#### **Outline**

- O Last time:
  - → Asynchronous Circuits
  - → Moore and Mealy Standard Forms
  - → Design Example: Word Problem
- This lecture:
  - → Race-free State Assignment
  - → Excitation Equations
  - → Design Example: Implementation
  - → Summary of Asynchronous Design Process

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#### Steps to Asynchronous FSM Design

Construct a *Primitive Flow Table* from the word statement of the problem.

- ✓ Derive a minimum-row primitive flow table or *Reduced Primitive Flow Table* by eliminating redundant, stable total-states.
- O Convert the resulting table to Mealy form, if necessary, so that the output value is associated with the total state rather than the internal state.
- Derive a minimum-row flow table, or Merged Flow Table, by merging compatible rows of the reduced primitive flow table using a merger diagram. (Note: solution not necessarily unique)
- Perform race-free, or critical-race-free, state assignment, adding additional states if necessary.
- Complete the Output Table to avoid momentary false outputs when switching between stable total states.
- Draw logic diagram that shows ideal combinational next-state and output functions as well as necessary delay elements.

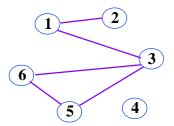
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## Conversion to Mealy Form for Merging: Example 1

	X	1 <b>X</b> 2				Z			
		00	01	11	10	00	01	11	10
1		1	2	-	3	0	-	-	-
2		1	(2)	4	-	-	0	-	-
3		1	-	5	(3)	-	-	-	0
4		-	6	4	3	-	-	1	-
5		-	6	(5)	3	-	-	0	-
6		1	6	5	-	_	0	_	-

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## **Create Merger Diagram**



What we are doing is choosing *internal* states that can have the *same* code, though the *total* states will still be different (since they will not have the same code for the same inputs; if that were possible they would have been redundant).

Two rows of a reduced primitive Mealy flow table are *compatible* and can be merged into a single row iff there are no state or output conflicts in any column.

Draw a line between any pair of rows (states) which are compatible and can be merged.

Choose the sub-groups of fully-connected rows that will result in the maximum reduction. In this case, {1,2} and {3,5,6} are best. We could also have chosen {1,3} and {5,6}, or just {3,6} in which case no others would be permitted.

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## **Example 1: After Merging**

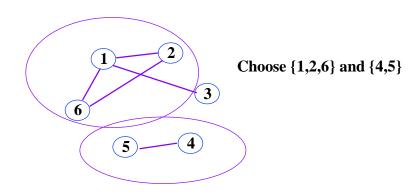
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13.2.5

## Conversion to Mealy Form for Merging: Example 2

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### **Create Merger Diagram: Example 2**



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13.2.7

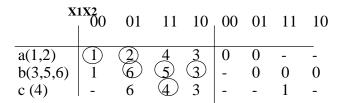
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## **Example: After State Reduction and Merging**



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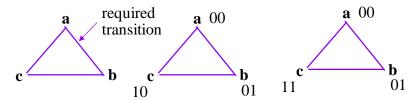
13.2.9

# **Example 1: States Labelled in Terms of Internal States**

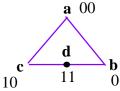
	X1X	2		I				
	00	01	11	10	00	01	11	_10
		_						
a	(a)	(a)	c	b	0	0	-	-
b	a	(b)	$\stackrel{c}{\textcircled{b}}$	<b>b</b>	-	0	0	0
c	-	b	$\widetilde{(c)}$	b	-	-	1	-

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## **Example: Race-Free State Assignment**



- O Line between states indicates required transition.
- O Need assignment such that only one state variable changes during each state transition a 00



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#### **Example: Critical-Race-Free State Assignment**

	X1X2							
	00	01	11	10	00	01	11	10
a 00	00	00	10	01	0	0	-	0v
b 01	00	$\widetilde{01}$	01	01	0u	0	0	0
d 11	_	01		-	-	-s	-	-
c 10	_	11	10	00	ا <u>-</u>	1t	1	_

- O In col. 01, row C, 10->11->01: critical race avoided
- O In col 10, could have directed transition via row d but already have transition to b in row a, so use it.
- Fill in outputs corresponding to unstable states to avoid momentary false outputs during transitions

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# Critical-Race-Free State Assignment via Shared-Row Assignments

	00	01	11	10
a	(1)	2	5	4
b	$ 7\rangle$	2	3	(10)
c	1	8	(3)	4
d	7	( <u>8</u> )	5	4
e	1	9	(5)	6
f	(1)	8	3	<b>(6)</b>

**O** Required transitions:

col 00: e,c -> a; d->b col 01: a->b; c,f->d col 11: b,f->c; a,d->e col 10: a,c->d; e->f

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13.2.13

### **Shared Row Assignment**

- O Consider required transitions: e,c -> a
- O Could implement as: e->a, c->a; or e->c->a; or c->e->a; or any of the above going through an intermediate state (or states).
- To avoid critical races, must ensure that {a,c,e} are placed in adjacent squares on the assignment map. Similar for other constraints. Must satisfy:

 ${a,c,e}, {b,d}, {a,b}, {c,d,f}, {b,c,f}, {a,d,e}, {a,c,d}, {e,f}$ 

a e
b d
x c
v f

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#### **Completion of the Output Table**

	X1X	2						
	00	01	11	10	00	01	11	10
a 00	00	(0)	10	01	0	0	-	0v
b 01	00	$\bigcirc$	01	01 <u>01</u>	0u	0	0	0
d 11	_	01	_	_	-	-s	-	-
c 10	-	11	$\bigcirc$	00	_	1t	1	_

From State 00, input change 00->10 causes transition to stable state 01. To avoid glitch if logic synthesis assigns "don't care" in output to 1 for input value 10, make it a 0 (labelled v above).

From State 01, input change 01->00 causes transition to State 00, so avoid possible glitch by assigning output in State 01 for input 00 to 0 (u above)

From State 10, input change 11->01 causes transition to stable state 01, via 11. Since output goes from 1 to 0, choose output at t above to be 1, consistent with the starting value, but leave output at s a "don't care" since must make the transition somewhere and either before or after State 11 is the same.

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