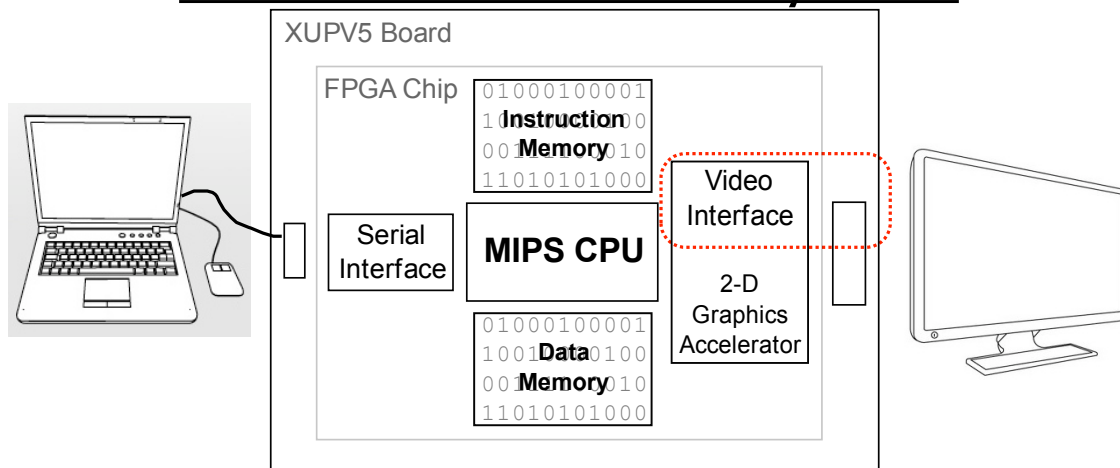


EECS150 - Digital Design

Lecture 12 - Video Interfacing

Feb 28, 2013
John Wawrzynek

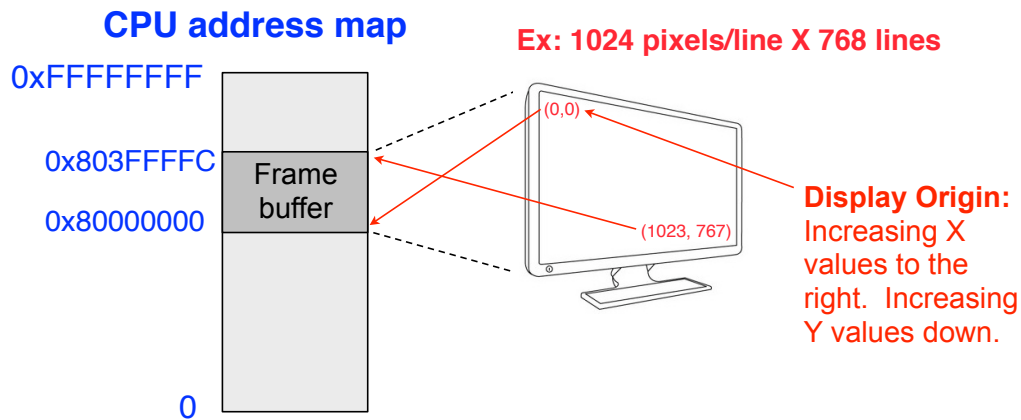
MIPS150 Video Subsystem



- Gives software ability to display information on screen.
- Equivalent to standard graphics cards:
 - Processor can directly write the display bit map
 - 2D Graphics acceleration

“Framebuffer” HW/SW Interface

- A range of memory addresses correspond to the display.
- CPU writes (using sw instruction) pixel values to change display.
- No synchronization required. Independent process reads pixels from memory and sends them to the display interface at the required rate.



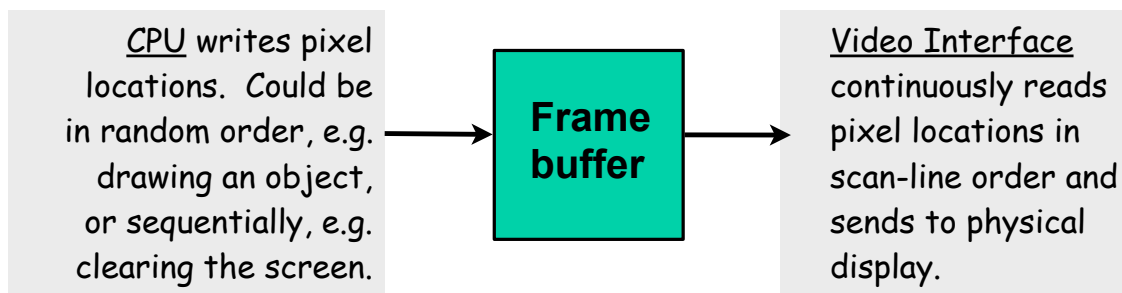
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Framebuffer Implementation

