Lecture #30: Operational Semantics, Part III

Classes and Functions as Values

- Although the language does not allow programmers to treat classes as first-class values, the semantics is free to do so.
- Thus, we represent a class T with attributes $a_1, \ldots$ a

$$class(T) = (a_1 = e_1, \ldots, a_m = e_m)$$

- Here, the e_i are either literal expressions or function definitions.
- Similarly, the semantics associates a function value with each function, even though programmers cannot manipulate functions as values:

$$v = (x_1, \ldots, x_n, y_1 = e_1, \ldots, y_k = e_k, b_{body}, E_f)$$

- Here, the x_i are parameter names and the y_i are the local variables (with initializers e_i.)

Function Invocation

Now things get complicated:

$$\frac{\begin{array}{c} S_0(E(f)) = (x_1, \ldots, x_n, y_1 = e'_1, \ldots, y_k = e'_k, b_{body}, E_f) \\ \hline n, k \geq 0 \\ G, E, S_0 \vdash e_1 : v_1, S_1, \_ \\ \vdots \\ G, E, S_{n-1} \vdash e_n : v_n, S_n, \_ \\ \hline l_{x1}, \ldots, l_{xn}, l_{y1}, \ldots, l_{yk} = newloc(S_n, n+k) \\ E' = E_f[l_{x1}/x_1] \ldots [l_{xn}/x_n][l_{y1}/y_1] \ldots [l_{yk}/y_k] \\ \hline G, E', S_n \vdash e'_1 : v'_1, S_n, \_ \\ \vdots \\ G, E', S_n \vdash e'_k : v'_k, S_n, \_ \\ \hline S_{n+1} = S_n[v_1/l_{x1}] \ldots [v_n/l_{xn}][v'_1/l_{y1}] \ldots [v'_k/l_{yk}] \\ \hline G, E', S_{n+1} \vdash b_{body} : \_, S_{n+2}, R \\ R' = \begin{cases} None, & \text{if } R \text{ is } \_ \\ R, & \text{otherwise} \end{cases} \end{array}}{G, E, S_0 \vdash f(e_1, \ldots, e_n) : R', S_{n+2}, \_} \quad [\text{INVOKE}]$$

- Evaluate Function
- Evaluate Actuals
- Allocate New Locations for Parameters and Locals
- Evaluate Initializers
- Assign Params. and Locals
- Evaluate Body
- And Capture Return Value

Function Invocation: Discussion

- In the rules for evaluating local definitions:

$$G, E', S_n \vdash e'_1 : v'_1, S_n, \_$$
$$\vdots$$
$$G, E', S_n \vdash e'_k : v'_k, S_n, \_$$

Why does the state remain S_n?

- What would happen if we changed the steps for allocating new variables to

$$\frac{\begin{array}{c} G, E, S_n \vdash e'_1 : v'_1, S_n, \_ \\ \vdots \\ G, E, S_n \vdash e'_k : v'_k, S_n, \_ \end{array}}{\begin{array}{c} l_{x1}, \ldots, l_{xn}, l_{y1}, \ldots, l_{yk} = newloc(S_n, n+k) \\ E' = E_f[l_{x1}/x_1] \ldots [l_{xn}/x_n][l_{y1}/y_1] \ldots [l_{yk}/y_k] \end{array}}$$

Evaluate Initializers

Allocate New Locations for Parameters and Locals

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Evaluate Initializers

Allocate New Locations for Parameters and Locals

? Nothing. The effect is the same.

Function Invocation: Discussion (II)

- Consider the lines:

$$S_0(E(f)) = (x_1, \ldots, x_n, y_1 = e'_1, \ldots, y_k = e'_k, b_{body}, E_f) \quad \text{Evaluate Function}$$
$$\vdots$$
$$E' = E_f[l_{x1}/x_1] \ldots [l_{xn}/x_n][l_{y1}/y_1] \ldots [l_{yk}/y_k] \quad \text{Parameters and Locals}$$
$$\vdots$$
$$G, E', S_{n+1} \vdash b_{body} : \_, S_{n+2}, R \quad \text{Evaluate Body} \ \vdots$$

$$\overline{G, E, S_0 \vdash f(e_1, \ldots, e_n) : R', S_{n+2}, \_} \quad [\text{INVOKE}]$$

- The environment for evaluating the body, E', is *not* an extension of E, but rather of E_f, the environment that is part of the function's value.
- This is in keeping with the rule you first saw in CS61A: a function value's parent frame is the one in which the function definition is evalated, not the one in which the call is evaluated.

