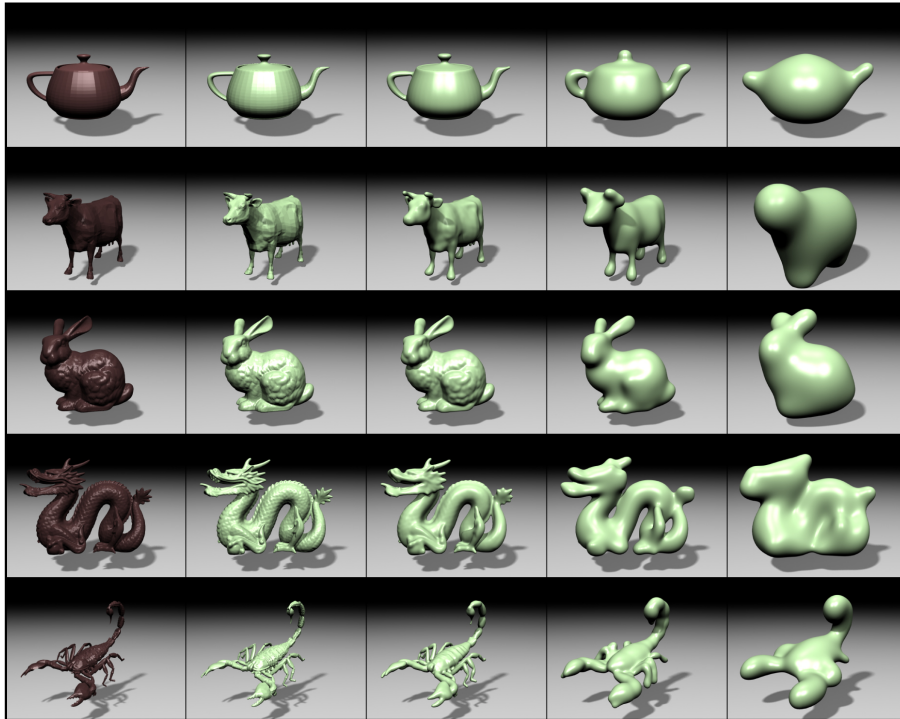


Proof of good behavior in
Kolluri SODA 2005

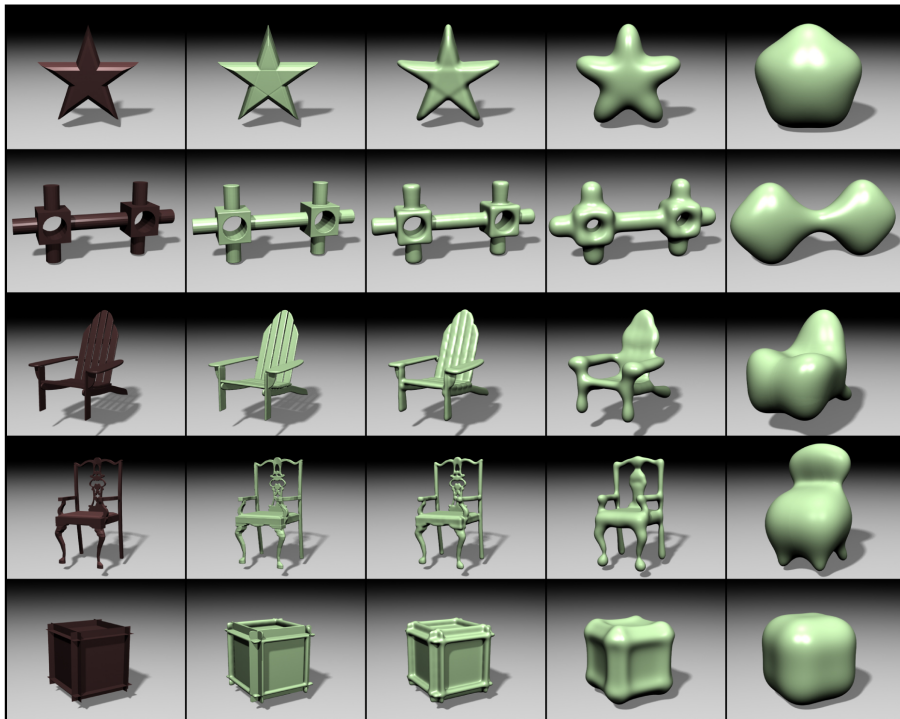


From Shen, et al., SIGGRAPH, 2004.