- Framebuffer like a simple dual-ported memory.
Two independent processes access framebuffer:



- How big is this memory and how do we implement it? For us:

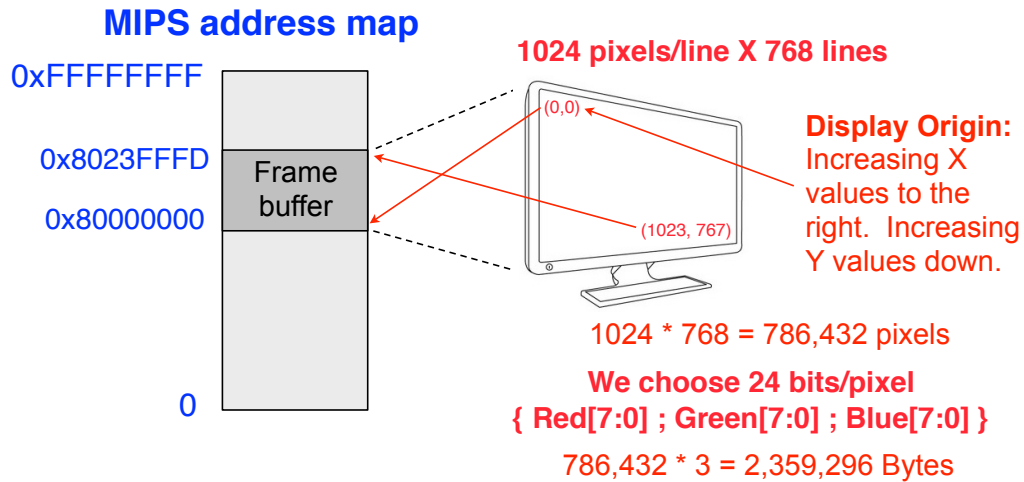
1024 x 768 pixels/frame x 24 bits/pixel

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Memory Mapped Framebuffer

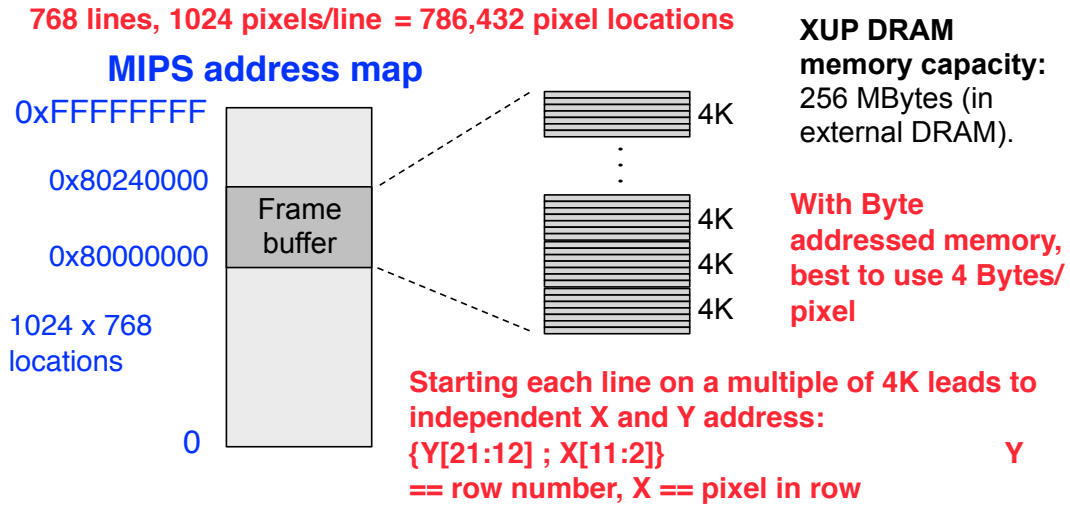


- Total memory bandwidth needed to support frame buffer?