Method Dispatching

Method dispatching, as in `x.f(3)`, is unsurprisingly close to function invocation.

$$G, E, S \vdash e_0 : v_0, S_0, \_$$ *Evaluate Object*

$$v_0 = X(a_1 = l_1, \ldots, f = l_f, \ldots, a_m = l_m)$$ *Find f in Class Value*

$$S_0(l_f) = (x_0, x_1, \ldots, x_n, y_1 = e'_1, \ldots, y_k = e'_k, b_{body}, E_f)$$

...Evaluate Parameters as for Function Calls...

$$l_{x0}, l_{x1}, \ldots, l_{xn}, l_{y1}, \ldots, l_{yk} = newloc(S_n, n+k+1)$$

$$E' = E_f[l_{x0}/x_0] \ldots [l_{xn}/x_n][l_{y1}/y_1] \ldots [l_{yk}/y_k]$$

...Evaluate Initializers for Locals as for Function Calls...

$$S_{n+1} = S_n[v_0/l_{x0}] \ldots [v_n/l_{xn}][v'_1/l_{y1}] \ldots [v'_k/l_{yk}]$$ *Assign Params. and Locals*

$$G, E', S_{n+1} \vdash b_{body} : \_, S_{n+2}, R$$ *Evaluate Body*

$$R' = \begin{cases} None, & \text{if } R \text{ is } \_ \\ R, & \text{otherwise} \end{cases}$$ *And Capture Return Value*

$$G, E, S \vdash e_0.f(e_1, \ldots, e_n) : R', S_{n+2}, \_$$ [DISPATCH]

Function Definitions

- Function definitions provide values for local definitions (nested functions) and global functions.
- In the [INVOKE] and [DISPATCH] rules, these values then get assigned to the local names (denoted y_i in those rules).

$$\frac{\begin{array}{c} g_1, \ldots, g_L: \text{ variables declared with `\textbf{global}' in } f \\ y_1 = e_1, \ldots, y_k = e_k: \text{ local variables and functions in } f \\ E_f = E[G(g_1)/g_1] \ldots [G(g_L)/g_L] \\ v = (x_1, \ldots, x_n, y_1 = e_1, \ldots, y_k = e_k, b_{body}, E_f) \end{array}}{G, E, S \vdash \texttt{def } f(x_1 : T_1, \ldots, x_n : T_n) \; [\![\texttt{->} \; T_0]\!]^? : b : v, S, \_} \quad \text{[FUNC-METHOD-DEF]}$$

- This is where we capture the parent local environment, E, in which f is defined.

Native Functions

- Certain functions are predefined (`print`, `len`, `input`), and do not have normal bodies.
- For these, we denote the function bodies as, e.g., `native len` and define special rules for these particular bodies.
- Assume that the native bodies expect a parameter named `val` (if they have one).
- Then we can define, e.g.,

$$\frac{\begin{array}{c} S(E(\texttt{val})) = v \\ v = int(i) \textsf{ or } v = bool(b) \textsf{ or } v = str(n, s) \end{array}}{G, E, S \vdash \texttt{native print} : \_, S, None} \quad [\text{PRINT}]$$

$$\frac{\begin{array}{c} S(E(\texttt{val})) = v \\ v = [l_1, l_2, \ldots, l_n] \\ n \geq 0 \end{array}}{G, E, S \vdash \texttt{native len} : \_, S, int(n)} \quad [\text{LEN-LIST}]$$

and others.

Accessing Attributes of Classes

The notation from the first slide provides us with a description of a value and its attributes:

$$\frac{\begin{array}{c} G, E, S_0 \vdash e : v_1, S_1, \_ \\ v_1 = X(a_1 = l_1, \ldots, id = l_{id}, \ldots, a_m = l_m) \\ v_2 = S_1(l_{id}) \end{array}}{G, E, S_0 \vdash e.id : v_2, S_1, \_} \quad [\text{ATTR-READ}]$$

$$\frac{\begin{array}{c} G, E, S_0 \vdash e_2 : v_r, S_1, \_ \\ G, E, S_1 \vdash e_1 : v_l, S_2, \_ \\ v_l = X(a_1 = l_1, \ldots, id = l_{id}, \ldots, a_m = l_m) \\ S_3 = S_2[v_r/l_{id}] \end{array}}{G, E, S_0 \vdash e_1.id = e_2 : \_, S_3, \_} \quad [\text{ATTR-ASSIGN-STMT}]$$

Q: In [ATTR-ASSIGN-STMT], what exactly happens when e_1 or e_2 have side effects?