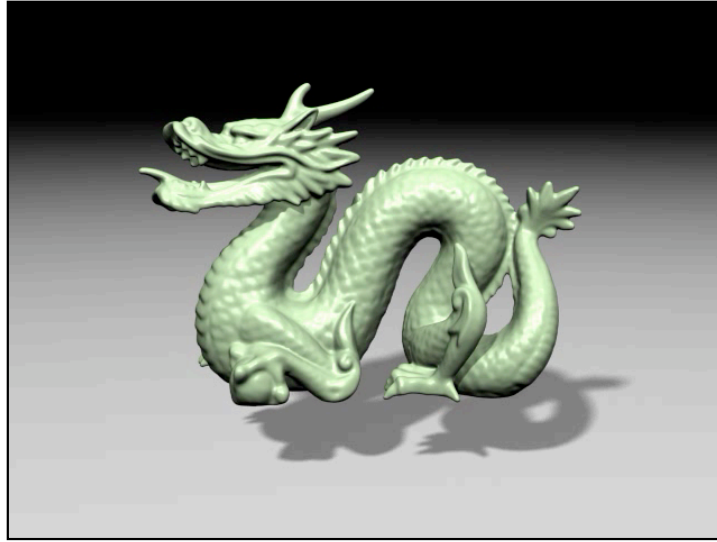
24



From Shen, et al., SIGGRAPH, 2004.
 (Actually based on polygon constraints... but same idea.)

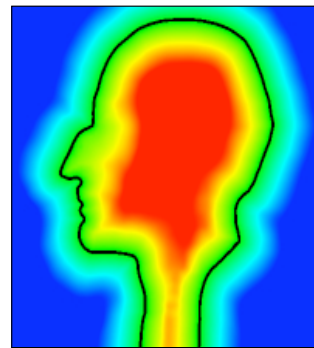
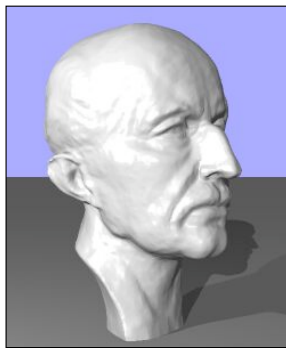
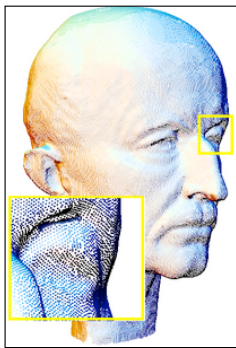


From Shen, et al., SIGGRAPH, 2004.
 (Actually based on polygon constraints... but same idea.)



From Shen, et al., SIGGRAPH, 2004.
(Actually based on polygon constraints... but same idea.)

Partition of Unity Method



Ohtake, et al., SIGGRAPH 2003

Partition of Unity is a special case of Moving Least-Squares

Partition of Unity Method

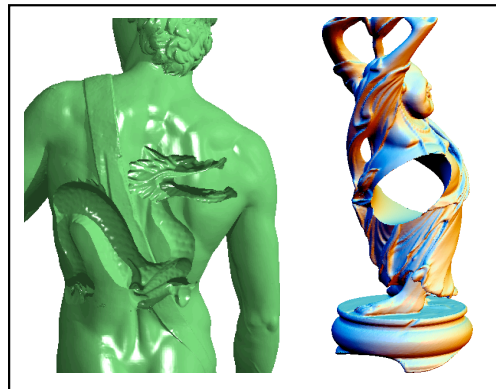


Ohtake, et al., SIGGRAPH 2003

29

Editing Operations

- Implicit function can be
 - Combined w/ booleans
 - Warped
 - Offset
 - Composed
 - And more...