Frame Buffer Implementation

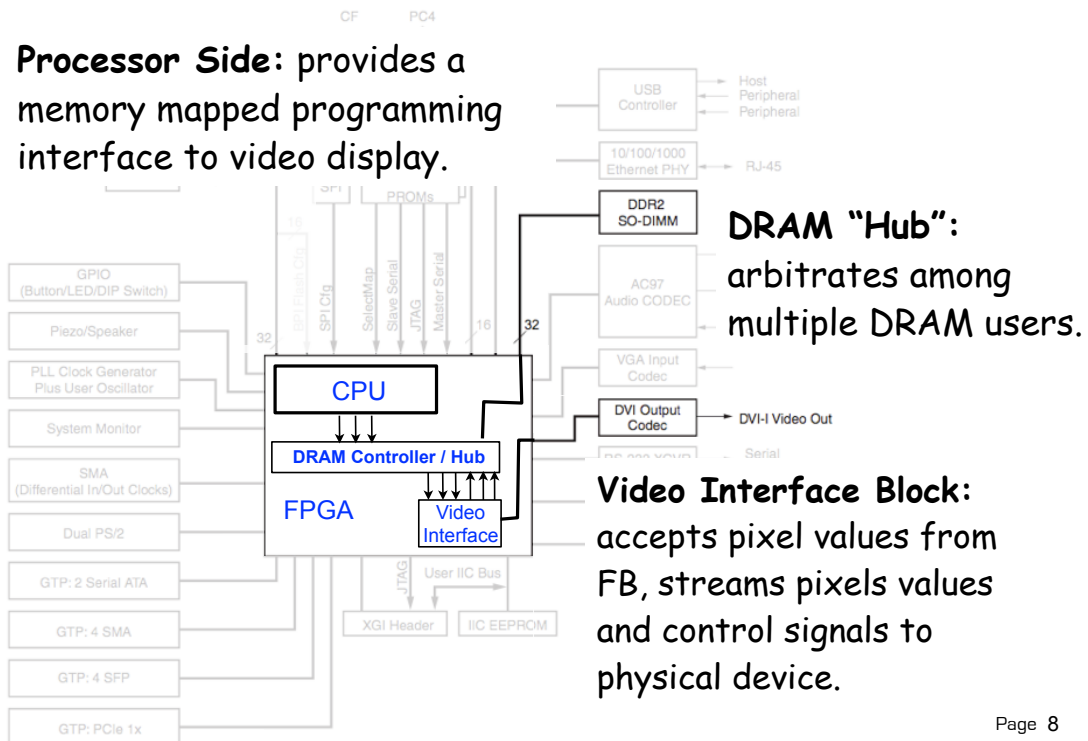
- Which XUP memory resource to use?
- Memory Capacity Summary:
 - LUT RAM
 - Block RAM
 - External SRAM
 - External DRAM
- DRAM bandwidth:

Framebuffer Details



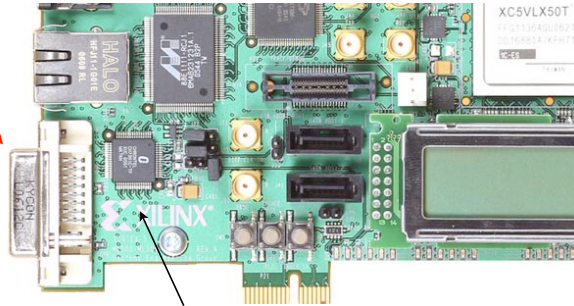
Frame Buffer Physical Interface

Processor Side: provides a memory mapped programming interface to video display.

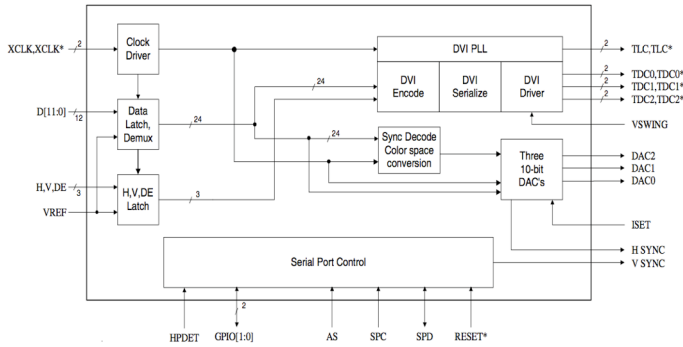


Physical Video Interface

DVI connector:
accommodates
analog and
digital formats



DVI Transmitter Chip, Chrontel 7301C.