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$$\frac{\begin{array}{c} G, E, S_0 \vdash e_2 : v_r, S_1, \_ \\ G, E, S_1 \vdash e_1 : v_l, S_2, \_ \\ v_l = X(a_1 = l_1, \ldots, id = l_{id}, \ldots, a_m = l_m) \\ S_3 = S_2[v_r/l_{id}] \end{array}}{G, E, S_0 \vdash e_1.id = e_2 : \_, S_3, \_} \quad [\text{ATTR-ASSIGN-STMT}]$$

Q: In [ATTR-ASSIGN-STMT], what exactly happens when e_1 or e_2 have side effects? **A:** e_2 is evaluated first, and therefore can affect the evaluation of e_1, but not vice-versa.

Creating Objects

$$class(T) = (a_1 = e_1, \ldots, a_m = e_m)$$

$$m \geq 1$$

T Must Be A Class

$$l_{a1}, \ldots, l_{am} = newloc(S, m)$$

Allocate Attributes

$$v_0 = T(a_1 = l_{ai}, \ldots, a_m = l_{am})$$

New Object Value

$$G, G, S \vdash e_1 : v_1, S, \_$$

$$\vdots$$

$$G, G, S \vdash e_m : v_m, S, \_$$

Evaluate Initializers in G

$$S_1 = S[v_1/l_{a1}] \ldots [v_m/l_{am}]$$

Initialize Attributes

$$l_{init} = l_{ai} \text{ such that } a_i = \texttt{\_\_init\_\_}$$

Get `__init__` method

$$S_1(l_{init}) = (x_0, y_1 = e'_1, \ldots, y_k = e'_k, b_{body}, E_f)$$

$$k \geq 0$$

$$l_{x0}, l_{y1}, \ldots, l_{yk} = newloc(S_1, k+1)$$

$$E' = E_f[l_{x0}/x_0][l_{y1}/y_1] \ldots [l_{yk}/y_k]$$

$$G, E, S_1 \vdash e'_1 : v'_1, S_1, \_$$

$$\vdots$$

$$G, E, S_1 \vdash e'_k : v'_k, S_1, \_$$

Call It On v_0

$$S_2 = S_1[v_0/l_{x0}][v'_1/l_{y1}] \ldots [v'_k/l_{yk}]$$

$$G, E', S_2 \vdash b_{body} : \_, S_3, \_$$

$$\overline{G, E, S \vdash T() : v_0, S_3, \_}$$

Starting Things Off: Programs

We start with an initial store and environment, containing just the pre-defined function.

$g_1 = e_1, \ldots, g_k = e_k$ are the global variable and function definitions in the program

P is the sequence of statements in the program

$$\frac{\begin{array}{c} l_{g1}, \ldots, l_{gk} = newloc(S_{init}, k) \\ G = G_{init}[l_{g1}/g_1] \ldots [l_{gk}/g_k] \\ G, G, S_{init} \vdash e_1 : v_1, S_{init}, \_ \\ \vdots \\ G, G, \emptyset \vdash e_k : v_k, S_{init}, \_ \\ S = S_{init}[v_k/l_{g1}] \ldots [v_k/l_{gk}] \\ G, G, S \vdash P : \_, S', \_ \end{array}}{\emptyset, \emptyset, \emptyset \vdash P : \_, S', \_} \quad [\text{PROGRAM}]$$

Initial Store and Environment

Here, we use the native body notation from previously.

$$G_{init} = \emptyset[l_{len}/len][l_{print}/print][l_{input}/input]$$

$$S_{init}(l_{print}) = (\texttt{val}, \texttt{native print}, \emptyset)$$

$$S_{init}(l_{len}) = (\texttt{val}, \texttt{native len}, \emptyset)$$

$$S_{init}(l_{input}) = (\texttt{native print}, \emptyset)$$