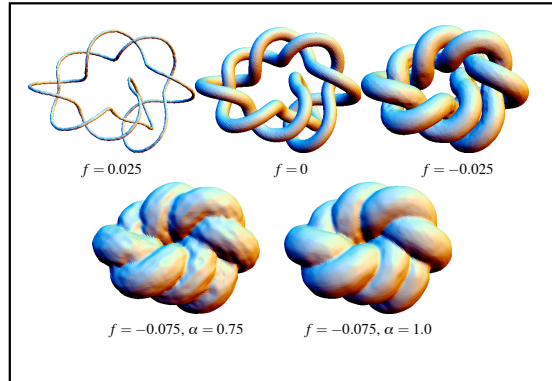
Ohtake, et al., SIGGRAPH 2003

30

Editing Operations

- Implicit function can be

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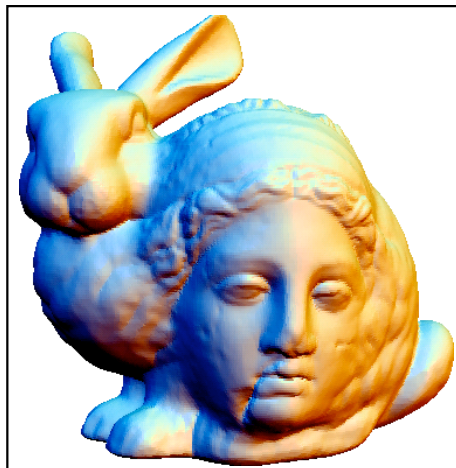
Ohtake, et al., SIGGRAPH 2003

31

Editing Operations

- Implicit function can be

- Combined w/ booleans
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- Composed
- And more...

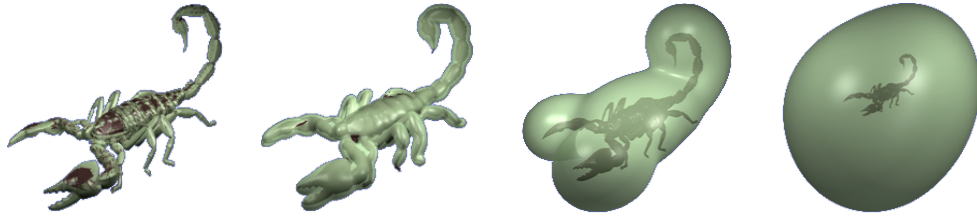


Ohtake, et al., SIGGRAPH 2003

32

Smoothing

Simple Smoothing



Adjustment Smoothing

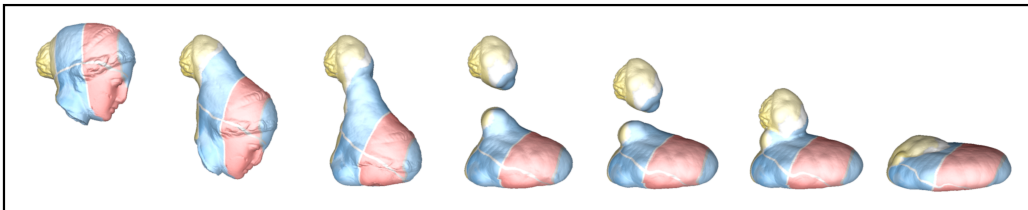


From Shen, et al., SIGGRAPH, 2004.

33

Point-Based Simulation

- MLS originated in mechanics literature
- Natural use in graphics for animation



From Mueller, et al., SCA, 2004.

34

Point-Based Simulation



**Point Based Animation
of Elastic, Plastic and
Melting Objects**

From Mueller, et al., SCA, 2004.

35

Suggested Reading

- “QSplat: A Multiresolution Point Rendering System for Large Meshes” by Szymon Rusinkiewicz and Marc Levoy, SIGGRAPH 2000.
- “Multi-level Partition of Unity Implicits” by Yutaka Ohtake and colleagues, SIGGRAPH 2003.
- “Point Based Animation of Elastic, Plastic and Melting Objects” by Mueller and colleagues, SCA 2004.
- “Defining point-set surfaces” by Nina Amenta and Yong Joo Kil, SIGGRAPH 2004.
- “Interpolating and Approximating Implicit Surfaces from Polygon Soup” by Chen Shen, James O’Brien, and Jonathan Shewchuk, SIGGRAPH 2004.

36