Implements standard signaling voltage levels for video monitors. Digital to analog conversion for analog display formats.

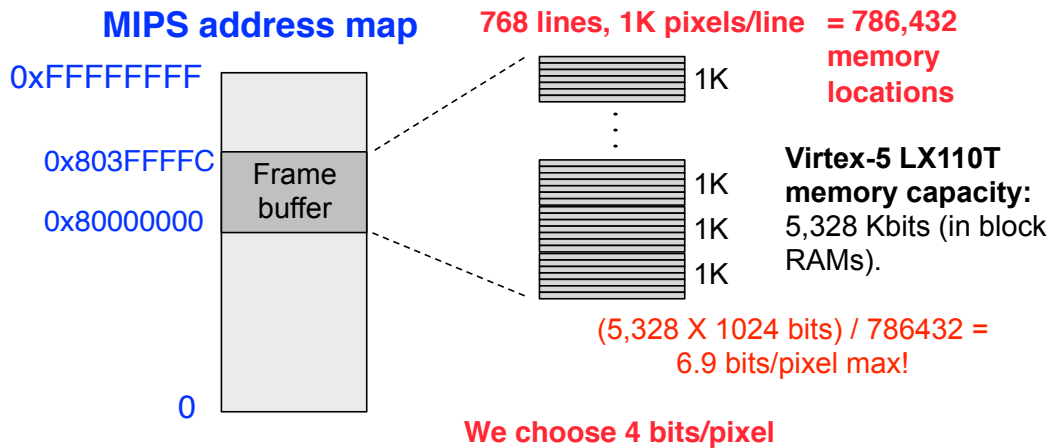
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Framebuffer Details 2009

- One pixel value per memory location.



- Note, that with only 4 bits/pixel, we could assign more than one pixel per memory location. Ruled out by us, as it complicated software.

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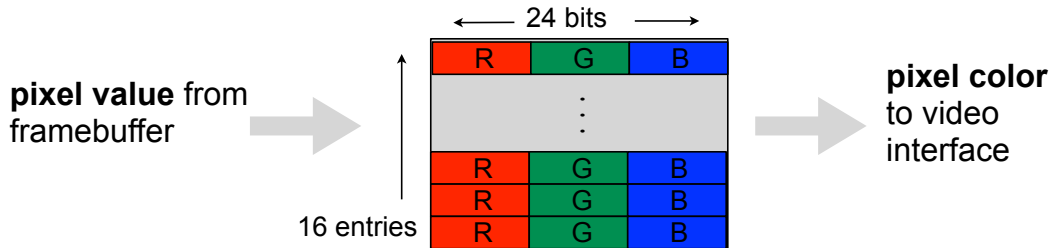
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Color Map

4 bits per pixel, allows software to assign each screen location, one of 16 different colors.

However, physical display interface uses 8 bits / pixel-color. Therefore entire pallet is 2^{24} colors.

Color Map converts 4 bit pixel values to 24 bit colors.

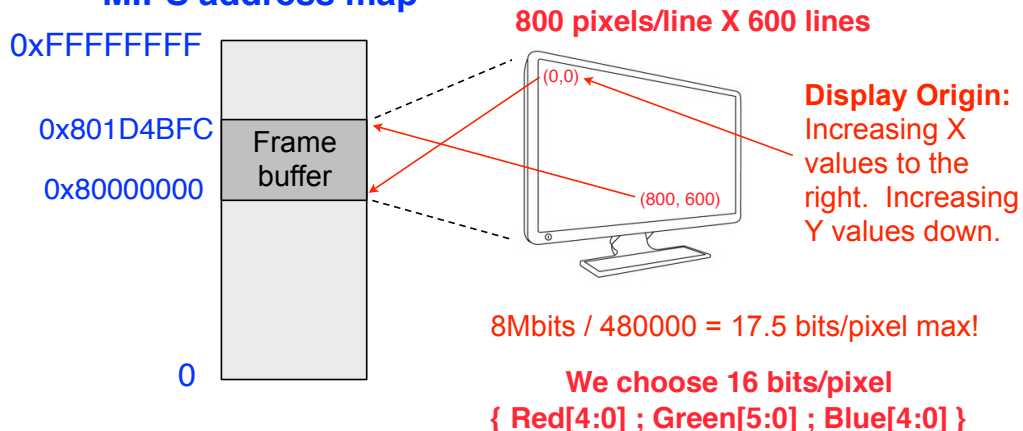


Color map is memory mapped to CPU address space, so software can set the color table. Addresses: `0x8040_0000` `0x8040_003C`, one 24-bit entry per memory address.

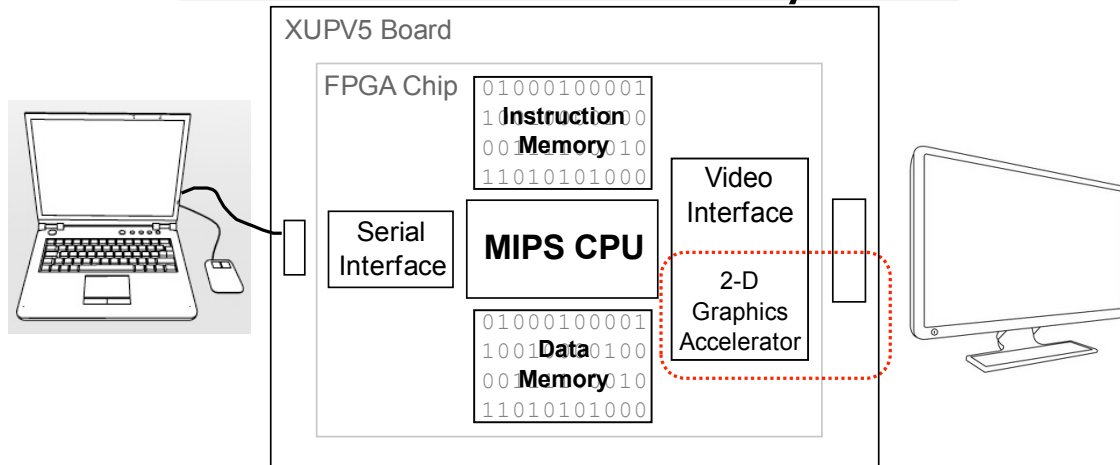
Memory Mapped Framebuffer 2010

- A range of memory addresses correspond to the display.
- CPU writes (using sw instruction) pixel values to change display.
- No handshaking required. Independent process reads pixels from memory and sends them to the display interface at the required rate.

MIPS address map



MIPS150 Video Subsystem



- Gives software ability to display information on screen.
- Equivalent to standard graphics cards:
 - Processor can directly write the display bit map
 - **2D Graphics acceleration**

Graphics Software

"Clearing" the screen - fill the entire screen with same color

Remember Framebuffer base address: `0x8000_0000`

Size: `1024 x 768`

```
clear:  # a0 holds 4-bit pixel color
        # t0 holds the pixel pointer
        ori    $t0, $0, 0x8000          # top half of frame address
        sll    $t0, $t0, 16             # form framebuffer beginning address
        # t2 holds the framebuffer max address
        ori    $t2, $0, 768            # 768 rows
        sll    $t2, $t2, 12            # * 1K pixels/row * 4 Bytes/address
        addu   $t2, $t2, $t0           # form ending address
        addiu  $t2, $t2, -4            # minus one word address
        #
        # the write loop
L0:     sw     $a0, 0($t0)              # write the pixel
        bneq  $t0, $t2, L0             # loop until done
        addiu $t0, $t0, 4              # bump pointer
        jr    $ra
```

How long does this take? What do we need to know to answer?

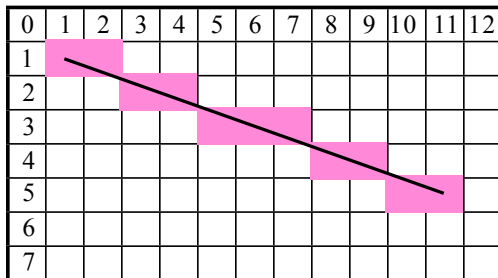
How does this compare to the frame rate?

Optimized Clear Routine

```
clear:
    .      Amortizing the loop overhead.
    .
    .
    # the write loop
L0:    sw    $a0, 0($t0)      # write some pixels
        sw    $a0, 4($t0)
        sw    $a0, 8($t0)
        sw    $a0, 12($t0)
        sw    $a0, 16($t0)
        sw    $a0, 20($t0)
        sw    $a0, 24($t0)
        sw    $a0, 28($t0)
        sw    $a0, 32($t0)
        sw    $a0, 36($t0)
        sw    $a0, 40($t0)
        sw    $a0, 44($t0)
        sw    $a0, 48($t0)
        sw    $a0, 52($t0)
        sw    $a0, 56($t0)
        sw    $a0, 60($t0)
        bneq  $t0, $t2, L0    # loop until done
        addiu $t0, $t0, 64    # bump pointer
        jr    $ra
```

What's the performance of this one?

Line Drawing



From (x_0, y_0) to (x_1, y_1)

Line equation defines all the points:

$$y - y_0 = \frac{y_1 - y_0}{x_1 - x_0}(x - x_0)$$

For each x value, could compute y, with: $\frac{y_1 - y_0}{x_1 - x_0}(x - x_0) + y_0$
 then round to the nearest integer y value.

Slope can be precomputed, but still requires floating point * and + in the loop: slow or expensive!

Bresenham Line Drawing Algorithm

Developed by Jack E. Bresenham in 1962 at IBM.

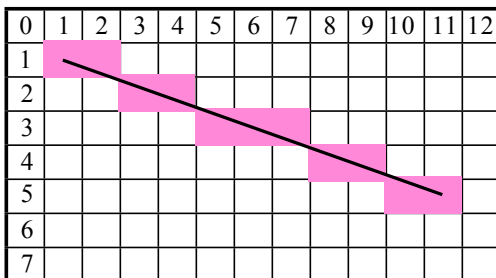
"I was working in the computation lab at IBM's San Jose development lab. A Calcomp plotter had been attached to an IBM 1401 via the 1407 typewriter console. ...



- Computers of the day, slow at complex arithmetic operations, such as multiply, especially on floating point numbers.
- Bresenham's algorithm works with integers and without multiply or divide.
- Simplicity makes it appropriate for inexpensive hardware implementation.
- With extension, can be used for drawing circles.

Line Drawing Algorithm

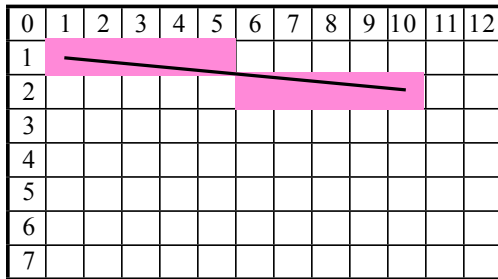
This version assumes: $x_0 < x_1$, $y_0 < y_1$, slope ≤ 45 degrees



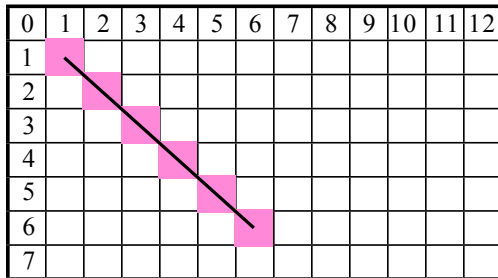
```
function line(x0, x1, y0, y1)
  int deltax := x1 - x0
  int deltay := y1 - y0
  int error := deltax / 2
  int y := y0
  for x from x0 to x1
    plot(x,y)
    error := error - deltay
    if error < 0 then
      y := y + 1
    error := error + deltax
```

Note: error starts at $deltax/2$ and gets decremented by $deltay$ for each x , y gets incremented when error goes negative, therefore y gets incremented at a rate proportional to $deltax/deltay$.

Line Drawing, Examples

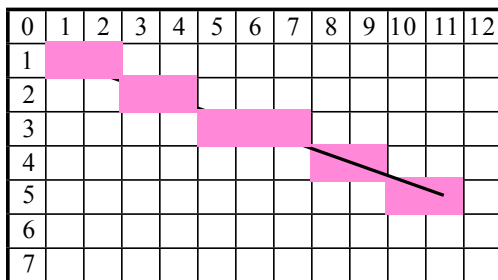


deltay = 1 (very low slope).
y only gets incremented
once (halfway between x0
and x1)



deltay = deltax (45 degrees,
max slope). y gets
incremented for every x

Line Drawing Example



(1,1) -> (11,5)

deltax = 10, deltay = 4, error = 10/2 = 5, y = 1

x = 1: plot(1,1)
error = 5 - 4 = 1

x = 5: plot(5,3)
error = 9 - 4 = 5

x = 2: plot(2,1)
error = 1 - 4 = -3
y = 1 + 1 = 2
error = -3 + 10 = 7

x = 6: plot(6,3)
error = 5 - 4 = 1

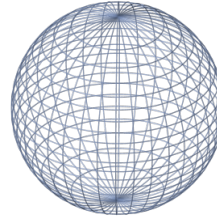
x = 3: plot(3,2)
error = 7 - 4 = 3

x = 7: plot(7,3)
error = 1 - 4 = -3
y = 3 + 1 = 4
error = -3 + 10 = 7

x = 4: plot(4,2)
error = 3 - 4 = -1
y = 2 + 1 = 3
error = -1 + 10 = 9

```
function line(x0, x1, y0, y1)
  int deltax := x1 - x0
  int deltay := y1 - y0
  int error := deltax / 2
  int y := y0
  for x from x0 to x1
    plot(x,y)
    error := error - deltay
    if error < 0 then
      y := y + 1
    error := error + deltax
```

C Version



```

#define SWAP(x, y) (x ^= y ^= x ^= y)
#define ABS(x) ((x)<0) ? -(x) : (x)

void line(int x0, int y0, int x1, int y1) {
    char steep = (ABS(y1 - y0) > ABS(x1 - x0)) ? 1 : 0;
    if (steep) {
        SWAP(x0, y0);
        SWAP(x1, y1);
    }
    if (x0 > x1) {
        SWAP(x0, x1);
        SWAP(y0, y1);
    }
    int deltax = x1 - x0;
    int deltax = ABS(y1 - y0);
    int error = deltax / 2;
    int ystep;
    int y = y0
    int x;
    ystep = (y0 < y1) ? 1 : -1;
    for (x = x0; x <= x1; x++) {
        if (steep)
            plot(y,x);
        else
            plot(x,y);
        error = error - deltax;
        if (error < 0) {
            y += ystep;
            error += deltax;
        }
    }
}

```

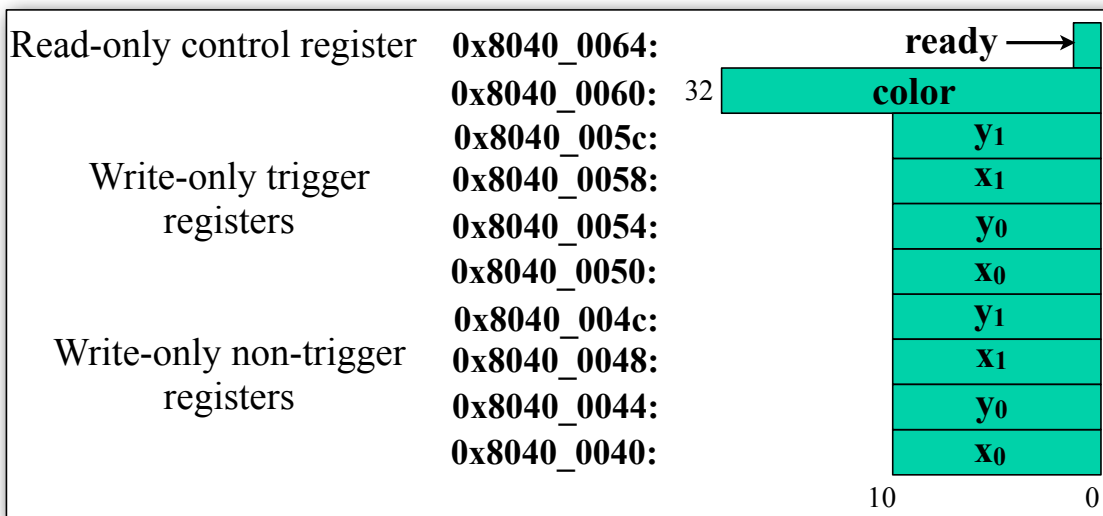
Modified to work in any quadrant and for any slope.

Estimate software performance (MIPS version)

What's needed to do it in hardware?

Goal is one pixel per cycle. Pipelining might be necessary.

Hardware Implementation Notes



- CPU initializes line engine by sending pair of points and color value to use. Writes to "trigger" registers initiate line engine.
- Framebuffer has one write port - Shared by CPU and line engine. Priority to CPU - Line engine stalls when CPU writes.